Dynamics of fortnightly water level variations along a tide-dominated estuary with negligible river discharge

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Abstract. Observations indicate that the fortnightly fluctuations in mean amplitude of water level increase in the upstream direction along the lower half of a tide-dominated estuary (the Guadiana) with negligible river discharge but remain constant upstream. Analytical solutions reproducing the semi-diurnal wave propagation shows that this pattern results from reflection effects at the estuary head. The phase difference between velocity and elevation increases from the mouth to the head (where the wave has a standing nature) as the timing of high and low water levels get progressively closer to slack water. Thus, the tidal (flood-ebb) asymmetry in discharge is reduced in the upstream direction. It becomes negligible along the upper estuary half, as the mean sea level remains constant despite increased friction due to wave shoaling. Observations of a flat mean water level along a significant portion of an upper estuary suggest a standing wave character and thus indicate significant reflection of the propagating semi-diurnal wave at the head. Details of the analytical model shows that changes in the mean depth or length of semi-arid estuaries, in particular for macrotidal locations, affect the fortnightly tide amplitude, and thus the upstream mass transport and inundation regime. This has significant potential impacts on the estuarine environment in terms of ecosystem management.

1 Introduction

When averaged over a tidal cycle, the slope of the free surface elevation is generally not flat everywhere in an estuary. Several factors operating at distinct frequencies may be responsible for mean (or subtidal, tidally-averaged) water level variations along the channel, such as the tide, freshwater inputs, local or remote atmospheric conditions (e.g., wind, air pressure) and various coastal ocean processes acting at the mouth (e.g., Aubrey and Speer, 1985; Gallo and Vinzon, 2005; Henrie and Valle-Levinson, 2014; Jay et al., 2015; Laurel-Castillo and Valle-Levinson, 2020; Matte et al., 2013; Ross and Sottolichio, 2016; Shetye and Vijith, 2013; Wong et al., 2009). At a fortnightly time scale, tide-dominated estuaries commonly feature relatively high and low mean water levels (MWL) on spring and neap tides, respectively, in relation to the tidal forcing variability produced by the interaction of the semidiurnal M_2 and S_2 tidal constituents (Aubrey and Speer, 1985). The resulting compound tide (MSf) has a 14.8-day period which corresponds to the beat period between M_2 and S_2 (i.e., ωS_2 - ωM_2 = ωMSf , where ω is the tidal frequency; Dworak and Gomez-Valdes, 2005; LeBlond and Mysak, 1978). The tidal potential also contains energy at

the MSf frequency, but this energy source is usually weak and becomes negligible in the upper estuary (LeBlond, 1979). Water level oscillations with MSf period along estuaries are typically referred to as fortnightly tides.

Fortnightly tides have been mainly described at long tidal rivers affected by substantial freshwater inputs. Subtidal changes in water elevation at these systems can be of order 1 m at the upper reaches and may have as such significant effects on navigability and tidal inundation (e.g., Aubrey and Speer, 1985; Godin, 1999; Guo et al., 2015; Jay et al., 2015; Matte et al., 2014). MSf tides with large amplitude derive from the subtidal friction produced by the interaction between the river flow and the various tidal constituents (Buschman et al., 2009; Cai et al., 2016a; Jay and Flinchem, 1997; Sassi and Hoitink, 2013). The river discharge nonlinearly enhances the subtidal friction experienced by the barotropic tidal wave propagating upstream (Godin, 1985; Godin, 1999; Guo et al., 2015; Jay, 1991; Matte et al., 2013; Pan et al., 2018; Sassi and Hoitink, 2013). Due to its nonlinear dependence to water depth, the subtidal friction is greatest on spring tides and is thus balanced by the largest subtidal water level gradient landward; likewise, the gradient is smallest on neap tides when friction is comparatively weak. This is demonstrated by analytical derivations of the along-estuary momentum equation for tidal averaged conditions, which indicates that the water slope term is dominantly balanced by the friction term (e.g., Buschman et al., 2009; Cai et al., 2016a; Cai et al., 2019; Cai et al., 2014; LeBlond, 1978; Sassi and Hoitink, 2013). Thus, if the river discharge and mean sea level remain constant, the variation of the mean slope with tidal forcing causes subtidal water levels to be higher at spring tide than at neap tide. The friction-induced modulation in subtidal water levels allows transporting, for any tidal amplitude, the same volume of riverine water seaward over the neap-spring cycle (Guo et al., 2015). At settings with extended intertidal areas, the lateral spreading of the flood tidal wave produces additional frictional asymmetries between spring and neap tides that may also contribute to the increase of the fortnightly tide amplitude in the upstream direction (Friedrichs and Aubrey, 1988).

Without significant river discharge, fluctuations of the subtidal friction generated by tidal contributions alone may also produce a fortnightly tide (Vignoli et al., 2003). This case concerns many worldwide estuaries, typically in semi-arid regions, where the river flow influence is non-relevant compared to the tidal forcing during a large part of the year, at least (e.g., Correia et al., 2020; Descroix et al., 2020; Dias et al., 2016; Frota et al., 2013; Garel and D'Alimonte, 2017; Lamontagne et al., 2016; Lopez et al., 2020; McCutcheon et al., 2019; Valle-Levinson and Schettini, 2016). Due to high freshwater demands for irrigation and other uses, semi-arid estuaries are under increasing stress worldwide from decreased freshwater inflows (Feng and Fu, 2013; Leblanc et al., 2012). As for tidal rivers, an accurate knowledge of water level variations at semi-arid estuaries with ephemeral freshwater inflows is necessary for ecosystem and freshwater management as well as for hydrodynamic research (Hoitink and Jay, 2016; Jay et al., 2011; Pan and Lv, 2019). However, the dynamics of the fortnightly tide produced by tidal asymmetry alone have been poorly documented so far.

The present study proposes to make explicit the dynamics of fortnightly tides in estuaries where tidal motion is the main forcing. Subtidal water level observations in a semi-arid estuary with negligible freshwater discharge (the Guadiana) are compared with the outputs of analytical solutions considering a semi-diurnal tide of variable forcing amplitude propagating along a convergent channel. The specific objectives are to establish the tidal properties that control the development of the subtidal slope along the channel, to evaluate the effects of reflection at the head, and to explore MWL variations in function

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of the tidal forcing and estuary geometry. Overall, this research proposes, for the first time, an analytical tool for assessing the impacts of geometric changes (such as the mean depth or length of the estuary) on fortnightly water level variations in tide-dominated estuaries with negligible river discharge. The results shed new light on how fortnightly dynamics in water levels is generated due to imposed tidal forcing at the mouth and tidal wave reflection from the head of the estuary. Through estimates of the MWL along the estuary, the approach is specifically helpful for sustainable water resources management of ecosystems, especially in macrotidal estuaries. In Sect. 2, the development of a fortnightly tide as a result of the balance between friction and water slope is described analytically. The study site and collected data are presented in Sect. 3, along with the hydrodynamic model used to reproduce tidal wave properties. The observational results are presented in Sect. 4. The model results are presented and explored in Sect. 5 to elucidate and discuss the dynamics of the fortnightly tide and implications for estuarine environments. The main conclusions of this work are summarized in Sect. 6.

2 Analytical description of the fortnightly tide

The subtidal water level slope along an estuarine channel produced by tidal effects can be derived from the 1D momentum equation (e.g., Savenije, 2012):

$$\frac{\partial U}{\partial t} + U \frac{\partial U}{\partial x} + g \frac{\partial Z}{\partial x} + g \frac{U|U|}{K^2 h^{4/3}} = 0, \tag{1}$$

where *U* is the cross-sectional average velocity, *h* is the water depth, *Z* is the water level fluctuation in relation to the tidally average water level, *g* is the gravitational acceleration, *t* is time, *x* is the longitudinal coordinate directed landward and *K* is the Manning-Strickler friction coefficient.

Assuming a periodic variation of flow velocity, the integration of Eq. 1 over a tidal cycle leads to (Cai et al., 2014; Vignoli et al., 2003):

$$85 \quad \frac{\partial \bar{Z}}{\partial x} = -\frac{1}{K^2} \overline{\left(\frac{U|U|}{h^{4/3}}\right)} - \frac{1}{2g} \frac{\overline{\partial U^2}}{\partial x},\tag{2}$$

where the overbars denote a tidal average. The second contribution to the subtidal water level in Eq. 2 originates from the advective acceleration term, which is relatively small when compared to the first contribution induced by the residual frictional effect as long as the Froude number is small (which is usually the case in estuaries, e.g., about 0.14 at the Guadiana; see also Cai et al., 2019).

Thus, Eq. 2 simply expresses a balance between the slope and friction. In several cases, the contribution of the time-variable depth is a second-order effect for the hydrodynamics (for instance, if the tidal amplitude is relatively small compared with the depth), but it can still be relevant for the subtidal water level. The total free surface elevation Z is the sum of its tidal average \bar{Z} (responsible for the subtidal slope) and tidal wave height Z_t such as $Z_t = Z - \bar{Z} = \zeta \bar{h} f_Z(t)$ where the function f_Z describes the variation of Z with time and ζ is the ratio of the tidal amplitude to the water depth. From a Taylor expansion of $h = \bar{h} + Z_t$, assuming that $\zeta \ll 1$, the frictional contribution to Eq. 2 can be rewritten as:

$$\frac{\partial \bar{Z}}{\partial x} = -\frac{1}{K^2 \bar{h}^{4/3}} \overline{U|U| \left(1 - \frac{4}{3} \frac{Z_t}{\bar{h}}\right)},\tag{3}$$

where the additional term in parentheses can be significant, depending on the relative phase difference between U and Z, i.e., the phase lead ϕ of the velocity with respect to the water level (van Rijn, 2011). The analysis of a simple case like a purely sinusoidal signal of frequency ω shows this feature clearly. If $U = v\cos(\omega t)$, where v is the tidal velocity amplitude, and $f_Z = \cos(\omega t - \phi)$, then $\overline{U|U|} = 0$, but $\overline{U|U|} = 4v^2\cos(\phi)/(3\pi)$, which is vanishing only for $\phi = \pi/2 + n\pi$ (with n being an integer number), i.e. for a standing wave. In the latter case, the peak of flow velocity occurs when the water level attains the mean sea level value both during the flood and the ebb phases (ebb discharge = flood discharge) and the tidally averaged water level keeps constant and horizontal along the channel. By contrast, if the wave contains a significant progressive component, the additional term produces a residual slope:

$$105 \quad \frac{\partial \bar{Z}}{\partial x} = \frac{16}{9\pi} \frac{v^2 \zeta}{K^2 \bar{h}^{4/3}} \cos(\phi). \tag{4}$$

Equation 4 shows that a purely sinusoidal tidal wave may produce a residual slope even in the absence of freshwater discharge into the estuary. In this case, the residual slope relates to intratidal variations in the friction experienced by the wave for distinct tidal velocities (tidal stages). When the lag between elevation and velocity is significant, the peaks of ebb and flood velocities occur during low and high-water stages, respectively. Thus, the frictional term yields larger dissipation during the ebb phase than during the flood phase; this implies that the free surface slope must increase to compensate the dynamic imbalance in order to conserve a zero discharge. This mechanism is also stronger at spring than neap tides, resulting in fortnightly fluctuations of the residual slope; these dynamics are the scope of the present study.

3 Material and methods

3.1 Study area and data collection

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The Guadiana estuary consists of a single channel that connects the Guadiana River to the Gulf of Cadiz at the southern border between Portugal and Spain (Fig. 1). The channel is 78 km long and broadly oriented north-south, with a cross-section width that reduces exponentially from 700 m at the mouth to 60 m at the head. The thalweg is generally between 4 m and 8 m, with a mean depth of approximately 5.5 m (Garel, 2017).

120 Tides are semidiurnal in the region and their range falls in the microtidal to mesotidal regime (1.3 m during neaps and 2.6 m during springs, on average), with a maximum of 3.4 m. The amplitude of the dominant M₂ constituent varies by < 10% along the estuary. It is slightly damped along the lower half of the estuary, where friction dominates morphological convergence effects, and it is slightly amplified along the upper half, due to reflection at the head which overall effect is to reduce the friction experienced by the propagating wave (Garel and Cai, 2018).

The freshwater discharge into the estuary is generally low, in particular in summer when it is typically < 10 m³/s (see Garel and D'Alimonte, 2017). During a single tide, this rate corresponds to a volume of freshwater input approximately 70 times lower than the average tidal prism (30 Mm³; Correia et al., 2020). Under these conditions, the water column is generally well-mixed (Garel et al., 2009).

3.1.2 Data acquisition and processing

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Water level variations along the Guadiana were measured from 31 July to 24 September 2015 with a series of 7 pressure transducers (Level TROLL 700 Data Logger, In-Situ), deployed every 10 km, approximately, from the mouth (St0) to 60 km upstream (St6; see Fig. 1). The sensor accuracy is rated at +/-0.55 cm by the manufacturer and their maximum range is 11 m. During the survey period, the mean freshwater discharge was 7 m³/s and weather conditions were mild, typical of summers in the region. The largest spring and lowest neap tides were on 31 August 2015 and 24 August 2015, with tidal ranges of 3.3 m and 1.2 m, respectively.

The raw pressure data, recorded at 1 min intervals, were smoothed with a 5 min moving average window and resampled to a common time at a 10 min interval. The records were then corrected for atmospheric pressure variations obtained from a station (Faro) located 50 km westward from the mouth (see Fig. 1 inset). The mean value was removed from the corrected time series to obtain water level variations around zero at each station. Pressure differences between Faro and Beja, located 110 km northward (see Fig. 1 inset), were weak (< 2 mBar) during the survey, indicating an insignificant effect of meridional pressure variations on the water level slope along the estuary. It should be noted that the potential impacts induced by wind and waves on the water level dynamics during storms are not addressed since the study focuses on normal (fair) meteorological conditions. Tidal amplitudes at each station were obtained through demodulation of the pressure records (see Garel and Cai, 2018). The resulting amplitudes were smoothed using a 6-point moving average to discard jagged fluctuations induced by (small) diurnal inequalities of the astronomical tide. A Continuous Wavelet Transform (CWT) analysis was performed to compare the amplitude of tidal species (diurnal D_1 , semi-diurnal D_2 , quarter-diurnal D_4 and fortnightly D_f) on the largest spring and lowest neap tides at each station. The basic principles of CWT analyses are described in Jay and Flinchem (1997; see Eqs. 1-3 in their manuscript).

A Butterworth low-pass filter with a cut-off period of 11 days was applied to the time series to expose the fortnightly modulation of water level variations (denoted Z_f , hereafter). The low-pass filter was also applied with a 40-hr cut-off period (discarding shorter periodic variations, which are mainly tidal) in order to assess the contribution of Z_f to the obtained subtidal water level, Z_s . The initial 4 days of the time-series were discarded due to artefacts produced by the filtering process. Significant differences between Z_s and Z_f are produced by external agents (such as atmospheric or coastal ocean processes) operating (and affecting the surface water level) in the subtidal to fortnightly band period.

In estuaries, a consistent increase of the MWL in the upstream direction is also produced by the horizontal water density gradient (e.g., Savenije, 2012; Savenije and Veling, 2005). Neap-spring variations in the salinity intrusion length may therefore contribute to the observed fortnightly water level modulation (*Z*_f). The effect of density on the slope was estimated based on

CTD measurements performed every ~4 km from the mouth to the freshwater front (defined as salinity <1 kg/g/m³). These surveys were conducted at both high-water slack (HWS) and low water slack (LWS) during consecutive spring (29 May 2018) and neap (06 June 2018) tides with range of 2.5 m and 1.1 m, respectively, under low river flow conditions (10 m³/s). The tidally-averaged salinity curves were obtained as half the excursion length (Savenije, 2012). The contribution to the water level from the density effects (denoted Z_{ρ}) was estimated as (e.g., Cai et al., 2016a; Cai et al., 2019; Vignoli et al., 2003):

$$\frac{\mathrm{d}Z_{\rho}}{\mathrm{dx}} = -\frac{1}{2\rho_0} \overline{h_{\mathrm{m}} \frac{\mathrm{d}\rho}{\mathrm{dx}}},\tag{5}$$

where the axial distance x=0 at the mouth, $h_{\rm m}$ is the measured cross-sectional mean depth and ρ is the (depth-averaged) water density. Hereafter, the subscript zero indicates a value at the mouth.

3.2 Hydrodynamic model of tidal wave propagation

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To derive the analytical solution for tidal hydrodynamics along an estuarine channel, it is assumed that the tidally-averaged cross-sectional area \bar{A} and width \bar{B} can be described by the following exponential functions (Savenije et al., 2008):

$$\bar{A} = \overline{A_0} \exp\left(-\frac{x}{a}\right),\tag{6}$$

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$$\bar{B} = \overline{B_0} \exp\left(-\frac{x}{b}\right),$$
 (7)

where a and b are the area and width convergence lengths, respectively. It is also assumed that the flow is concentrated in a rectangular cross-section, with a possible influence from storage areas described by the storage width ratio r_S that is defined as the ratio of the storage width B_S to the tidally-averaged width \bar{B} ($r_S = B_S/\bar{B}$). It directly follows from the assumption of a rectangular cross-section that the tidally-averaged depth is given by $\bar{h} = \bar{A}/\bar{B}$.

Toffolon and Savenije (2011) showed that the analytical solutions for tidal hydrodynamics along an estuary can be described by a few externally defined dimensionless parameters that depend on the estuary geometry and external forcing (see Table 1): the tidal amplitude ζ_0 , representing the boundary condition imposed at the estuary mouth; the estuary shape number γ , indicating the effect of the channel cross-sectional area convergence; the friction number χ_0 , describing the role of the frictional dissipation at the estuary mouth; and the dimensionless estuary length L_e^* . In Table 1, η_0 is the tidal amplitude at the mouth,

 c_0 is the frictionless wave celerity in a prismatic channel (defined as $c_0 = \sqrt{g\bar{h}/r_S}$) and L_0 is the frictionless tidal wavelength $(L_0 = c_0/\omega)$. The tidal frequency of the considered constituent is $\omega = 2\pi/T$ (with T the tidal period). It is noted that the friction number χ_0 is dependent of the Manning-Strickler friction coefficient K that describes the effective friction resulting from various environmental factors such as bedforms, grain roughness, vegetation, channel geometry (e.g., Savenije and Veling, 2005; Wang et al., 2014; Winterwerp and Wang, 2013), river discharge and from nonlinear effects induced by minor tidal constituents (Prandle, 1997). The value of K is generally difficult to estimate accurately and is preferably obtained by calibrating the model results with observations, if available.

The corresponding dependent dimensionless parameters which are used to describe the main tidal hydrodynamics along the channel include (Table 1): the actual tidal amplitude ζ , the actual friction number χ (χ = 0 in a frictionless case), the velocity

number μ (the ratio of the actual velocity amplitude to the frictionless value in a prismatic channel), the celerity number for elevation λ_A and velocity λ_V (the ratio between the frictionless wave celerity in a prismatic channel and the actual wave celerity), the amplification number for elevation δ_A and velocity δ_V (describing the rate of increase, δ_A (or δ_V) >0, or decrease δ_A (or δ_V) <0 of the wave amplitudes along the estuary axis), and the phase lead angle ϕ between velocity ϕ_V and elevation ϕ_A ($\phi = 90^\circ$ for a standing wave).

The dependent parameters defined in

Table 1 can be calculated using the equations developed by Toffolon and Savenije (2011; see also Cai et al., 2016b and Eqs. 6-20 in Garel and Cai, 2018) for both infinite and semi-closed channels. To account for the longitudinal variation of the cross-sections in width and depth, the entire channel was subdivided into multiple reaches. The solutions were then obtained by solving a set of linear equations, with internal boundary conditions at the junction of the sub-reaches satisfying the continuity conditions for both water level and discharge. Previous applications have shown that the model can accurately describe the effect of tidal forcing variations (e.g., spring and neap tides) on tidal properties along narrow convergent estuaries (such as the Guadiana) by considering a single effective tidal wave (Garel and Cai, 2018).

4 Observations

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4.1 Fortnightly tide

Pressure records indicate large spring-neap fluctuations in tidal amplitude at the mouth (Fig. 2a), which are due to a relatively large S_2 constituent in the region (Garel and Cai, 2018). At the mouth (St0), there is no apparent relation between the tidal amplitude and the (11 day) low-passed filtered water level, Z_f . About 10 km upstream at St1, Z_f occasionally accompanied the tidal forcing variations, in particular during the tides on 24 (neap) and 31 (spring) August. Upstream (St2-6), Z_f clearly covaries with the tidal amplitude (Fig. 2a, b), being relatively higher at spring tide and lower at neap tide (Fig. 2b, c), typical of a fortnightly tide (e.g., Buschman et al., 2009; Hoitink and Jay, 2016; Sassi and Hoitink, 2013; Speer and Aubrey, 1985). The greatest water level variations of Z_f (about 20 cm in range) correspond to the largest changes in tidal height, observed between the 24 and 31 August 2015 (see Fig. 2b). It is also noted that Z_f at St1 is incongruous in September, showing variations that are unrelated with the signal at adjacent stations.

Linear correlations confirm that the tidal forcing and fortnightly water level modulations are not correlated at the mouth (Fig. 3a, blue line). The correlation increases significantly upstream until St3 (where the coefficient of correlation R is 0.8) and remains constant along the upper estuary half. Additionally, wavelet analyses show that during the neap-spring tidal cycle on 24-31 August the amplitude of the 15 days-period species (D_f) increased from about 0 cm at the mouth (St0) to 6 cm at St3 and upstream (Fig. 3b). Clearly, the fortnightly tide is produced in the lower estuary half and its amplitude upstream depends on the tidal forcing. It is also obvious in Fig. 2b that Z_f remains at a similar level along the upper estuary half.

Despite their small amplitude (e.g., Fig. 3b), the fortnightly variations Z_f contributed notably to the subtidal water level Z_s at the upstream stations (compare Figs. 2b and 2c). For instance, the largest range of Z_s variations at St3-6 occurred during the

neap-spring cycle on 24-31 August 2015. In the upper half of the estuary, Z_s is largely controlled by the tidal forcing at the mouth, as indicated by the correlation between both parameters, which is marginally weaker than for Z_f (Fig. 3a). During the survey, the residual Z_s - Z_f (Fig. 2d), representing water level variations within a period band of 40 hours to 11 days, was associated with fluctuations in wind conditions at the mouth with periods of 7 and 9 days (not shown). The wind-induced water level variations are constant along the estuary and dominate the subtidal signal (Z_s) along its lower half. As the fortnightly tide grows in the upstream direction, Z_f and wind-induced water level variations contributed similarly to Z_s in the upper estuary half.

The above observations indicate that, under typical (fair) weather conditions that prevail in summer, the MWL along the Guadiana is affected by spring-neap variations produced within the system, characterized by an amplitude growth of 0.2 cm/km until ~30 km upstream. This distance is in the range of the salinity intrusion length for low river discharge conditions, as exemplified by the salinity measurements performed in 2018 (Fig. 4). Despite expected differences in intrusion length at high water slack (HWS) and low water slack (LWS), the tidally averaged (TA) salinity curves are highly similar on spring and neap tides. From Eq. 5, the density-induced water level (Z_{ρ}) increases up to 5-6 cm from the mouth to the salt intrusion limit. However, neap-spring differences in Z_{ρ} over the fortnightly cycle are weak (~ 0.3 cm) along the channel. The density gradient has therefore a negligible effect on the observed fortnightly modulation of water level variations.

To examine how the fortnightly signal is produced, the difference in Z_f between St3 and St0 (ΔZ_f , hereafter) is represented along with the difference in high water level (HWL) and low water level (LWL) at the same stations (Δ HWL and Δ LWL, respectively) for each tidal cycle (Fig. 5, with ΔZ_f on the right axis that is maximum on springs and minimum on neaps). It is noted that these water level differences are not absolute values (since the pressure records were not referred to the same datum) but rather indicate the temporal trend (i.e., increasing or decreasing) of the surface water slope at high and low water. For instance, the difference in HWL between St3 and St0 varies weakly (Fig. 5, blue line), indicating that the slope at HWL is relatively constant whatever the tidal forcing. In detail, Δ HWL decreases (about 5 cm) from neap to spring tides, as opposed to ΔZ_f variations (compare the blue and black lines in Fig. 5). By contrast, the relative difference in LWL between St3 and St0 (Δ LWL, red line in Fig. 5) was larger than Δ HWL (> 15 cm in range between the 24 and 31 August), and clearly features fortnightly variations in phase with ΔZ_f . This pattern indicates that the increase of the Z_f slope (from neap to spring tides) between St0 and St3 is mainly produced by LWL variations, as expected due to the strong depth dependence of frictional effects. The temporal variations of Δ HWL and Δ LWL also indicate that the tidal wave height is significantly reduced at spring tide and slightly amplified at neap tide between St0 and St3. These differences in wave damping are examined in the next section considering the tides with lowest and largest amplitudes on 24 August and 31 August, respectively.

4.2 Neap and spring waves propagation

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The observed tidal waves on 24 (neap) and 31 (spring) August at Stations 0 to 6 are illustrated in Fig. 6. On both dates, the wave is sinusoidal near the mouth (St0); as it propagates upstream, the wave remains approximately sinusoidal at neap tide but is increasingly distorted at spring tide (the ebb and flood phases get typically longer and shorter, respectively).

The diurnal (D_1) , semi-diurnal (D_2) and quarter-diurnal (D_4) species contained in the tidal signal were extracted with a wavelet analysis of the non-filtered pressure records (Fig. 7). Note that the sixth-diurnal species were not analysed since their magnitudes are relatively small when compared with other components (see Garel and Cai, 2018). The amplitude of D_1 is relatively low and constant along the channel on both neap and spring tides (Fig. 7a). D_2 is responsible for most of the tidal wave height variations along the channel (Fig. 7b), due to the predominance of the M_2 constituent. On spring (neap) tide, D_2 is damped (amplified) along the lower estuary half, while it is similarly amplified on both spring and neap tides along the upper half. These along-channel variations in tidal elevation are noticeable in Fig. 6. The amplitude of D_4 also features significant differences between spring and neap tides (Fig. 7c): it is weak (< 3 cm) and nearly constant on neap tide, while it grows upstream on spring tide from 4 cm at St0 up to approximately 20 cm at St6. The quarter-diurnal species consists mainly of M_4 (interaction of M_2 with itself) and MS_4 (M_2 - S_2 interaction), both of equivalent importance in the Guadiana (Garel and Cai, 2018). Typically, the growth of these constituents in the upstream direction indicates increasing distortion of the tidal wave due to the combined effects from non-linear continuity term, convective acceleration term and quadratic friction in both mass and momentum equations (Parker, 1991). Such along channel wave distortion is apparent at spring tide in Fig. 6b.

Amongst the three main tidal species at the Guadiana, D_2 is characterized by damping patterns that account for the previously reported fortnightly Z_f modulations resulting from temporal LWL slope variations along the lower reach. There, the opposite semi-diurnal wave patterns on neap (amplification) and spring (damping) tides are due to variations in friction: frictional effects dominate morphological convergence effects on spring tide and the opposite occurs on neap tide (Garel and Cai, 2018). By contrast, along the upper reach, where the fortnightly wave height is constant, D_2 amplifies similarly on springs and neaps due to reflection at the head that reduces the overall friction experienced by the (spring) wave (Garel and Cai, 2018). These observations indicate that the fortnightly tide amplitude along the channel is intrinsically linked, through friction, to the neapspring variability of the damping patterns of the semi-diurnal wave propagating upstream. In the next section, the fortnightly tide hydrodynamics are further explored with an analytical model considering a M_2 wave with variable amplitude.

5 Application of the analytical model

5.1 Model implementation

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The hydrodynamic model of tidal propagation described in Sect. 3.2 was implemented at the Guadiana Estuary in order to compute the residual slope using Eq. 4. The model was set up with the same parameters as those in Garel and Cai (2018), considering a flat bed and semi-closed channel with cross-section area convergence length (a) of 31 km and width convergence length (b) of 38 km (Eqs. 6 and 7), that accurately represents the estuary geometry. The model was calibrated with a Manning-Strickler coefficient K of 47 m^{1/3} s⁻¹. Considering a flat, non-rippled, sandy bed, K is related to the drag coefficient (C_d) through (Soulsby, 1997):

$$C_d = \frac{g}{h^{1/3} K^2},\tag{8}$$

285 $C_d = \left(\frac{0.4}{1 + \ln(Z_0/h)}\right)^2$. (9)

A typical value for the bed roughness in estuaries is $Z_0 = 0.7$ mm, corresponding to mixed (non-rippled) sand and mud surface sediment. Thus, for the mean water depth of 5.5 m considered here, the drag coefficient from Eq. 9 is $C_d = 2.5 \times 10^{-3}$. This coefficient is in the range of typical values applicable to depth averaged currents in estuaries, typically on the order of $2 \times 10^{-3} - 3 \times 10^{-3}$ (Dronkers, 2005; see also Li et al., 2004). This value yields a Manning-Strickler coefficient $K = 47 \text{ m}^{1/3} \text{ s}^{-1}$, which matches the value used to calibrate the model. The calibrated model reproduces remarkably well the observed properties (amplitude and phase) of the spring and neap semi-diurnal tides along the channel when considering a M_2 wave of variable amplitude (see Garel and Cai, 2018).

To facilitate comparisons with observations, the mean value of the tidal average (\bar{Z}) time-series predicted by Eq. 4 was removed in order to obtain MWL variations around zero (denoted Z_m , hereafter), at each position along the channel (as for Z_f at St0-6). Furthermore, the observed Z_f at each station was corrected from the value at St0 to obtain $Z_f = 0$ at the mouth (as for Z_m). Finally, the records at St1 were substituted by interpolated values between St0 and St2 to discard the incongruous observations reported in Sect. 4.1.

The model reproduces remarkably well the observed fortnightly tide (Fig. 8): Z_m increases asymptotically along the lower estuary half only, with the largest amplitude (about 10-15 cm) on the largest spring tides. The tendency for the observed Z_f to be slightly higher (on springs) and lower (on neaps) than Z_m at St6 is attributed to backwater effects induced by a sill across the channel near the estuary head, not included in the model (see Garel and Cai, 2018). Overall, the correspondence of the analytical results with observations confirms that the fortnightly tide at the Guadiana results from intratidal variations in friction produced by distinct tidal stages.

5.2 Fortnightly tide dynamics

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This section examines the relations between the fortnightly tide development and the main dimensional parameters that describe the M_2 tide propagation (Table 1): the damping number for water level, δ_A (i.e., the rate of increase, $\delta_A > 0$, or decrease, $\delta_A < 0$, of the wave amplitude along the estuary); the friction number χ (which represents the contribution of frictional dissipation); the celerity number for water level, λ_A (i.e., the wave speed relatively to the frictionless wave celerity c_0 , being < 1 for waves faster than c_0); and the phase difference ϕ between velocity and elevation. Both semi-closed and infinite channels (denoted hereafter SC and IC, respectively) are considered to make explicit the effect of wave reflection at the head. Figure 9 represents the variations of the MWL slope (S), δ_A , λ_A , χ and ϕ along the channel in function of the tidal forcing for both SC (a-e, left column) and IC (k-o, right column). To highlight the fortnightly variability of each parameter, the middle column (Fig. 9f-i) indicates their difference (ΔS , $\Delta \delta_A$, $\Delta \lambda_A$, $\Delta \chi$ and $\Delta \phi$) considering the strongest (spring) and weakest (neap) tidal forcings (with SC as solid lines and IC as dashed lines).

The slope S increases with tidal forcing along the lower half of the SC channel, but becomes insignificant upstream (Fig. 9a). Thus, the spring-neap difference in slope (ΔS) becomes negligible at mid-estuary (Fig. 9f) and the fortnightly tide amplitude

grows along the lower reach, as previously observed (Figs. 2a and 8a). By contrast, a significant slope *S* develops along the entire infinite channel for tidal amplitudes larger than the mean value of 1 m, approximately (Fig. 9k). In this case, the fortnightly tide amplitude grows from the mouth to the head (see Δ*S* on Fig. 9f, dashed line). Such a pattern has been typically observed in many long estuaries, although subject to substantial river discharge, where the MSf propagates much further landward that the semi-diurnal and diurnal tidal constituents (e.g. Buschman et al., 2009; Gallo and Vinzon, 2005; Godin, 1999; Godin and Martínez, 1994; Matte et al., 2014). In these settings, the river discharge effect can be accounted for by enhanced friction, increasing the tidal asymmetry in discharge, hence the fortnightly tide amplitude (Godin, 1985; Godin, 1999; Laurel-Castillo and Valle-Levinson, 2020; Sassi and Hoitink, 2013; Savenije and Veling, 2005). Fortnightly oscillations of the MWL eventually exceed the amplitude of the main tidal constituents, with mean LWL progressively being lowered during neap tides rather than spring tides (Gallo and Vinzon, 2005; LeBlond, 1979; LeBlond, 1991). Moreover, general observations of long systems indicate that the MSf amplitude maxima is located further landward than the maxima in the overtides (Gallo and Vinzon, 2005; Guo et al., 2015; Jay et al., 2015), which is not the case at the Guadiana (compare Figs. 3b and 7c). Overall, the analytical results show that wave reflection at the head inhibits the growth of the fortnightly tide along the upper reach of estuaries.

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Figures 9b and 9l illustrate how reflection affects the semi-diurnal wave amplitude variations along the channel. The wave shoals along the SC channel for tidal amplitude < 0.7 m (Fig. 9b). For larger tidal forcing, the wave is increasingly damped along the lower half of the channel but remains amplified upstream. Near the head, the wave shoals independently of the tidal forcing (as indicated by the verticalized isocontours in Fig. 9b). The spring-neap difference in damping $\Delta \delta_A$ is insignificant along the upper estuary half (Fig. 9g, solid line), indicating that the difference in amplitude between the neap and spring waves remains constant (the wave is amplified in both cases). For an IC channel, the M_2 wave is damped along the entire system for tidal forcing > 0.6 m and amplified otherwise (Fig. 9l). Yet, damping is relatively weak, as indicated by the sub-horizontal contours on Fig. 9l. Thus, $\Delta \delta_A$ remains significant from the mouth to the head (Fig. 9g, dashed line).

Due to its nonlinear depth dependence, the friction number (χ) reflects the above described variations of the M₂ wave height.

In particular, χ increases (decreases) with the tidal forcing or for shoaling (damped) waves (Fig. 9c, m). The frictional dissipation in the lower half of the estuary is similar for the SC and IF channels, indicating similar M₂ amplitude in both cases (Fig. 9b, 1). By contrast, at the upper channel half, friction increases for SC and decreases for IF, in particular for large tidal forcing, due to opposite shoaling patterns. Hence, the greatest spring-neap differences in the friction term (Δχ) between the SC and IF channels are in the upper 30 km (Fig. 9h). This pattern indicates a significantly higher spring wave for SC than IF along this reach. Overall, the main effect of wave reflection at the head is to amplify the M₂ wave along the upper channel half, in particular for large tidal forcing. Compared to the IF case, these dynamics should enhance the MWL slope at springs, and thus the MSf amplitude at the upper reach, opposed to observations (see Fig. 2).

It can also be observed that for both the SC and IF channels, the M_2 wave accelerates with decreasing tidal forcing (Fig. 9d, n). Thus, the wave travels faster on neap tide than on spring tide. This pattern is explained by tidal damping effects on progressive waves' celerity (Savenije et al., 2008; Savenije and Veling, 2005). As observed in many estuaries (e.g., the Thames,

Shelde, Incomati), damped waves propagate slower than the classical wave celerity c_0 (corresponding to the frictionless case) while amplified waves often travel significantly faster than c_0 . This phenomenon occurs because changes in the height of a propagating wave affect the phase difference ϕ between the horizontal and vertical tides (which is otherwise constant in the frictionless case). For IF channels, where damping is weak, the phase is relatively constant both spatially and temporally (between 53° and 54.5°; Fig. 9o). The difference in phase between spring and neap tides ($\Delta \phi$) is < 2° (Fig. 9j, dashed line), indicating that the ebb-flood discharge asymmetry remains constant along the entire channel. As the wave height is only slightly damped, this asymmetry produces a significant MWL slope along the entire channel at spring tide. For the SC channel, the phase lead varies significantly as the wave propagates upstream (see the vertical contours in Fig. 9e). This is because the tidal wave tends to show a standing behaviour ($\phi \simeq 90^\circ$) towards the head. The difference in phase between neap and spring tides, $\Delta \phi$, is maximum at the lower reach (up to 15°, representing a difference of about 31 min for a M₂ tide) but have a weak incidence on the fortnightly slope which is slightly larger than for IF at this location (Fig. 9f). The main effect of reflection is in the upper reach where HWL and LWL occur close to slack water, reducing the tidal discharge asymmetry. Hence, the discharge asymmetry is not sufficient to produce a significant MWL slope on springs in the upper estuary half, although the wave is larger than for the IF channel.

5.3 Fortnightly tide amplitude and potential implications on estuarine environment

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In this section, the analytical model is exploited to analyse the fortnightly variations in MWL for SC channels with distinct geometry (depth, length and morphological convergence). Implications for water resources management in semi-arid systems are also discussed.

First, the maximum MWL (\bar{Z}_{max}) is predicted in function of the tidal forcing, using the analytical model that was setup for the Guadiana (see Sect. 5.1). Overall, the tidal forcing largely controls \bar{Z}_{max} , which is significant (e.g. > 0.5 m) for macrotidal ($\eta > 2$ m), shallow, weakly convergent and long systems (Fig. 10a-c, respectively). Of the three geometric parameters considered, the mean depth has the strongest influence on \bar{Z}_{max} (Fig. 10a), as expressed in Eq. 4. The two other parameters affect \bar{Z}_{max} the most in the case of strongly convergent and short channels (as indicated by the sub-vertical contours in Fig. 10b, c), but the maximum MWL tends to remain small. For short systems, the superimposition of the incident and reflected wave typically produces a standing wave (Cai et al., 2016b). In strongly convergent systems, the tide propagates as an 'apparent' standing wave (Friedrichs and Aubrey, 1994; Hunt, 1964; Jay, 1991; Savenije et al., 2008; van Rijn, 2011). In both cases, the tidal discharge asymmetry is negligible (the phase difference between velocity and elevation is close to 90°), inhibiting the growth of \bar{Z}_{max} along the channel.

Second, the position of \overline{Z}_{max} along the channel is investigated for SC channels with usual geometric settings (i.e., estuary length of 20-200 km, convergence length of 20-100 km and mean depth of 2-8 m). This position is defined at the distance from the mouth where the slope becomes negligible (< 0.1 cm/km) and is denoted $X_{s=0}$. Results are reported in Fig. 11, considering a tidal amplitude of 2 m at the mouth. Two geometric parameters are evaluated while the value of the 3rd parameter corresponds

to the one at the Guadiana (i.e., the convergence length is 38 km, the estuary length is 78 km and the water depth is 5.5 m in Fig. 11a, b and c, respectively). In general, the slope gets negligible slightly upstream of the mid-estuary length. This position varies weakly upstream or downstream with the convergence length and mean depth, except for deep and highly convergent systems where $X_{s=0}$ is close to the mouth (Fig. 11b). In all the evaluated cases, the slope is flat along the upper estuary reach, contrarily to infinite channels where \overline{Z}_{max} is located at the estuary head.

The above results indicate that morphological changes in tidally-dominated estuaries with negligible river discharge affect fortnightly water level variations along the channel. In particular, both an increased mean depth (due to channel dredging or to sea level rise) and the installation of a tidal barrage (reducing the channel length) decrease the maximum fortnightly tide amplitude along the estuary (Fig. 10a, c). A greater depth reduces the friction of the propagating semi-diurnal tidal wave, and hence the MWL slope. Enhanced reflection effects by tidal barrages restrict the MWL growth to the first half of the (shorter) estuary, especially during spring tides. For both cases, the reduced growth of MSf amplitude implies weaker spring-neap differences in the LWL along the channel (e.g., Fig. 5). Margins usually exposed to air on spring low tide may experience permanent inundation in the modified estuary. Such changes in the tidal inundation regime can have severe impacts on estuarine environments. In particular, tidal inundation is a fundamental driver of wetland functions, and even small changes can influence the extent and function of saltmarsh habitats (Janousek and Folger, 2014; Valiela et al., 1978). An increased LWL also enhances flooded areas during strong river discharge events, which are predicted to increase both in intensity and frequency in semi-arid regions (e.g., Smith, 1996; Tabari, 2020). Moreover, in comparison with (diurnal and semi-diurnal) tidal components that dominate at the mouth, the upstream mass transport by MSf motions is more effective due to a longer wavelength (Buijsman and Ridderinkhof, 2007; MacMahan et al., 2014). In particular, variations in subtidal water level are directly linked to salt intrusion into estuaries (Henrie and Valle-Levinson, 2014). Reductions of the fortnightly tide amplitude in modified estuaries may therefore have significant effects on water quality and ecology. These potential effects on the fortnightly tide are particularly relevant for macrotidal semi-arid estuaries like those found in NE Brazil (e.g., Barletta and Costa, 2009; Clark and Pessanha, 2014; Dias et al., 2009; Frazão and Vital, 2006).

6 Conclusions

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Using analytical solutions, this study has examined the fortnightly water level variations due to tidal motions alone in tide-dominated estuaries with negligible river discharge. These systems are typically found in semi-arid regions, where the river discharge is negligible during a large part of the year. In the Guadiana estuary, pressure measurements in August-September 2015 show that the MWL along the estuary is typically higher on spring tide and lower on neap tide. These fluctuations result from an increase of the relative LWL in the upstream direction on spring tides, while the relative HWL remains approximatively constant. The MSf amplitude grows from the mouth until the mid-estuary and remains constant upstream. During the survey, weather conditions were fair, and the fortnightly tide represented about half of the subtidal signal in the upper estuary half. The other main contribution, with approximately constant amplitude from the mouth to the head, was

induced by wind (not studied further in the present paper). The contribution of neap-spring differences in water density is negligible.

It is confirmed that the fortnightly tide is produced by intratidal variations in friction using an analytical model of wave propagation. Frictional asymmetries relate mainly to the nonlinear depth dependence of friction to water depth which strongly (weakly) affects the balance between ebb and flood discharges on springs (neaps). Considering a semi-closed channel, the model results match the observations, indicating that the MSf growth in the first half of the estuary is due to reflection effects at the head. Reflection affects MWL mainly through modification of the phase difference between velocity and elevation, which increases in the upstream direction (the wave is standing near the head due to the superimposition of the incident and reflected waves). The low and high-water levels get progressively closer to slack water, reducing the flood-ebb discharge asymmetry. In the upper half of the estuary, the discharge asymmetry becomes negligible, despite wave shoaling. Overall, observations of a flat MWL along a significant portion of the upper estuary, in particularly on springs, may indicate the presence of significant reflection effects. These data are generally easier to obtain than the phase difference, which requires combined velocity and elevation records.

Finally, changes in the mean depth (e.g., due to dredging or sea level rise) or in the channel length (e.g., due to the installation of a tidal barrage) affect the MSf amplitudes along semi-arid estuaries with negligible river discharge. Impacts on the ecosystem may arise from the induced modification of the inundation regime (through changes of the MWL and LWL) and of the upstream mass transport, in particular in macrotidal regions.

Author contributions

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All authors contributed to the design and development of the work. The experiments were originally carried out by HC. PZ carried out the data analysis. EG built the model and wrote the paper.

435 Competing interests

The authors declare that they have no conflict of interest.

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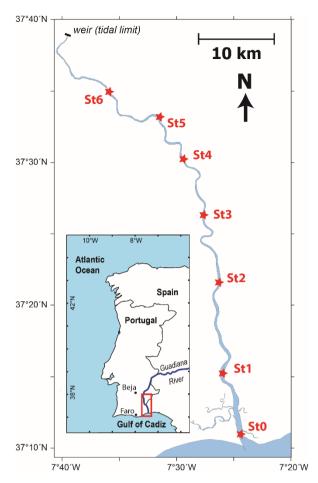


Figure 1: Location of the pressure measurement stations along the Guadiana Estuary (St0-6, red stars) and general location (inset).

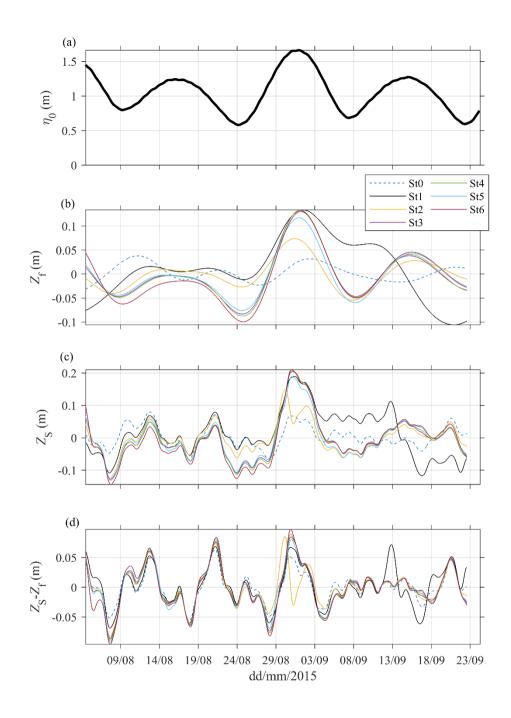


Figure 2: (a) Tidal amplitude (η_0, m) near the mouth (St0), (b) low-pass filtered (11 days) water level (Z_f , m) at stations St0-6 along the estuary, (c) low-pass filtered (40 hr) water level (Z_s , m) at St0-6, (d) residual water level Z_s - Z_f .

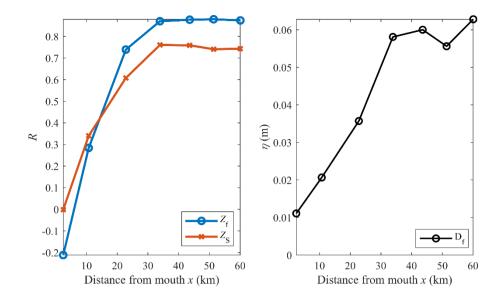
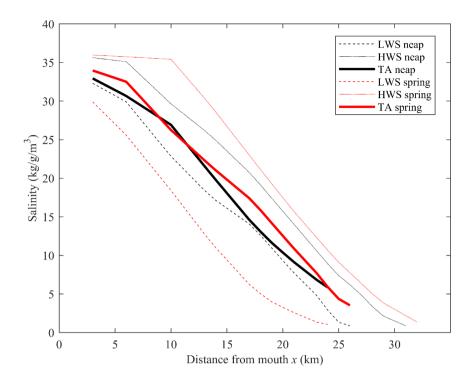


Figure 3: (a) Correlation coefficient (R) of the tidal amplitude forcing with the fortnightly water level Z_f (blue line) and subtidal water level Z_f (red line) along the estuary, (b) Amplitude of the 15 days tidal species D_f along the estuary during the neap-spring tidal cycle of 24-31 August 2015.



610 Figure 4: Vertically averaged salinity along the Guadiana estuary at spring tide (29 May 2019, red lines) and neap tide (06 June 2018, black lines) under a river discharge of 10 m³/s. The sampling was performed at high water slack (HWS, dotted lines) and low water slack (LWS, dashed lines) every 2-4 km along the channel. TA (solid lines) represents the tidally averaged salinity.

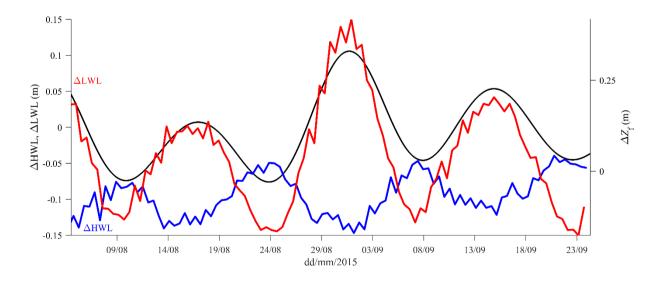


Figure 5: Differences in the relative water level between St3 and St0: fortnightly tide (ΔZ_f , black line, right axis), ΔHWL (blue line, 615 left axis) and ΔLWL (red line, left axis).

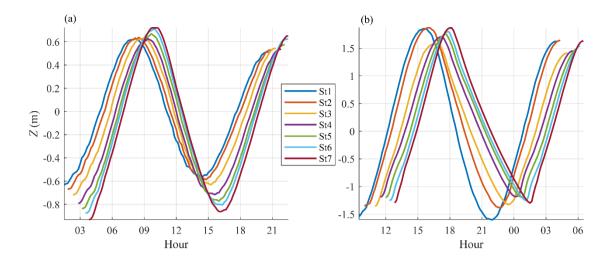


Figure 6: Water level variations (Z, m) at stations St0-6 on (a) neap (24/08/2015) and (b) spring (31/08/2015) tides.

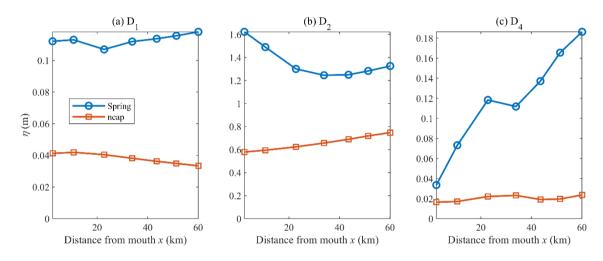


Figure 7: Amplitude (η, m) of (a) diurnal D_1 , (b) semi-diurnal D_2 and (c) quarter-diurnal D_4 tidal species along the channel during the largest spring (blue line, 31 August 2015) and lowest neap (red line, 24 August 2015) tides.

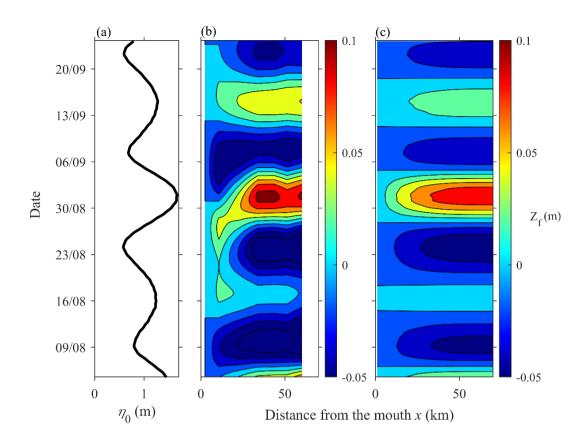


Figure 8: (a) Tidal amplitude at the mouth (η_0, m) , (b) observed (Z_f) and (c) simulated (Zm) fortnightly water level variations along the Guadiana estuary.

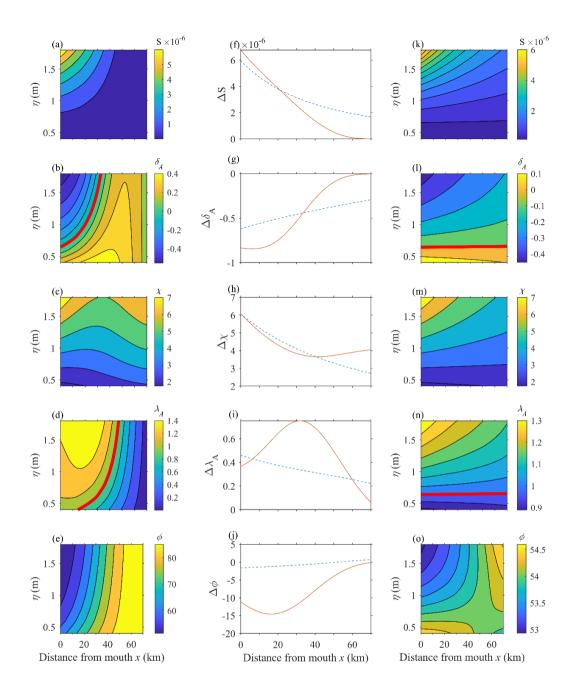


Figure 9: Tidally averaged slope (S) and main dimensionless parameters describing the tidal propagation along the Guadiana in function of the tidal amplitude at the mouth (η_0 , m): the damping number for water level (δ_A), the friction number (χ), the celerity number for water level (λ_A) and the phase angle between velocity and elevation (ϕ). The left column (a-e) and the right column (k-o) represent the results for a semi-closed channel and an infinite channel, respectively; the middle column (f-j) represents the spring-neap difference for each parameter (ΔS , $\Delta \delta_A$, $\Delta \lambda_A$ and $\Delta \phi$, respectively). The thick red lines presented in subplots b and l correspond to δ_A =0; in subplots d and n, they correspond to λ_A =1.

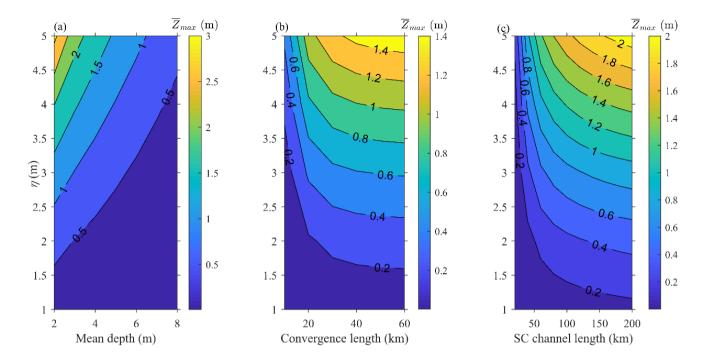


Figure 10: Maximum tidally average water level (\overline{Z}_{max}) as a function of the tidal forcing and mean depth (a), convergence length (b) and estuary length (c) at a semi-closed channel.

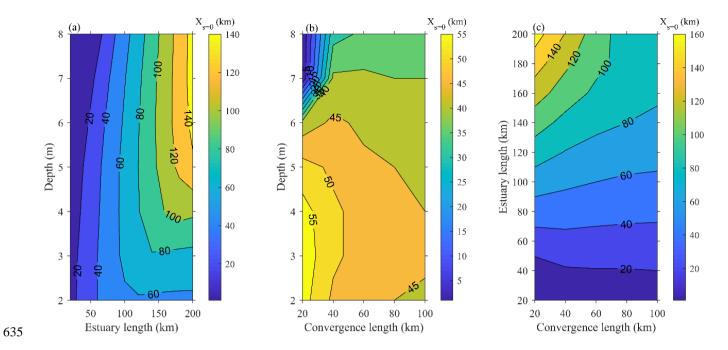


Figure 11: Position of negligible slope ($X_S=0$, in km) along a semi-closed channel with distinct geometric settings. In (a) the convergence length is 38 km, in (b) the estuary length is 78 km and in (c) the water depth is 5.5 m (as at the Guadiana).

Table 1: The definitions of dimensionless parameters.

Independent	Dependent
	Tidal amplitude $\zeta = \eta / \overline{h}$
	Friction number $\chi = r_S c_0 \zeta g / \left(K^2 \omega \overline{h}^{4/3}\right)$
Tidal amplitude at the mouth $\zeta_0 = \eta_0 / \overline{h}$	Velocity number $\mu = \upsilon / (r_S \zeta c_0) = \upsilon \overline{h} / (r_S \eta c_0)$
Estuary shape number $\gamma = c_0 / (\omega a)$	Celerity number for water level $\lambda_A = c_0 / c_A$
Friction number at the mouth $\chi_0 = r_s c_0 \zeta_0 g / \left(K^2 \omega \overline{h}^{4/3} \right)$	Celerity number for velocity $\lambda_V = c_0 / c_V$
Estuary length $L_e^* = L_e / L_0$	Damping /amplification number for water level $\delta_A = \frac{c_0}{\eta \omega} \frac{\mathrm{d} \eta}{\mathrm{d} x}$
	Damping number for velocity $\delta_{V} = \frac{c_{0}}{v\omega} \frac{dv}{dx}$
	Phase lead angle $\phi = \phi_V - \phi_A$