Assessment Components of 21 years (1995-2015) of Arctic Ocean Absolute Sea Level Trends (1995-2015) in the Arctic

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Abstract. The Arctic Ocean is at the frontier of the fast changing climate in the northern latitudes. As the first In this study, we validate and assess the components of the observed sea level trend (SLT) from altimetry and tide gauges (TG) , without using observations from the from 1995-2015. The Arctic Ocean manometric (mass component of the) SLT is estimated by solving the elastic Greens Functions for the contemporary mass changes of glaciers, Greenland and Antarctica and accounting

- 5 for Glacial Isostatic Adjustment (GIA) and the Inverse Barometer (IB) effect. This approach does not use ocean mass data from The Gravity Recovery and Climate Experiment (GRACE). This approach permits a longer time series and avoids problems with errors from leakage effects associated with GRACE. Steric and manometric sea level change is reconstructed and, which permits extension of the timeseries into the pre-GRACE era and also bypasses known leakage effects of GRACE-products from contemporary deglaciation in the Arctic. Halo- and thermosteric sea level is estimated by interpolating 300,000 temperature
- 10 (T) and salinity (S) in-situ observations.

The manometric and steric sea level is combined into an Aretie a reconstructed sea level estimate , that is independent from any observed sea level change. Relative sea level observed by that is compared to the observed SLT from altimetry and 12 selected tide gauges is corrected with novel (TG) corrected for vertical land movement (VLM)estimates accounting for past and contemporary deglaciation. The calculations shows that contemporary deglaciation alters the Aretic absolute sea level of

15 around 1 mm y^{-1} , while. The reconstructed estimate manifests that the salinity-driven halosteric sea level trend component is dominating the sea level trend spatial SLT-pattern with variations between -7 and 10 mm y^{-1} .

Large uncertainties originate from limited data to constrain the steric data in some regions. The manometric SLT is in comparison estimated to 1-2 mm y^{-1} for most of the Arctic while also altimetry is visibly challenged in sea ice covered areas. The reconstructed sea level estimate SLT shows a larger sea level rise in the Beaufort Sea compared to altimetry,

20 which was also identified by previous studies. A TG-observed sea level rise in the Siberian Arctic is opposing the sea level fall from the reconstructed and altimetric estimate.

The reconstructed SLT agrees (within uncertainty the 68% confidence interval) with the observed sea level SLT from altimetry in 9860% of the Arctic and for 11 (between 65N and 82N) and with 5 of 12 TGs. The correlation between the reconstructed estimate and altimetry (R=0.50) clearly outperforms a similar study using GRACE-estimates. The results confirm a large

25 negative absolute sea level trend shown by other studies in the eastern Siberian Arctic, that is in contrast to the significant sea level rise observed in the area by TGsTG-derived (VLM corrected) SLT estimates. The residuals are seemingly smaller than results from similar studies using GRACE estimates and modelled T/S-data. Thus is the reconstructed manometric component suggested as an legitimate alternative to GRACE, that can be projected into the past and future.

1 Introduction

- 30 The Arctic is globally the region with the fastest changing climate and is warming twice the rate of the global average (Box et al., 2019). The resulting enhanced deglaciation of land, <u>decline of sea</u> ice cover decrease and ocean freshening has several affects on sea level, hence understanding sea level in the Arctic Ocean paramount for mapping consequences of climate change. At the same time, oceanographic in-situ observations and satellite observations. Hence are observations of sea level a measure of multiple ongoing processes, but naturally lacks information on the source of sea level change. Parallel are sea level
- 35 <u>observations from satellite altimetry and tide gauges</u> of the Arctic <u>are prone to challenges from Ocean challenged by an harsh</u> environment, sea ice floes and lack of spatial coverage (Smith et al., 2019). <u>Decomposing the observed long term sea level</u> change provides insight into the regional effects of ongoing climate processes and helps consolidating the observed sea level.

Satellite altimetry has been measuring the measured the sea level of the Arctic Ocean since 1991 with ESA's European Remote Sensing (ERS)-1 satellite being the first reaching polar latitudes. (Laxon et al., 2003) were the first to study Arctic sea level

40 from the ERS-1/2 satellites to produce sea-ice sea ice thicknesses. Since then many have followed e.g. (Peacock and Laxon, 2004; Prandi et , but uncertainties (Peacock and Laxon, 2004; Giles et al., 2012; Prandi et al., 2012; Cheng et al., 2015; Rose et al., 2019), but large variability in particular in sea ice-covered regions are still present (Armitage et al., 2016; Rose et al., 2019; Raj et al., 2020) (Armitage et al., 2016; Carret et al., 2017; Rose et al., 2019).

Reconstructing sea level change with the sea level budget is useful both to constrain sea level observations and separate

- 45 sterie-driven and manometric sea level change (Gregory et al., 2019) and hence quantify the origins of sea level change. The sea level budget has been assessed-resolved on global and basin-wide scales since the for observations since the begin of the 19th century by using a combination of in-situ data, satellite observations and probabilistic analysis (Church and White, 2011a; WCRP, 2018; Dangendorf et al., 2019; Royston et al., 2020; Frederikse et al., 2020), but these studies tends to neglect the polar region are neglecting the polar regions due to large uncertainties and the relative small area of the Arctic Ocean in a
- 50 global context.

Previous <u>studies have made</u> attempts to reconstruct sea level in the Arctic has shown to be difficult (Henry et al., 2012; Armitage et al., 20 , because both satellite observations and in-situ observations are less consistent than in low and mid-latitudes. Observations from the Gravity Recovery And Climate Experiment (GRACE) offer the only direct Arctic-wide measurements of manometric sea level change since mid-2002. However, discrepancies of over 10 spatially (Henry et al., 2012; Carret et al., 2017; Raj et al., 2020; Ludw

, while Armitage et al. (2016) estimates the mass and steric SLT-components as basin-wide average. All studies are using different solutions of GRACE to obtain their result. Henry et al. (2012) used CSR-RL04 (Bonin et al., 2012) from 2003-2009, Armitage et al. (2016) used JPL-RL05 (Chambers and Bonin, 2012) from 2003-2014, and Raj et al. (2020) used GSFC-mascons (Luthcke et al., 2013) from 2003-2018. Carret et al. (2017) and Ludwigsen and Andersen (2020) compared the sea level trend of different GRACE-solutions which revealed discrepancies of 5-10 mm y⁻¹ (Ludwigsen and Andersen, 2020) exist among

- 60 different GRACE-products (Wiese et al., 2016; Save et al., 2016; Lutheke et al., 2013), and previous studies often tend to choose the solution that has the best agreement with the absolute sea level observed by altimetry and modeled steric sea level (Carret et al., 2017; Raj et al., 2020)in large areas of the Arctic. This disagreement among GRACE-solutions has been attributed to different methods to remove contamination from land mass changes that leaks into the ocean signal observed by GRACE (Mu et al., 2020). Hence is the chosen GRACE-solution consequential for the sea level budget and its ability to validate
- 65 altimetric observations.

In this paper, we attempt to assess the satellite and tide gauge observed contrast to the mentioned Arctic sea level trends from 1995-2015 budget studies, this study bypasses GRACE-based ocean mass estimates by reconstructing the sea level response to contemporary land ice loss, glacial isostatic adjusment (GIA) and atmospheric pressure (inverse barometer, IB) and thereby mapping the which results in a long-term manometric sea level ehange without GRACE. The time series of 21 years is generally

- 8 years more than assessments using GRACE (Armitage et al., 2016; Carret et al., 2017; Raj et al., 2020). This estimate. This approach gives three advantages over GRACE: (i) Insights of the different contributions to manometric sea level change, (ii) a longer time series that extends into the pre-GRACE era, which has the advantage, that non-secular and inter-annual dynamic ocean dynamic mass effects, which are mainly driven by the Arctic Oscillation , (Henry et al., 2012; Armitage et al., 2018) are reduced (AO) (Henry et al., 2012; Volkov and Landerer, 2013; Peralta-Ferriz et al., 2014; Armitage et al., 2018), are reduced
- 75 and (iii) Mentioned leakage from effects caused by the low spatial resolution (300-500 km (Tapley et al., 2004)) are avoided. Combining the manometric 1995-2015 SLT-estimates with satellite-independent steric SLT estimates (Ludwigsen and Andersen, 2020) reconstructs the absolute SLT as it is observed by altimetry. Besides consolidating observed sea level change, the sea level budget decomposition permits analysis of the sources of contemporary long-term Arctic sea level change, which also aids predictions of future change.

80 2 Method

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Sea level observations from satellite altimetry are measured relative to a terrestrial reference frame and is <u>called referred to</u> as geocentric or absolute sea level (ASL) <u>observations</u>. Tide gauges (TG) measures the sea level while being grounded to the coast, and is affected by vertical <u>deformations of the solid earth, called vertical</u> land movement (VLM). The ASL (similar to altimetry) can be reconstructed by adding vertical land movement (VLM), When VLM is defined with respect to the same

85 reference frame as altimetry , to tide gauge-measured and added to TG-measured relative sea level (RSL) - the ASL is restored:

$$ASL = RSL + VLM \tag{1}$$

Changes of ASL (ASL) originates either from changed ocean density (steric, $\dot{\eta}$) due to changes in salinity (halosteric) or temperature (thermosteric) or from changes in ocean mass, which is defined as manometric sea-level sea level change, \dot{M} (Gregory et al., 2019)). According to (Gregory et al., 2019), manometric sea level change can be referred to as the 'non-steric'

sea level change and is assumed indifferent to the commonly used Ocean Bottom Pressure (OBP).

$$A\dot{S}L = \dot{\eta} + \dot{M} \tag{2}$$

As already mentioned, the steric sea level change can be is split into halosteric (η_S) and thermosteric (η_T) sea level change:

$$\dot{\eta} = \dot{\eta}_S + \dot{\eta}_T \tag{3}$$

95 The manometric component is further divided into contributions from changes in the gravitational field, G that together with a spatial uniform constant, c, composes the gravitational sea level fingerprint (N) due to different land-to-ocean mass changes, i, which in this study originates from either different sources of land ice (Greenland (GRE), Northern Hemisphere (NH) Glaciers and Antarctica (Ant) + Southern Hemisphere (SH) glaciers) or GIA. Change in HB-atmospheric pressure (Inverse Barometer, IB) is also part of the total manometric sea level change, M.

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$$\dot{\mathbf{M}} = \sum_{i} \dot{N}_{i} + \dot{\mathbf{B}}$$
, where $\dot{N}_{i} = \dot{G}_{i} + \dot{c}_{i}$ (4)

By substituting eq. 4 and eq. 3 into eq. 2, we achieve the reconstruction of absolute sea level, ASL_r , that is comparable with the altimetry observed ASL (denoted as ASL_A):

$$A\dot{S}L_{r} = \sum_{i} (\dot{G}_{i} + \dot{c}_{i}) + I\dot{B} + \dot{\eta}_{S} + \dot{\eta}_{T}$$

$$(5)$$

VLM is split into the viscoelastic solid earth deformation caused from past millennial ice (un-)loading, GIA, and the elastic adjustment from contemporary (1995-2015) change in ice loading, VLMe, which, as G, is a composite of the elastic response from different origins of land ice (*i*). Possible local VLMs not associated with glacial mass redistribution (i.e. non-glacial land water change, tectonics or oil depletion) is not accounted for since little knowledge on their VLM-contribution exist. Frederikse et al. (2019) used GRACE-observations to estimate the non-glacial VLM, which varied between -0.5 mm y⁻¹ in North America and +0.2 mm y⁻¹ in the Barents/Kara sea region.

110 $V\dot{L}M = G\dot{I}A + \sum V\dot{L}Me_i$

By substituting eq.4 and eq. 3 into eq. 2, we achieve the reconstruction of absolute sea level, ASL_r , that is comparable with the observed ASL by satellite altimetry (denoted as ASL_A):

$$V\dot{L}M = \underbrace{\sum}_{i=1}^{n} (G\dot{I}A + \underline{)} + \underline{+}_{S} + \underline{T}_{i} \sum_{i=1}^{n} V\dot{L}\dot{M}e_{i}$$
(6)

Thirdly, a TG-based ASL estimate, ASL_{TG} , is achieved by adding Adding VLM (eq. 6to-) to TG-measured RSL, gives 115 according to eq. 1 ÷ a third ASL estimate, ASL_{TG} :

$$AS\dot{L}_{TG} = RS\dot{L}_{TG} + \underline{GIA}G\dot{I}A + \sum V\dot{L}\dot{M}e_i$$
(7)

3 Data

This study combines various in-situ data (temperature and salinity (T/S) profiles and TG-data), satellite (GRACE and altimetry) altimetry and model data (VLM-model and ECCOv4r4 and VLM) to reconstruct the Arctic sea level change. In this section follows a description of the different datasets and how they are obtained.

3.1 Altimetry

The DTU/TUM Arctic Ocean Sea Level Anomaly sea level anomaly (SLA) record (Rose et al., 2019) provides an independent estimate of ASL change ($ASL_A ASL_A$). The altimetric time series is covering the whole altimetric era given as monthly grids from September 1991 to September 2018, covering 65° N to 81.5°N and 180°W–179.5°E.

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The product is corrected by geophysical corrections such as tides and atmospheric delays. Leads (cracks in the sea ice cover) and open ocean are located and separated according to the different classification of their surfaces. The detection of leads is not flawless, and their sparse distribution in the sea ice cover, and the uncertainty of the the applied geophysical corrections in the Arctic (Stammer et al., 2014; Ricker et al., 2016) makes the sea level estimates more uncertain in the sea ice covered region.

- The altimetric record includes data from four ESA satellites: ERS-1 (1991-1995), ERS-2 (1995-2003), Envisat (2002-2010) and CryoSat-2 (2010-2018). It combines results of different retrackers as well as conventional and SAR-altimetry , which may lead to biases (Rose et al., 2019). In particular ERS-1/2 has a relatively low spatial resolution and thereby limiting the measurements from leads in sea ice , while the are limited. The SAR altimeter on CryoSat-2 is made designed to measure over the sea ice cover, which increases the observations from leads and decreases the uncertainty (Rose et al., 2019). The uncertainty however remains large in the Arctic due to varying sea ice cover and large spatial and temporal non-seasonal variability associated with the Arctic Oscillation (Armitage et al., 2018; Raj et al., 2020). The applied version of the DTU/TUM altimetry
- product is not corrected for <u>GIA or</u> atmosphere pressure loadingto be able to compare to the tide gauges . The altimetric sea level trend is shown in the results section (the middle panel of figure 6).

3.2 Tide Gauges and Vertical Land Movement

TG-data Observations from tide gauges (TG) is obtained from the Permanent Service of Sea Level sea level (PSMSL)-database
(Holgate et al., 2012) given as monthly SLA. TGs with a consistent time series are few and unevenly distributed in the Arctic (Henry et al., 2012; Limkilde Svendsen et al., 2016). Usually, TG-observed RSL is aligned to ASL by utilizing vertical velocities from a nearby Global Navigation Satellite System (GNSS) receiver. Restricting However, only few reliable GNSS-data that spans the time period of this study at coastline of the Arctic Ocean exist (Wöppelmann and Marcos, 2016; Ludwigsen et al., 2020a) and restricting TGs to locations with usable GNSS significantly limits the selection of TGs further. Therefore, an Arctic-wide

145 VLM-model (Ludwigsen et al., 2020a) with annual VLM-rates from 1995-2015 (Ludwigsen et al., 2020a) is utilized as a substitute for GNSS is applied (figure 1). A detailed comparison between 2003-2015 vertical rates from the used VLM-model and GNSS-measurements (from URL6B (Santamaría-Gómez et al., 2017)) showed very good agreement, in particular along the Norwegian Coast Ludwigsen et al. (2020a).



Figure 1. Left: 1995-2015 RSL trend [mm y^{-1}] and location of the selected tide gauges of this study. Right: 1995-2015 VLM-trend [mm y^{-1}] from the model of Ludwigsen et al. (2020b). The VLM-trend from the GNSS-sites at Reykjavik and Ny-Ålesund are shown with squared color coded markers.

The region around the Ny-Ålesund TG and Reykjavik TG experiences extraordinary VLM that is caused by substantial
deglaciation during the Little Ice Age (LIA) (Svalbard) and low mantle viscosities in Iceland and Greenland. This is not captured in the spatially uniform REF6371 earth model (Kustowski et al., 2007) used in the VLM-model. Therefore, the two sites are corrected with nearby GNSS instead of the VLM-model. Large residual between the VLM-model (-1.4mm y⁻¹) and GNSS (-3.2 mm y⁻¹) was also found at Prudhoe Bay. This additional subsidence is likely caused by near-by construction or oil depletion sites. However, the tide gauge is located on a peninsula reaching into the Beaufort Sea 10 km away from the GNSS-location, which is why the VLM-model is trusted over the GNSS-measurement.

The VLM-model is composed from eq. 6. The GIA-component is based on the Caron2018 GIA-model (Caron et al., 2018), which includes an uncertainty estimate. Reported discrepancies from other GIA-models in central North America and Greenland (Caron et al., 2018; Ludwigsen et al., 2020a) has little affect at the locations of TGs of this study. Annual rates of VLMe is estimated from the 1995-2015 annual change of land ice using the Regional Elastic Rebound Calculator (REAR) (Melini

- 160 et al., 2015). REAR also provides the gravitational response G to land ice change used for estimating the manometric sea level. Uncertainties of the elastic VLM-estimates are mainly due to uncertainties of the applied land ice change. An additional 10% of the VLM-signal (after Wang et al. (2012)) is added to represent uncertainties associated with the REF6371 Earth earth model (Kustowski et al., 2007) applied in REAR. The VLM contribution from non-tidal ocean loading (NOL) (van Dam et al., 2012) and rotational feedback (RF) (King et al., 2012) are in total of an order of ± 0.3 mm y⁻¹ and are included in the
- 165 VLM-contribution from Northern Hemisphere glaciers.

12 TGs are selected (geographical locations shown in figure 1) based on visual inspection of the monthly time series and to ensure that as many regions of the Arctic is represented as possible. 3-month averaged time series and linear trend of TG observed sea level (RSL_{TG}) and VLM-corrected sea level (ASL_{TG}) from 1995-2015 is shown in figure 2. The annual VLM-model is interpolated onto the TG time series and the linear trend is determined with least-squares method using months with

170 available data between 1995 and 2015. In particular, the Alaskian and Siberian TGs have months with no or unreliable data (flagged by PSMSL). However, there is no evident seasonality in the missing months and therefore the trend estimates are not significantly affected by a seasonal bias.

Ny-Ålesund and Reykjavik TG experience extraordinary VLM that is caused by substantial deglaciation during the Little Ice Age (LIA) (Svalbard) and low mantle viscosities in Iceland and Greenland. This is not captured in the spatially uniform

- 175 REF6371 earth model. Therefore, the two sites are corrected with nearby GNSS (Global Navigation Satellite System) instead of the VLM-model. GNSS is uncertain at Prudhoe Bay, where it measures a significant subsidence, that is considerably different from the VLM-model. This is likely caused by near-by construction or oil depletion sites. However, the tide gauge is located on a peninsula reaching into the Beaufort Sea 10 km away from the GNSS-location, which is why the VLM-model is trusted over the GNSS-measurement.
- 180 **Reykjavik** (Reykjavik (64.2°N), Nome (64.5°N), and Rorvik (64.9°N) are located off the edge of the altimetric data, which only extends to 65°N, but are nevertheless included to extend the spatial distribution of the TG-sites.

From figure 2, we see that the RSL-trends in the Arctic vary with nearly +/- 1 cm y⁻¹, with Ny-Ålesund on Svalbard having a negative RSL-trend of -7.45 mm y⁻¹, while Kostelnyi Island between the Laptev and East Siberian Sea shows a positive trend of 7.67 mm y⁻¹. However, after applying the VLM-correction, all TGs show a positive ASL-trend within a range of 0.3
0.38 mm⁻¹ (Prudhoe Bay) and 6.5-6.55 mm⁻¹ (Kostelnyi).

3.3 Steric sea level

The DTU steric sea level change is computed as described in Ludwigsen and Andersen (2020)steric estimate is derived from the DTU Steric product (Ludwigsen and Andersen, 2020). The steric sea level change is computed heights are calculated from a three dimensional T/S-grid that is interpolated from a over more than 300,000 T/S profiles and thus not constrained by any satellite observations. The independent steric sea level estimate is in contrast This approach is different to Morison et al. (2012) and Armitage and Davidson (2014)Armitage et al. (2016), that use a difference between altimetry and GRACE to estimate steric heights and Henry et al. (2012); Carret et al. (2017); Raj et al. (2020), that use model-estimates of T/S to calculate the steric component.

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T/S-profiles from buoys, ice-tethered profiles and ship expeditions in the Arctic Ocean are <u>as shown in figure 3</u> spatially and temporally unevenly distributed and also depends on seasonal accessibility (Behrendt et al., 2017). Especially, the data density is poor in the shallow seas along the Siberian Coast (Ludwigsen and Andersen, 2020), which results in large uncertaintiesmaking these areas the most uncertain. In the interior of the Arctic Ocean mostly summer data are available, while in the North Atlantic decent data coverage is reached year-around (figure 3). Temperature and salinity data are interpo-



Figure 2. Relative sea level [m] from 1995-2015 registered at the 12 tide gauge from the PSMSL-database (Holgate et al., 2012)]. Blue line represents the 3-month running average, while the thick line is the linear trend (trend estimate $[mm y^{-1}]$ shown in legend). Yellow line represents the absolute sea level and trend, equal to the blue line corrected for VLM with a VLM-model (Ludwigsen et al., 2020b) (except Ny-Ålesund and Reykjavik that are corrected with GNSSan extrapolated GNSS-trend). The vertical lines indicate where observations are missing and the sea level is linearly interpolated from adjacent months.

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lated by kriging into a monthly 50x50 km spatial grid on 41 depth levels. If values are more than 3σ away from the mean of neighbouring grid cells, values from the same month in adjacent years is used.

Following the notion of Gill and Niller (1973); Stammer (1997); Calafat et al. (2012); Ludwigsen and Andersen (2020), the change in steric sea level is calculated as the sum of halosteric sea level, η_S and thermosteric sea level, η_T (equation 3). From the depth profiles of the temperature and salinity T/S grid, η_S and η_T are calculated:

$$\eta_{S} = -\frac{1}{\rho_{0}} \int_{-H}^{0} \beta S' dz$$
(8)
205 $\eta_{T} = \frac{1}{\rho_{0}} \int_{-H}^{0} \alpha T' dz$
(9)



Figure 3. Percentage of months with available T/S data in 200x200 km grid cells. Left map: Summer months (May-October). Right map: Winter months (November-April).

where *H* denotes the minimum height (maximum depth (z)). The maximum integration depth is as in Ludwigsen and Andersen (2020) 2000 meters. *S'* and *T'* are defining salinity and temperature anomalies, with reference values (as used in Ludwigsen and Andersen (2020)) are 0 C° and 35psu, respectively. β is the saline contraction coefficient and α is the thermal expansion coefficient. The opposite sign of η_S is needed since β represents a contraction (opposite to thermal expansion). α and β are functions of absolute salinity, conservative temperature and pressure, and is determined with help from the freely available TEOS-10 software (Roquet et al., 2015). Sea level trends of η_S and η_T from 1995-2015 are shown in figure 4.

3.4 Manometric sea level contributions

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Maps of the individual contributions from 1995-2015 to manometric SLTs (from equation 4) to changes in manometric sea level are shown in figure 5. The gravitational sea level change (\dot{G}) of contemporary changes in ice loading ice loading change

215 (equation 4) is computed , similar to the elastic VLM-component, by using solving the elastic greens functions by with REAR (Melini et al., 2015). The gravitational sea level change from GIA is derived from the Caron2018-model.

The sea level fingerprint of each component (figure 5a-d) is retrieved by adding the spatially invariant constant c (barystatic (global mean) sea level contributionsea level change) to the gravitational changeand. c is equal to the individual components contribution to global mean sea level (given in brackets of figure 5) (Spada, 2017). Following Spada (2017), c is defined as

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$$c_i = -\frac{M_i \rho_w}{A_O} - \left\langle G_i - \text{VLM}_i \right\rangle \tag{10}$$



Figure 4. Halo- and thermosteric sea level trend $[mm y^{-1}]$ from 1995-2015 derived from the DTU Steric sea level product used in Ludwigsen and Andersen, 2020).

, where M_i is the mass change of the ice model, A_O is the total ocean area, ρ_w is the average density of ocean water and $\langle ... \rangle$, denotes the average of the ocean surface. For calculating c_i , G_i and VLM_i for glacierswith REAR, individual glacial mass estimates are combined into a high resolution model for ice height change (Marzeion et al., 2012; Ludwigsen et al., 2020a). These estimated are combined with ice models Ice models are used for Greenland (Khan et al., 2016) and Antarctica (Schröder et al., 2019). From 1995 to 2015, the estimated ice loss is 142 Gt y⁻¹ for Greenland, 206 Gt y⁻¹ for Northern Hemisphere glaciers and 105 Gt y⁻¹ for Antarctica and Southern Hemisphere glaciers, consistent with recent studies by Zemp et al. (2019); Shepherd et al. (2018, 2020)Zemp et al. (2019) and Shepherd et al. (2018, 2020).

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The contemporary change in ice mass, M_i, is zero for GIA, hence GIA is assumed to be unaffected by contemporary ice changes. This means that the barystatic GIA contribution, c, is defined from the right part of equation 10. c for GIA is, which
 is estimated to 0.3 mm y⁻¹ consistent with other studies (Peltier, 2009; Spada, 2017). The gravitational sea level change of RF and NOL (≪is less than 0.05 mm y⁻¹), and are included in the Northern Hemisphere glacial contribution to G.



Figure 5. Contributions to the Arctic manometric sea level trend $[mm y^{-1}]$ from 1995-2015. a-d shows \dot{N} (eq. 4) for different sources of land-to-ocean mass changes with the barystatic sea level contribution (\dot{c}) written in brackets: Greenland (incl. peripheral glaciers) (a), Northern Hemisphere (NH) glaciers (b), Antarctica (Ant) + Southern Hemisphere (SH) glaciers (c), and GIA (d). The estimated Inverse Barometer trend (e). The sum of a-e and hence the total reconstructed manometric sea level trend (f). Modelled OBP-estimate from ECCOv4r4 (Fukumori et al., 2019) (g). Difference between g and f (h).

The manometric sea level change <u>SLTs</u> is completed with the loading from atmospheric pressure, IB (figure 5e). IB is estimated by the simple relationship derived from the hydro-static equation (Naeije et al., 2000; Pugh and Woodworth, 2014). Monthly averaged pressure estimates from National Center for Environmental Prediction (NCEP) are used for surface pressure change Δp :

 $\mathbf{IB} = -9.948 \, [\mathsf{mm/mbar}] \, \Delta p \tag{11}$

The total manometric sea level change SLTs (M, figure 5f) is reconstructed as:

$$\dot{\mathbf{M}} = \dot{N}_{\mathrm{NHG}} + \dot{N}_{\mathrm{GRE}} + \dot{N}_{\mathrm{SH}} + \dot{N}_{\mathrm{GIA}} + \mathbf{I}\mathbf{\dot{B}}$$
(12)

Figure 5g shows the OBP-trend from the ECCOv4r4-model (Estimating the Circulation and Climate of the Ocean (ECCO)
version 4 release 4) (Forget et al., 2015; Fukumori et al., 2019), which is a model estimate of M. The ECCO consortium (ecco-group.org) combines ocean circulation models with observations to estimate different physical parameters of the ocean. The model is among others constrained with observations from GRACE, satellite altimetry and in-situ T/S-profiles (Fukumori et al., 2019), The difference between ECCO OBP and M is displayed in figure 5h.

4 Results

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- 245 Generally, the steric (in particular the halosteric) The reconstructed sea level trend is dominating the spatial variability of the reconstructed sea level trend (ASL_r), with over 10 from 1995 to 2015 (\dot{ASL}_r) is shown in figure 6 panel (i) and the residual to altimetry is shown in figure 7. In large the spatial variability and residual is dominated by the halosteric sea level rise in the Beaufort Sea (10-15 mm y⁻¹), halosteric sea level fall in the East Siberian Sea (5-8 mm y⁻¹ in the Beaufort Gyre and -7) and thermosteric sea level rise (2-5 mm y⁻¹) in the Norwegian Sea, where thermal expansion has a relatively larger impact
- 250 compared to the near-freezing temperatures in the interior of the Arctic Ocean. A similar pattern is observed by altimetry (figure 6 panel (ii)), albeit a smaller sea level rise in the Beaufort Sea and East Siberian Sea is detected.

The right panel of figure 7 shows the correlation matrix between $A\dot{S}L_{ATG}$ and $A\dot{S}L_{r}$. The matrix shows that $A\dot{S}L_{r}$ and $A\dot{S}L_{A}$ are largely correlated (R=0.50). There is a large accumulation around 2 mm y⁻¹ in the Russian Arctic (figure 4), with slightly higher $A\dot{S}L_{A}$ than $A\dot{S}L_{r}$. This originates from the underestimate of $A\dot{S}L_{r}$ (see figure map of 7) in the Norwegian Sea.

255 This residual agrees with the ECCO OBP-M difference (figure 5h) and thus likely explained by the missing dynamic sea level contribution of M. From 7 also large residuals in the Beaufort Sea (ASL_r higher) and Siberian Coast (ASL_{A/TG} higher) are evident.

The sea level rise of Beaufort Sea has been associated with a spin-up of the Beaufort Gyre from 2005 to 2010 that accumulated a lot of freshwater (Proshutinsky et al., 2009; Giles et al., 2012; Armitage and Davidson, 2014). The halosteric

trend in the Beaufort Sea and thermosteric trend in the Norwegian Sea is in agreement with the steric estimates from 1992-2014 by Carret et al. (2017) and from 2003-2016 by Raj et al. (2020). The steric-driven sea level fall in the East Siberian Sea is not recognized in extent and magnitude by these studies, but is nevertheless in agreement with the observed sea level fall by Armitage et al. (2016), which attributes this pattern to a rapid 10-15 cm fall in halosteric height in the East Siberian Seas from 2012-2014, resulting in a 2003-2014 trend of around -5 mm y^{-1} .

- In contrast, is the The reconstructed manometric sea level trend (\dot{M}) , figure 5f) is varying between 0 and 2 mm y⁻¹, with smaller spatial variability. This is in alignment aligns with the 2003-2015 the release 05 GRACE-mascon OBP-estimates from GRACE JPL mascons JPL (Wiese et al., 2016) used in Ludwigsen and Andersen (2020), but way is much smaller than the estimates from GSFC mascons (RL05) (Luthcke et al., 2013) used by Raj et al. (2020) and CSR (Save et al., 2016) used by RL05 (Chambers and Bonin, 2012) preferred in Carret et al. (2017).
- Figure 5a-c shows that the contributions from contemporary ice loading has a (compared to steric) small contribution to spatial sea level variability, but the sea level fingerprints from deglaciation of Greenland and glaciers arehowever, however, still clearly visible with an absolute a sea level fall of 0.5 to 1 mm y^{-1} , which . This seems to be in agreement with global sea level fingerprint studies of Bamber and Riva (2010); Spada (2017); Frederikse et al. (2018). In total, the three figures sums to a sea level rise of around 1 mm y^{-1} in most of the Arctic, except close to areas with deglaciation in areas close to land-deglaciation (like Greenland and Svalbard).
 - Figure 5g shows that ECCO has a higher manometric sea level change higher manometric SLTs in the interior of the Arctic Ocean, while the coastal zones, except east East Siberia, are lower than M.

The ECCO-model does attempt to include term include a dynamic sea level changes change associated with wind-forcing and ocean currents into their OBP-estimate (Forget et al., 2015). Those changes are not part of \dot{M} and is probably the main reason

280 for the difference between ECCO OPB and M - seen in figure 5h. The dynamic mass variations follows largely the temporal variations of the AO (Peralta-Ferriz et al., 2014; Armitage et al., 2018). To some extent, the coastal/non-coastal Arctic dipole from Peralta-Ferriz et al. (2014) is recognized in figure 5h, but over the extent of the time series of this study, the effect of the AO is assumed to be less significant than the pattern in Peralta-Ferriz et al. (2014).

4.1 Comparing reconstructed ASL with altimetry

285 The reconstructed $ASL(ASL_r)$ trend is compared to the altimetric ASL trend (ASL_A) in figure 6, while TG-based $ASL(ASL_{TG})$ trend is indicated with dots. Table 1 and figure 8 shows the

4.1 Comparing reconstructed absolute sea level with altimetry

For 60 % of the area of the Arctic between $65N^{\circ}$ and $82N^{\circ}$ is the reconstructed sea level pattern ($A\dot{S}L_{r}$) in agreement with the observed sea level contributions estimated at each tide gauge. There is an overall agreement of the sea level trend pattern

- 290 in both ASL_r and ASL_A The main obvious difference between the spatial sea level pattern of ASL_r and ASL_A is the (ASL_A) within the 68% confidence interval (figure 7). The main difference between ASL_r and ASL_A is the mentioned larger sea level rise (residual of + 5-10 mm y⁻¹) in the Beaufort Sea and sea level fall (residual of 2-5 mm y⁻¹) in the East-Siberian seas of ASL_r. ASL_r. ASL_r. In the Norwegian Sea the residuals are in the order of +/- 1.5 mm y⁻¹.
- The correlation coefficient (R) between ASL_r and ASL_A is R=0.50 (R=0.23 without the halosteric contribution) and R=0.53 when using the ECCO OBP estimate instead of the reconstructed manometric sea level. The correlation is better than the



Figure 6. Absolute sea level trend of the reconstructed product (ASL_r) (first map from left (i)) and from DTU/TUM Altimetry (ASL_A) (second map (ii)) from 1995 to 2015 [mm y⁻¹]. In both maps is the sea level trend of the 12 VLM-corrected tide gauges (ASL_{TG}) shown with circles. Third panel from left (iii) shows the timeseries of ASL_A and ASL_r for two selected regions. Norwegian Sea (NS) and Beaufort Sea (BS) (marked in the DTU/TUM Altimetry map). The right panel (iv) shows the mean seasonal cycle for two periods of ASL_A (solid line: 1995-2009, dotted line: 2010-2015) and ASL_r (dashed line) for the same two regions as in (iii).

correlation coefficients reached by Ludwigsen and Andersen (2020) using different datasets of GRACE (R=0.19-0.40) combined with the same steric and altimetric dataset.

Absolute sea level trend of the reconstructed product $(A\dot{S}L_r)$ (left) and from DTU/TUM Altimetry $(A\dot{S}L_A)$ (middle) from 1995 to 2015 mm v⁻¹. The circles show the sea level trend of the 12 VLM-corrected tide gauges ($A\dot{S}L_{TG}$). Right plot shows

- 300 timeseries of ASL_A and ASL_r for two selected areas (marked in the DTU/TUM Altimetry map). Before the era of SAR altimetry (from pre CryoSat-2, launched in October 2010), the ability to separate the leads and the sea ice was more difficult due to the larger footprint of the conventional satellites. Therefore, in areas with a dense sea ice cover (like the Beaufort Sea), more altimetric observations exist during the sea level high of the autumn and fewer during winter/spring where sea level is lower (i.e.Armitage et al. (2016)). This creates e.g. Armitage et al. (2016)). The sampling of the seasonal signal (figure 6 panel
- 305 (iv)) can create a seasonal bias that is which was more pronounced before the CryoSat-2 era, because of the lower resolution in the pre-SAR era. This bias can explain the 'flattening' contribute to a flattening of the trend in the Beaufort Sea seen as seen from the time series in figure 6), where ASL_A panel (iii). In figure 6 panel (i) and (ii) ASL_A shows a smaller doming trend of the Beaufort Gyre than ASL_r . From the time series (right panel of figure 6) is it evident that ASL_A is higher than ASL_r from Sea than ASL_r , mainly caused by an apparent sea level decline from 2010-2015. Studies of altimetry-based sea level
- 310 in the Beaufort Sea from Giles et al. (2012) and Armitage et al. (2016) indicate a similar flattening of the sea level anomaly around 2009/10. The change in sea level trend is attributed to a shift in the cyclonic regime of the Beaufort Gyre in 2010/2011 (Proshutinsky et al., 2015) which released significant amounts of freshwater (Armitage et al., 2016). However, the significant change in the Beaufort Sea coincides with the transition from Envisat to CryoSat-2 and a inter-satellite bias in DTU/TUM Altimetry can not be excluded.
- 315 A previous study (Ludwigsen and Andersen, 2020) using the same steric sea level estimate combined with GRACE-observations showed a better agreement with the sea level trend of Armitage et al. (2016) in the Beaufort Sea than the DTU/TUM estimate in the present study. The residuals between $A\dot{S}L_r$ and $A\dot{S}L_{A}$ (of this study) are however seemingly smaller than the results from Raj et al. (2020) who found region-averaged residuals in the Beaufort Sea of +10 mm y⁻¹ from 2003-2009 and then shifts to a lower level after 2010. The same difference between ASL_r and ASL_A is not observed in a predominately non-SAR region
- 320 of the Norwegian Sea and +3.6 mm y⁻¹ from 2010-2016 between a GRACE+steric solution and the same DTU/TUM altimetry product. An significant underestimate of the altimetric observations (Cheng et al., 2015) was also identified by Carret et al. (2017) from both 1992-2014 and 2003-2010. Another altimetry based SLA-estimate from 2003-2015 (Armitage et al., 2016), observes a larger trend-
- The mean seasonal cycle of the Beaufort Sea (panel (iv) of figure 6) shows how a summer and wintertime peak of ASL_A (in January and June) is visible before 2010, but almost disappears in the CryoSat-2 era. The double-peak is also found by Armitage et al. (2016) from 2003 to 2014, but is not nearly as large because of the relative larger CryoSat-2 weight. Since the manometric components are yearly averaged, only the seasonal variations of the steric component of ASL_r is shown. From the figure, it is evident that the steric signal is dominating the seasonal variation in the Beaufort Gyre in alignment with the values of ASL_rSea, while a significant residual between steric and ASL_A, which indicates a dominant manometric signal.

330 This is in alignment of the results of (Carret et al., 2017), who found that the variability in the North Atlantic (GNB-sector) is predominantly non-steric.

In the altimetric estimate (middle panel of ASL_A (figure 6) a positive sea level trend extends shows a sea level rise in the Norwegian Sea that extends until it reaches the average sea ice boundary, which (intentionally) coincides with the average SAR-boundary of CryoSat-2. From altimetry it is unclear if this signal is a real physical signal or due to a bias when different

- altimetric observations (different satellites and SAR/non-SARconventional), sea ice and open ocean regions are aligned in the (no sea state bias correction in the SAR areas) in the DTU/TUM product or an altimetry product or a known error in the SAR-based DTU18MSS (Andersen et al., 2018) that is used as a reference in the altimetry data. From the ASL_r some of the positive sea level trends is restored ASL_r shows a similar SLT-pattern in the Norwegian Sea by from a combination of the thermosteric contribution (change (warmer ocean) (figure 4) and the negative gravitational contribution from a sea level fall from
- 340 a gravitational weakening of Greenland (figure 5a). The boundary between sea ice and open ocean is however less significant in $ASL_r ASL_r$ and a spatial bias in altimetry cannot be excluded. A thermosteric sea level rise that is countered by a halosteric sea level fall in the Norwegian Sea is also reported by the other studies (Henry et al., 2012; Carret et al., 2017; Raj et al., 2020) . The residuals in the present study are however qualitatively smaller than the results of the mentioned studies, albeit they use different subsets of periods and for the case of Raj et al. (2020) only basin-wide averages are given.

345 4.2 Comparing ASL-trends at tide gauge locations

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TGs only measure sea level in coastal areas, and are therefore not useful when analyzing spatial sea level trend patterns of the interior of the Aretic OceanTGs measures sea level from the coast, and thus only able to observe coastal sea level change. Furthermore, is the coastal location often disturbed by the local environment that might be unknown (e.g. small river outflow, local construction, packing of sea ice etc.), which can influence affects both sea level measurements from tide gauge TGs and altimetry.

In figure 8 and table 1, the contributions to ASL_r is ASL_r are quantified at the location at each of the twelve-12 TGs by taking the mean trend of a radius of 50 km (5 km for GIA and elastic VLM). This radius ensures, that Rorvik, Nome and Reykjavik overlaps the altimetric data, but the fewer number of data points might cause the data-altimetry estimates at these TGs to be more variable and hence increase the uncertainty (estimated as. The residuals between the TG-observed ASL-trend,

355 ASL_{TG} , and ASL_{r} are visible from figure 6. ASL_{TG} is in agreement of ASL_{r} at only 5 of the 12 TGs (8 of 12 for ASL_{A} / ASL_{TG}) are within the combined standard error, σ), while 9 are within two standard errors (95 % confidence interval). Relative low standard errors of ASL_{TG} contributes to the apparent low agreement.

The Norwegian tide gauges (Rorvik, Tromso, Vardo) are considered the most stable and also show the lowest error estimate (together with Ny-Ålesund). ASL_r is in good agreement with the tide gauge and is for , Ny Ålesund) are together with

360 Reykjavik the most consistent with the smallest errors. These are also the sites where ASL_A and ASL_r are most precise, due to little or no sea ice and high density of hydrographical data (figure 3). For Rorvik and Vardoin better alignment with ASL_{TG} than ASL_A. This is also the region with highest density of hydrographical data and thus the region with the most reliable steric estimate, is ASL_T more in alignment with ASL_{TG} than ASL_A, while ASL_{TG} of Tromso and Ny Ålesund is better aligned with



Figure 7. Left map shows the difference between $A\dot{S}L_{r}$ and $A\dot{S}L_{A/TG}$. The dark green contour shows the areas or tide gauges (green edge) where the absolute difference is larger than one standard error (68% confidence interval), but less than two standard errors (95% confidence interval) (combined error from figure 9). The light green areas or tide gauges (light green edge) where the absolute difference is larger than two standard errors. Right panel shows a correlation matrix between $A\dot{S}L_r$ and $A\dot{S}L_{A/TG}$. The color indicates the number of data grid cells falling into bin size of 0.5 mm y⁻¹. 96% of the grid cells with data is covered within the bounds of the matrix (N_{total}=18150). The red line is where $A\dot{S}L_r$ is equal to $A\dot{S}L_{A/TG}$.

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- $A\dot{S}L_A$. We see that for Vardo and Rorvik, the <u>sea level change $A\dot{S}L_T$ </u> is split between a steric and a mass contribution of roughly the same size, which is similar to the <u>contributions</u> share of the global sea level trend (Church and White, 2011b; WCRP, 2018). At Tromso a <u>local</u> negative halosteric trend (more saline water) is lowering ASL_r . However, ASL_r $A\dot{S}L_r$, while for the area around Tromso (50-200 km)yields a better agreement, $A\dot{S}L_r$ agrees well with the observed ASL_{TG} and $ASL_AAS\dot{L}_{TG}$ and $A\dot{S}L_A$.
- The Siberian coast has multiple river outlets that contributes with significant freshwater of the Arctic Ocean (Proshutinsky et al., 2004; Morison et al., 2012; Armitage et al., 2016). A positive halosteric sea level trend is visible at the coast of the Bering and Kara Sea (figure 4), where the river OB has a major outflow. At Amderma TG, which is located on the coast between the Barents and Kara Sea, but not near any major outflow, a significant halosteric trend is an apparent large halosteric sea level fall is also recognized by the TG-measured sea level, despite rather large uncertaintieserrorbars due to lack of in situ data (figure 4). Ice loss from Novaya Zemlya contributes with over 1 gigaton of freshwater to the Kara Sea every year and the ice loss has been accelerating (Melkonian et al., 2016), but the contribution is small compared to the +500 Gt coming from the rivers every year. The halosteric signal could (falsely) be extrapolated from the gulf of Ob which has major river outlets and the agreement



Figure 8. Components of sea level trend $[mm y^{-1}]$ for each tide gauge from 1995-2015. The three bars in the middle ($ASL_{T}A\dot{S}L_{T}$, ASL_{A} $A\dot{S}L_{A}$ and $ASL_{TG}\dot{A}\dot{S}L_{TG}$) are the three independent estimates of absolute sea level. The error bars indicate one standard error (combined error from each component when relevant) <u>equivalent to the 68% confidence level</u>. The VLM component 'Local (GNSS-VLM)' is only relevant at Reykjavik and Ny Ålesund, because significant local properties causes VLM that is not present in the VLM-model (Ludwigsen et al., 2020b). Glacier component of VLM includes the effect of rotational feedback, ocean loading, and Antarctica which are is less than 0.5 mm y⁻¹ combined.

	$\dot{\mathrm{RSL}}_{TG}$	VLM (model/GNSS)	$\dot{\mathrm{ASL}}_{TG}$	IB	\dot{N}	М	$\dot{\eta}$	$\dot{\mathrm{ASL}}_r$	$\dot{\mathrm{ASL}}_A$
NOME	2.0 ± 1.4	-1.1 ± 0.9	$\textbf{0.9} \pm \textbf{1.7}$	0.1	1.1 ± 0.4	1.2 ± 0.4	1.7 ± 3.0	$\textbf{2.8} \pm \textbf{3.0}$	$\textbf{0.2} \pm \textbf{2.8}$
PRUDHOE BAY	1.7 ± 0.8	-1.4 ± 1.3	$\textbf{0.4} \pm \textbf{1.5}$	0.4	1.0 ± 0.5	1.4 ± 0.5	5.7 ± 3.2	$\textbf{7.1} \pm \textbf{3.2}$	$\textbf{1.1} \pm \textbf{3.0}$
REYKJAVIK	3.8 ± 0.5	0.0 ± 0.3	$\textbf{3.8} \pm \textbf{0.6}$	1.0	0.3 ± 0.7	1.3 ± 0.7	$\textbf{-0.4}\pm0.8$	$\textbf{0.9} \pm \textbf{1.0}$	$\textbf{2.3} \pm \textbf{1.6}$
RORVIK	$\textbf{-0.7}\pm0.7$	4.3 ± 1.8	$\textbf{3.6} \pm \textbf{1.9}$	0.3	1.3 ± 0.4	1.5 ± 0.4	2.0 ± 1.9	$\textbf{3.5} \pm \textbf{1.9}$	$\textbf{2.4} \pm \textbf{1.4}$
NY-ALESUND	$\textbf{-7.4}\pm0.5$	8.0 ± 0.5	$\textbf{0.5} \pm \textbf{0.7}$	0.6	0.1 ± 1.4	0.7 ± 1.4	$\textbf{-2.0}\pm0.6$	$\textbf{-1.3}\pm\textbf{1.5}$	$\textbf{1.1} \pm \textbf{0.8}$
TROMSO	$\textbf{-0.1}\pm0.6$	2.3 ± 1.7	$\textbf{2.2} \pm \textbf{1.8}$	0.1	1.1 ± 0.5	1.3 ± 0.5	$\textbf{-0.1} \pm 1.0$	$\textbf{1.2} \pm \textbf{1.0}$	$\textbf{2.2} \pm \textbf{1.1}$
VARDO	$\textbf{-0.0}\pm0.7$	2.5 ± 1.4	$\textbf{2.5} \pm \textbf{1.5}$	-0.1	1.2 ± 0.5	1.1 ± 0.5	0.6 ± 1.2	$\textbf{1.7} \pm \textbf{1.2}$	$\textbf{4.1} \pm \textbf{1.1}$
AMDERMA	4.9 ± 0.8	0.2 ± 1.1	$\textbf{5.1} \pm \textbf{1.3}$	-0.1	1.1 ± 0.4	1.0 ± 0.4	3.9 ± 3.5	$\textbf{4.9} \pm \textbf{3.5}$	$\textbf{-0.8} \pm \textbf{2.6}$
IZVESTIA TSIK	2.7 ± 0.9	2.3 ± 1.5	$\textbf{5.0} \pm \textbf{1.7}$	0.2	1.1 ± 0.6	1.3 ± 0.6	$\textbf{-5.2}\pm2.1$	$\textbf{-3.9}\pm\textbf{2.1}$	$\textbf{1.0} \pm \textbf{3.2}$
GOLOMIANYI	0.0 ± 0.9	2.8 ± 2.3	$\textbf{2.8} \pm \textbf{2.5}$	0.6	0.9 ± 0.9	1.5 ± 0.9	$\textbf{-5.4} \pm \textbf{2.5}$	$\textbf{-3.9}\pm\textbf{2.6}$	$\textbf{-0.7} \pm \textbf{3.4}$
KOTELNYI	7.7 ± 1.3	-1.1 ± 0.8	$\textbf{6.5} \pm \textbf{1.5}$	0.2	1.1 ± 0.4	1.4 ± 0.4	$\textbf{-7.5}\pm3.8$	-6.1 \pm 3.8	-0.8 \pm 3.3
KIGILIAH	1.7 ± 1.0	-0.9 ± 0.7	$\textbf{0.8} \pm \textbf{1.3}$	-0.1	1.2 ± 0.4	1.0 ± 0.4	-7.9 ± 3.8	$\textbf{-6.8} \pm \textbf{3.8}$	-1.6 ± 3.0

Table 1. 1995-2015 sea level trends $[mm y^{-1}]$ at the 12 tide gauge locations. The trends (least-squares) are generally based on a annual mean-value of a 50 km radius around the tide gauge. For VLM a 5 km radius is used, except for Ny-Alesund and Reykjavik where VLM is based on GNSS-measurements. The columns in bold indicate the three estimates of Absolute <u>Sea Level sea level</u> ($A\dot{S}L_{TG}$, $A\dot{S}L_r$ and $A\dot{S}L_A$). Errors indicate the 1 standard error equivalent to the 68% confidence level.

with ASL_{TG} ASL_{TG} is accidental. So the reason for this The halosteric sea level rise at Anderma is remains unclear. In any ease, both ASL_{TG} and ASL_r is in opposition to altimetry observations that remains doubtful, since ASL_A shows a negative ASL-trend in opposition to ASL_{TG} and ASL_r .

- ³⁸⁰ Further east along the Siberian coast the four TGs The four TGs along the eastern Siberian coast (Izvestia Tsik, Golomianyi, Kotelnyi, Kigiliah) all show a rising ASLobserve a rising sea levels, while both $ASL_A ASL_A$ and in particular $ASL_r ASL_r$ shows a negative trend in the region. Even though the ECCO OBP is 1-2 mm y⁻¹ higher than the manometric estimate (figure 5) it is not enough to explain the discrepancy between ASL_{TG} and ASL_r but explains some of the ASL_A Missing data in the end of the timeseries of Golomianyi (figure 2) might significantly alter the observed trend. From 2005-2010, Golomanyi showed a
- sea level fall, while few high measurements in 2012 and 2014 skews the trend upwards. Also the TG Izvestika Tsik observed a decreasing sea level from 2006/ ASL_r difference. Figure 4 shows that a negative halosteric sea level 7-2013, but an apparent steep sea level increase from 2013-2015 changes the trend is dominating the reconstructed sea level trend in the region, but the poor hydrographic coverage along the Siberian coast (Ludwigsen and Andersen, 2020) makes the uncertainty of the halosteric trend large. This negative steric sea level trend is however supported by the results of Armitage and Davidson (2014) from
- 390 combining GRACE with altimetry. They estimate a steric sea level in the Siberian Arctic (excluding the Barents Sea)in the order of -5 to positive.

Non-seasonal variations in sea level in eastern Siberian seas are dominated by large scale wind patterns controlled by the AO (Volkov and Landerer, 2013; Peralta-Ferriz et al., 2014; Armitage et al., 2018), which has a significant sea level impact in the region. These wind-driven sea level effects are largely manometric, but a not included in the manometric estimate (\dot{M}), while

395 the wind-driven sea level effects are part of ECCO OBP, which is 1-2 mm y⁻¹ from 2003 to 2014, which is same order of the estimated steric trend of this study in the region higher than \dot{M} in the area (figure 5). This is however not enough to explain the discrepancy between $A\dot{S}L_{TG}$ and $A\dot{S}L_{T}$ (but can explain some of the $A\dot{S}L_{A}/A\dot{S}L_{T}$ difference).

The positive ASL trend among tide gauges in the eastern Russian Arctic is however consistent and has been recognized in consistent with the results of other studies using an extended set of Russian tide gauges (Proshutinsky et al., 2004; Henry

- 400 et al., 2012). Remarkablyis that, the TG-trend at Kotelnyi and Kigiliah differ with almost 6 mm y⁻¹ (in total 12 cm difference over the time span of this study) despite being less than 250 km apart. This gradient is only reasonable, if local circumstances that affects the RSL is considered. Local coastal subsidence not associated with land ice loss/gain, i. e. From the timeseries in figure 2 a 30 cm RSL rise from 2002 to 2008 at Kotelnyi is visible. This significant change is however not observed by any altimeter product. A reasonable explanation can be local coastal subsidence caused by thawing of permafrost or oil depletion,
- 405 is a possible explanation. which also could explain the mentioned sea level 'jumps' of Golomanyi and Izvestika Tsik. This is however speculative, since it is not confirmed by any literature. In general, the poorest agreement is found at the Siberian TGs, which is similar to Armitage et al. (2016) who found that these tide gauge correlated the least with the altimetric observations.

Nome and Prudhoe Bay in Alaska both show a positive steric trend TG-trend which is not reflected in sea level trends from altimetry or the tide gauge $A\dot{S}L_{TG}$ or $A\dot{S}L_A$, thus resulting in a rather large discrepancy between ASL_r and $ASL_{A/TG}A\dot{S}L_T$

410 and ASL_{ACTG}. The strong halosteric trend of the Beaufort Gyre, might be extrapolated towards the Alaskan coastline and into the Bering Strait in the DTU steric model. There is no evidence in the literature for a an extent of the Beaufort Gyre Sea doming as shown from the halosteric trend, which indicates, that the weighted spatial interpolation in combination with higher hydrographic data density in the Beaufort Sea creates this widening of the Beaufort Gyre.

Ny-Ålesund on Svalbard is dominated by a large VLM caused by recent deglaciation. This uplift completely mitigates the
large sea level fall measured by the tide gauge and results in small rise of ASL_{TG}ASL_{TG}. In (Ludwigsen et al., 2020a) it is argued that the discrepancy between GNSS and the VLM-model in large originates from VLM because of post-LIA deglaciation on Svalbard (Rajner, 2018). This viscoelastic GIA-like LIA-effect will certainly also have a gravitational sea level fingerprint (*N*) that should be added to the manometric sea level change SLTs M. This can explain some of the difference between ASL_T and ASL_{A/TG}ASL_T and ASL_{A/TG}. A possibly positive dynamic M-change (from the (ECCO OBP)–M difference in figure 5h) could
further close the ASL_T – ASL_{A/TG} gap-gap between ASL_T and ASL_{A/TG}.

From the calculations of the gravitational fingerprint, none of the TG-sites in this study experience a net sea level fall from contemporary deglaciation and GIA (\dot{N} in table 1) and only Ny-Ålesund (-0.4 mm y⁻¹) and Reykjavik (-0.2 mm y⁻¹) will experience a small sea level fall from contemporary deglaciation alone. So even though the Arctic is heavily prone to ice mass loss and thus a smaller weakened gravitational pull, the Arctic as a region is not experiencing a-an absolute sea level fall

from comtemporary deglaciation. On the contrary, it causes the sea level to rise with around 1 mm y^{-1} in most of the Arctic. However, by accounting for the deglaciation effect on VLM, the RSL-change from contemporary deglaciation will be negative in large contribute to an RSL-fall in most areas of the Arctic.



Figure 9. Standard error ($\frac{1 \sigma 68\%}{N}$ confidence interval) of the 1995-2015 trend [mm y⁻¹] for combined steric, combined \dot{N} , $\frac{ASL_{A/TO}}{ASL_{A/TO}}$ and combined VLM contributions.

5 Uncertainty and assessment of ASL-trendsthe contributions

The uncertainties of the trend estimates for RSL_{TG}, VLM, gravitational fingerprint (*N*), steric (η) in table 1 and figure 8 are 430 derived as the standard error (σ) of the detrended and deseasoned timeseries of the annual mean valuescontributions. GIA (Caron et al., 2018) and altimetry (Rose et al., 2019) has a associated uncertainty that is used. In the case of VLM For the VLM-model a 10% error is added to account for uncertainties of the earth model (Wang et al., 2012).

The spatial distribution of the uncertainties are shown in figure 9. Generally, the largest uncertainties are found along the Siberian coastand in the interior of the Arctic where the largest sea level trend is present. The steric uncertainty is in most

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cases the largest source of uncertainty (figure 8). The standard error naturally reflects if the steric heights are unstable and poorly constrained (if for example there are few hydro-graphic data (figure 3)). In principle, this method requires temporal

independence, which is not entirely true, since outliers are replaced with data from adjacent years. Furthermore, large influence by the non-periodic and non-linear Arctic Oscillation, would enhance the uncertainty, even though this is a real physical signal. Thereby is the estimated error a composite of uncertainties originating from the way the sea level component is constructed and from , the sometimes large, interannual variability.

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The mass contribution and VLM has naturally the largest uncertainties close to glaciated areas. Glacial ice loss on Baffin Island is poorly constrained in the ice model, which is reflected with large uncertainties in this area. The uncertainty of altimetry is reflecting the data availability of areas with sea ice contrary the ice-free ocean, while the largest uncertainties of the TGs are those with largest interannual variability.

- Left map of figure 7 shows the difference between ASL_r and $ASL_{A/TG}$. The pattern resembles the trend of the halosteric contribution, which reflects the halosteric dominance of the spatial variability. The correlation coefficient (R) between ASL_r and ASL_A is R=0.50 (R=0.23 without the halosteric contribution) and R=0.53 when using the ECCO OBP estimate instead of the reconstructed manometric sea level. The correlation is better than the correlation coefficients reached by (Ludwigsen and Andersen, 202 , where they used different datasets of GRACE combined with the same steric and altimetric datasets from 2003-2015 (R=0.19-0.40).
- 450 From the middle panel in figure 7 we see that for most of the Aretic (78%) and for 8 of 12 TGs, the absolute difference is less than half of the combined standard error and in 98% of the area, is ASL_r in agreement with ASL_A within the associated uncertainty, which indicates that the error is a conservative estimate. Only the TG Izvestia Tsik shows a larger difference between observed (ASL_{TG}) and reconstructed sea level (ASL_r) than the associated standard error.
- Left map shows the difference between ASL_r and $ASL_{A/TG}$. Middle map is the absolute difference divided by the standard 455 error from 9 (combined uncertainty). Right panel shows a correlation matrix between ASL_r and $ASL_{A/TG}$. The color indicates the number of data grid cells falling into bin size of 0.5 mm y⁻¹. 96% of the grid cells with data is covered within the bounds of the matrix (N_{total}=18150). The red line is where ASL_r is equal to $ASL_{A/TG}$.

The right panel of figure 7 shows the correlation matrix between observed ASL (ASL_{A/TG}) and reconstructed ASL (ASL_r). The matrix shows that ASL_r and ASL_A are largely correlated. There is large accumulation around 2 mm y⁻¹, with slightly

460 higher ASL_A than ASL_r. This originates from the underestimate of the ASL-reconstruction (see figure 7) in the Norwegian Sea and the difference agrees with the ECCO OBP-M difference (figure 5h) and thus likely explained by the missing dynamic sea level contribution of M. Evident are also the large positive ASL_r-trends from the Beaufort Sea and negative ASL_r-trends along the Siberian Coast that is not reflected in ASL_A.

6 Conclusion

465 All significant contributions to the sea level change from 1995-2015 in the Arctic Ocean were mapped and assessed at 12 tide gauges located throughout the Arctic Ocean. This was done for the first time without the use of GRACE data or modeled steric data. Thereby are we Here we are able to reconstruct the Arctic absolute sea level change and attribute the changes to their origin and thus understand the causes behind the altimetry and TG-observed sea level trend. By using a VLM-model, that

includes both GIA and elastic uplift, the TG-observed sea level can be utilized in locations where no reliable GNSS-data is

470 present.

From figure 6 we clearly see Figure 6 shows that the general spatial pattern of altimetry observed sea level (ASL_Atrend (\dot{ASL}_A) is restored in the reconstructed ASL-estimate (ASL_r from the reconstructed trend-estimate (\dot{ASL}_r). The correlation (R=0.50) outperforms GRACE-based sea level budget assessments from (Ludwigsen and Andersen, 2020)-2003-2015 (R=0.19-0.40) - Figure 8 and 9 show that (Ludwigsen and Andersen, 2020). Hence is the calculated manometric contribution

- 475 an alternative to GRACE that should be considered for studying long-term past and future Arctic sea level change. Figure 7 shows the residual between observed sea level (ASL_{A/TG}) and the reconstructed ASL estimate within the combined uncertainty. The reconstructed ASL-trend agrees with altimetry at 60% of the area within the 68% confidence level (95% of the area within the 95% confidence level). The residual map indicate an improvement over previous studies (Carret et al., 2017; Raj et al., 2020) , however this assessment is only qualitatively since different subsets of periods are used. The two major residuals between
- 480 altimetry and the reconstructed product are found in the Beaufort Sea and East Siberian Sea. In both regions, the altimetry estimate by Armitage et al. (2016) has a better agreement than the used DTU/TUM-altimetry product. A dominant halosteric trend larger than the altimetric trend is also observed by Carret et al. (2017) and Raj et al. (2020).

The sea level trend at 5 (9) of the 12 TGs corrected for VLM agree with the reconstruction, while 8 of 12 TGs agree with altimetry. The relatively poor correlation at TG's, can be attributed to few T/S-data to constrain steric sea level dominates the

485 spatial variability. This is also the long at the coast of the Beaufort Sea and in the Siberian Arctic and possible local unknown VLM-effects.

From 8 and 9 it is evident that the steric estimate is the main source of uncertainty, while. The manometric sea level change has a more uniform and smaller contribution to ASL with smaller associated uncertainties compared to the steric component. Some areas, in particular, the Norwegian Sea, has more observations (from both altimetry and hydrographic data) and thus

- 490 ean are the individual contributions be estimated with lower uncertainty. The Siberian Seas are however poorly constrained with observations and both the steric product, altimetry and tide gauges show large uncertainties. Figure 7 shows the spatial agreement between observed sea level (ASL_{A/TG}) and the reconstructed ASL estimate within the combined uncertainty. The reconstructed ASL-estimate agrees with altimetry in 98% of the area and 11 of the 12 TGs within the uncertainty.
- The correlation between the reconstructed sea level and altimetry is significant (R=0.50), but also shows that the sea level budget is not closed or completely understood everywhere in the Arctic – likely because of poorly constrained steric data a uncertain dynamic contribution that is difficult to reconstruct. However, the reconstructed sea level confirms the negative halosteric-driven sea level trend along the east Siberian coast identified by (Armitage and Davidson, 2014), which is in contrast to the TG-observed sea level in the region. Large variations among TGs in East Siberia indicate very local VLM affecting the TG-observed RSL.
- 500 From figure 7 we see that the uncertainties in most of the Arcticare significantly larger than the difference between the reconstructed sea level and altimetry. This is including most of the Siberian Seas, indicating that the uncertainty of the components of this study of the sea level trend might be a conservative estimate. Better constrained estimates of both the manometric and steric sea level are necessary to get a complete understanding of what changes Arctic sea level and to validate

sea level trends observed by altimetry, which are not necessarily more accurate than the derived ASL-estimates The Arctic sea

- 505 level reconstruction can be improved by constraining the steric estimate further. Eventually integrating sea surface temperature and salinity from satellite observations could improve the estimates in areas with few in-situ data. Furthermore an independent estimate of the dynamic contribution to manometric sea level change is needed to include the significant wind-driven sea level changes in the Arctic. A complete recovery of the manometric sea level change can be used to validate future releases of GRACE-estimates that soon spans +20 years of observations.
- 510 *Code and data availability.* Tide gauge sea level timeseries is available at psmsl.org, the VLM-model available at data.dtu.dk/articles/dataset/ Arctic_Vertical_Land_Motion_5x5_km, DTU Steric is available at ftp.space.dtu.dk/pub/DTU19/STERIC/, the REAR-software is available at github at github.com/danielemelini/rear.git.

Author contributions. CAL: Method, concept, data analysis and writing. OBA: Concept and editing. SKR: Providing altimetry data, validation and editing.

515 Competing interests. The authors declare no competing interests.

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Acknowledgements. The authors want to thank two_three anonymous reviewers for their comments that greatly improved the manuscript. Furthermore, we thank Lambert Caron for providing the Caron2018 GIA-model, available at https://vesl.jpl.nasa.gov/solid-earth/gia/ and Danielle Melini for creating the REAR-code (Melini et al., 2015). This research was funded by the EU-INTAROS project (Grant agreement no. 727890) (CAL and OBA) and by the ESA-Climate Change Initiative Sea sea level budget closure (Expro RFP/3-14679/16/INB) (OBA and SKR).

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