Response to Ocean Science Discussion:
https://doi.org/10.5194/os-2020-112-RC1, 2021
Authors reply in bold.

General Comments:

This paper makes a good contribution to the field of seismic oceanography and presents interesting and useful analyses of 3D seismic data. The writing and figures are of a high quality. Thank you for acknowledging our contribution and the quality of our paper.

I recommend Major Revisions as I have a number of comments. Most of my comments can be easily addressed. However, I do feel that this paper could benefit from a change of focus. Please see my comment below: Thank you for providing valuable suggestions to us. We have implemented your comments and revised the manuscript.

The paper is written in such a way that it is not immediately clear what the benefit is to an oceanographer. As you know, seismic oceanography is simply a tool that we can use to learn about the ocean. So, I think this paper could benefit from some redirection toward the oceanographic aspects of its findings. We have enhanced the oceanographic aspects of the findings in the revision (throughout Sections 2, 3, and 4). In particular: - In the Introduction, there is little description of the oceanographic setting. What is it and what do you expect to see/resolve with seismic oceanography? Adding a paragraph along these lines would help place your findings in context later on. We have revised the introduction to clarify our goal and expectation (Lines 54-59). - In Section 3, you describe some seismic images in different orientations (i.e. inline, crossline, depth slices). Are the observations you describe typical across the survey? There are no typical observations, as our seismic inline images may look very diverse as they are from different periods of time. Our choice of images has been clarified (e.g., Lines 171, 182, 194-195). If so, can you comment further on what oceanographic implications these images have. We have commented on the oceanographic implications in the revised manuscript (e.g., Lines 178-181, 183-186, 193, 200-204, 349-362). For example, are the discontinuities in the crossline direction caused by heave of water masses? Yes, the heaving can cause discontinuities in our crossline images (Lines 183-184). What sort of mixing processes could cause the degradation in Figure 5. The possible mixing processes are discussed in Lines 348-361. Section 3 is presented as a way to guide the reader through the meaning of the images, but I think you could present them as some results (particularly if the images in Figs 5-7 are representative). We now present Section 3 as some oceanographic results, but we are very conservative here to avoid giving arbitrary interpretations.

Please see some related suggestions in ‘Specific Comments’. - The discussion is dominated by seismic acquisition and processing thoughts. However, you could
make some interesting discussion points about the oceanography related to Section 3 and 4. **We add some discussion about the oceanography throughout Section 3 and 4.** The authors may have a future paper that will address some of these points, and I understand that it is difficult to conclusively interpret seismic data without concurrent hydrographic information. Nevertheless, I think that the paper would be more impactful and have a wider scope if the authors address this general comment. **Thank you for understanding the difficulty of interpreting seismic data.** Yes, we are writing a paper on internal wave variations in this region, with in-depth spectral analysis of seismic images and estimation of diapycnal diffusivity, combining satellite sea surface height and geostrophic currents. This is too much to include and beyond the scope of this paper, which is to explore fundamental features of oceanic 3D seismic volume. However, we respect your comments, and add discussion of ocean dynamics in Lines 348-361.

Specific Comments:

Introduction: - In the Introduction, I think you should set up the expectation for this paper more clearly. For example, something like Line 331 would be useful at the end of the Introduction. **We have revised the end of the introduction to clarify the expectation (Line 54-67).** - You (correctly) mention a few times that 3D seismic oceanography is not well-developed. However, I think it would be fair to devote a few sentences to the seismic oceanography studies that have used 3D data, and to what end, in the Introduction (I see they are signposted in the Discussion). As far as I am aware, these 3D studies are: (i) Gunn et al., (2020) who showed the evolution of a front, (ii) Dickinson et al., (2020) who explored the passage of an eddy, and (iii) Blacic and Holbrook (2010). **We have briefly reviewed these 3D seismic oceanography studies in our revised manuscript (Lines 45-46, 52-53).**

3D Seismic Processing - Why does the velocity model have to be calibrated with the CTDs and in what way did you do this calibration? **The CTD casts were used to improve the RMS velocity model building since they are high-resolution data and are helpful for quality control of velocity model building.** In this sense, the CTD is used as guidance for the manual picking of the semblance panels. In my experience, the seismic derived sound speed models are poor when there is some unknown in the acquisition geometry (e.g. stretch in the streamer). Is that the case here? Another sentence to explain further would be useful. **Yes. We also excluded far-traces with offsets greater than 4000 m for processing/imaging to reduce the effect of long-offset deviations on the data preprocessing and velocity model building (added in Line 84-85).** - You do not mention deconvolution in this section. I suspect it was too computationally expensive to apply? **It would be good to describe what each reflection is in a bit more detail for those that are unfamiliar with seismic imagery (insert somewhere around Line 104). Then if you did/did not apply deconvolution becomes important for this description.**
We have excluded deconvolution from our preprocessing workflow since our initial deconvolution tests were not satisfactory and reliable (being too expensive was also a minor cause). We now explain seismic reflection for those that are unfamiliar with seismic imagery in Lines 113-114.

3D Seismic Volume - I understand your point about using the inline and crossline terms. However, can you add in a sentence about how the survey is orientated with regards to the oceanographic context. From the inset of Figure 1, the survey is a bit too far north of the Loop Current. Do you expect this section to have high eddy-kinetic energy or be quiescent? Perhaps it should be mentioned somewhere that you are in a continental slope setting. We have added the description of the oceanography context including the water dynamics in our seismic location (Line 68-72), and information regarding inline and crossline orientation (Line 117-118).

Understanding 3D Seismic Water Column Images. - The observations you describe in this section are interesting and warrant further discussion here. Can you explain these qualitative observations further and link them with your inferences in Section 4.2? We have added the explanation for the observations in Section 3 and further discuss them in the Discussion. o Paragraph 2: I think that your observations are very interesting. Can you speculate on what might be driving the mixing of the water column? Discussed in Lines 349-262. What are the typical processes in this area? Mentioned in Lines 350-352. o Paragraph 3: Again, this is very interesting. Can you expand on how you interpret these discontinuities? Heaving of the isotherms? Tides? Expended in Lines 183-186. Heaving can be more prevalent at different depths, so may explain why the discontinuities are not constant as a function of depth. The timescale of the deep ocean is generally longer than that of the surface ocean, causing discontinuities being less significant at deeper depths. Heaving is a possible cause here. Revised in Line 183-184. o Paragraph 4: Again, an interesting observation. Can you comment on what this suggests in terms of timescales? Commented in Lines 200-204.

Theoretical Analysis - This thought experiment is useful, however I am not sure what you are trying to get at given your empirical analysis in Section 4.2. You mention the high-frequency aliasing in Lines 261-262, but that is your only direct comparison between the two sections. Perhaps adding a few sentences to explain the purpose of this section in more detail, or removing it and expanding and improving upon Section 4.2? Our theoretical analysis is to use a simple (single-frequency) theoretical example to understand the temporal variation (now explained in Line 210), while our empirical analysis resolve the complex variations in our 3D seismic volume (now explained in Lines 247-248).

Empirical Analysis - Your cross-correlation analysis is very interesting; however the structure of this section is confusing and I think you need further explanation and
quantification in some places. **We revised this section based on your following comments (Lines 245-290).** o You define the terms 'inline variation' and 'crossline variation', but then do not use them very often. You could use them in some places in the main text which would make the writing sharper (e.g. Line 260). **We have moved the term definition to Line 216-217 and reused them throughout the section.** o After the equation, can you include the portion about 1D and 2D cross-correlation (i.e. Line 236-242). Following that, can you describe what these cross-correlations mean (i.e. Lines 230-235). Finally, discuss the results of Figure 9 and 10. **We have revised this section following your suggested structure (see Line 245-290).** o Having read this section a number of times, I am confused by why there is no temporal variation in 9a. Does the cross-correlation not compare multiple inlines that are separated by a few hours? **We have updated Fig. 9 by adding illustrations for how to derive inline and crossline variations and corresponding text (Line 252-254). There is no temporal variation in Fig. 9a/c because the inline variation compares multiple crossline sections. Temporal variation appears in Fig. 9b/d because crossline variation compares multiple inline sections that are separated by a few hours.** I think the description in Line 236-242 could be clarified by removing the use of alternating brackets to describe two things in the same sentence, e.g. ‘inline (crossline)..’, and by including some descriptive examples. **We have removed the brackets and revised this part (Line 253-254).** o What is the level of noise here? **The signal-to-noise ratio (SNR) of our seismic images is ranging from 8-10 (using the formula of Ruddick, 2013).** Are you sure some of the fluctuations in 9a are real? **We believe our results are correct.** What is a significant R value here? **There are no significant R values here. The correlation function measures the fluctuation.** Can you include an uncertainty and/or level of significance on Fig 9? **We cannot add uncertainty or significance analysis to Fig. 9 because the correlation function analysis is not statistics based. It only quantifies the fluctuation.** o Line 250-252: I’m not sure I follow this conclusion from Figure 9. I agree with you, but not based on Figure 9. **We have revised this part (Lines 288-289).** Furthermore, I think you should specify that the lack of temporal variation in the inline direction is specific to this region, as this conclusion will not be relevant everywhere (also specify at Line 264). **We have limited our conclusions to within our seismic volume (Line 279).** However, please kindly allow us to explain our thoughts. As far as we know, seismic vessels are often surveying with the velocity of 2-3 m/s, which is much faster than the movement of mesoscale ocean structures such as eddies, fronts, and internal waves. Therefore, there is not much temporal variation in the surveying line (i.e., inline direction). But in the crossline direction, there must be significant temporal variations because of the vessel special moving (e.g., zigzag) patterns. The bottom line is the temporal variation is always way more significant in the crossline direction compared to the inline direction. Thus, this is the case in any 3D marine seismic data, not just our data set. The reason there is little temporal variation in the inline direction here is because of the setting of the seismic survey with respect to the oceanographic context. **Agreed.**
Discussion - The discussion is coming from a seismic point of view, there is little
discussion of the oceanography. Please see my general comment. **We added a new paragraph to discuss the oceanography (Lines 348-361).**

Figures - Figure 1 is excellent. It might be useful to add the average time between
each inline on the figure, as you mention the temporal aspect several times in the
main text. However, this change is up to the authors. **Thank you for your suggestion. However, we kept Fig. 1 unchanged, because the time between inline is complicated (see Fig. 4).** Figure 2. In this figure, you have the vertical resolution as 5 m, but in the text you mention 6-7 m. Whichever it is, be consistent. **Revised as 6-7 m in Fig. 2 caption.** Figures 5-7: Interesting figures. Are they representative? Why did you choose them? If they are typical, you could replace ‘example’ with ‘representative’. **They are not always representative. We have explained our reason of choice in the corresponding text.** Figure 9-10: Can you add some indication of the uncertainty? **We are not able to add the uncertainty here because the correlation function analysis is neither a prediction, nor a measurement, and people usually do not give the uncertainty for the correlation function analysis.**

Technical Corrections:
Line 7: missing ‘the’ before ‘crossline direction’ **Corrected.**
Line 9: delete ‘allow to’. **Deleted.**
Line 29: not sure if ‘indeed’ is necessary. **Deleted.**
Line 30: change ‘primary’ to ‘and are primarily’ **Corrected.**
Line 31: the placing of the commas makes the sentence sound weird. How about
‘This new cross-discipline, between . . . . oceanography,. . . .’ or start a new sentence after ‘known as seismic oceanography’. **A comma added in front of the word “between”.**
Line 101: I am not familiar with the term ‘chair cut display’. Do you mean the display in Fig. 2? If so, please can you add a signpost to Fig. 2 at the end of this sentence. **Figure 2 is not shown in the chair-cut display. Sorry for the confusion. We have removed this term.**
Line 109: ‘water columns’ sounds a bit odd. What about ‘shows only the portion of the water column below 200 m’? **Revised.**
Line 112: please be more specific about the average hours between the inlines. **Revised.**
Line 115-116: Great sentence. **Thanks.**
Line 136: Do you need a new paragraph here? **Paragraphs combined.**
Line 138: You could delete ‘Again’ before ‘We emphasize’ **Deleted.**
Line 143: You could just cite Klaeschen, as you have already given the name of the assumption earlier. **Revised.**
Line 150: the ‘indeed’ chops up the sentence. I would delete. **Deleted.**
Line 151: missing ‘to’ after ‘We refer’. **Added.**
Thank you for all your valuable comments.
Temporal and spatial variations in three-dimensional seismic oceanography

Zheguang Zou\textsuperscript{1,2}, Parsa Bakhtiari Rad\textsuperscript{2}, Leonardo Macelloni\textsuperscript{3}, and Likun Zhang\textsuperscript{1,2}

\textsuperscript{1}Department of Physics and Astronomy, University of Mississippi, University, MS 38677
\textsuperscript{2}National Center for Physical Acoustics, University of Mississippi, 145 Hill Drive, University, MS 38677
\textsuperscript{3}Hydrographic Science Research Center, School of Ocean Science and Engineering, The University of Southern Mississippi, 1020 Balch Blvd., Stennis Space Center, MS 39529

Correspondence: Likun Zhang (zhang@olemiss.edu)

Abstract. Seismic oceanography is a new cross-discipline between geophysics and oceanography that uses seismic reflection data to image and study ocean water columns. Previous works on seismic oceanography were largely limited to two-dimensional seismic data and methods. In this work, we explore temporal and spatial variations embedded in three-dimensional (3D) seismic oceanography. From a 3D multichannel seismic survey acquired for oil and gas exploration in the Gulf of Mexico over six months period, a 3D oceanic seismic volume was derived. The 3D seismic images exhibit both temporal and spatial variations of the ocean, and theoretical and empirical analyses were used to determine their contribution. Results suggest that temporal variation is largely embedded in the crossline direction, showing discontinuities due to acquisition at varied times; however, inline sections, which can be seen as snapshot representation of the water column, capture not only thermohaline structures but also temporal variation of ocean dynamics. Our finding highlights that marine 3D seismic data can provide superior oceanic images for the investigation of time-evolving mesoscale ocean dynamics.

1 Introduction

Despite being the Earth’s largest habitat by volume, the ocean water column remains one of the most poorly explored environments. Even where investigations are executed, physical, biological, and chemical parameters are generally derived over one-dimensional (1D) profiles (e.g., CTD casts, buoys, and moorings) or two-dimensional (2D) transects (e.g., underwater gliders). Capturing the three-dimensional (3D) structure of the water column is extremely complicated: it can be reconstructed for a very large volume by combining 1D and 2D measurements, or, in a capacity limited to the surface water, it can be inferred from satellite observations. Also, mesoscale and small-scale thermohaline fine structures are very difficult to observe with conventional methods whose lateral resolutions are low (usually > 100 m). The ocean interior instead is 3D by nature and varies in both time and space on a wide range of scales, as ocean dynamics that affect thermohaline fine structures such as internal waves, solitons, tidal beams, eddies, and fronts are expected to vary both spatially and temporally.

Previous work has shown that marine seismic reflection profiling, a technique commonly used by geophysicists and geologists to image the Earth beneath the seafloor, can produce surprisingly detailed images of water-column structures. Holbrook et al. (2003) and Holbrook and Fer (2005) demonstrated that 2D seismic reflection sections, if appropriately processed, pro-
vided very high-resolution images of the ocean structure, both vertical and, in particular, horizontal. Within the ocean water column, water density variations, fine scale (1-10 m thickness) temperature-salinity contrasts, and water turbidity fluctuations result in small changes in sound speed that produce weak, but distinct, sound reflections. These reflections, 100 to 1000 times weaker than those from the solid earth below, have generally been neglected by geophysicists, whose focus is the structure of the sub-seafloor. However, studies reveal that these reflections correspond to ocean thermohaline structures (Nandi et al., 2004; Nakamura et al., 2006), and are primarily (not completely) associated with temperature gradient (Ruddick et al., 2009). This new cross-discipline, between exploration seismology and physical oceanography, has come to be known as seismic oceanography (Holbrook et al., 2003) and has been successfully applied to imaging mesoscale and sub-mesoscale water-column structures such as ocean fronts (Gorman et al., 2018), eddies (Song et al., 2009; Tang et al., 2014a), internal waves (Holbrook et al., 2009; Tang et al., 2014b; Buffett et al., 2017), and other thermohaline fine structures (Holbrook et al., 2003). Additionally, several theoretical studies have been derived from the application of water-column seismic images including estimation of geostrophic currents (Sheen et al., 2011; Tang et al., 2014b), wave field spectra (Fortin et al., 2016), and internal wave mixing (Dickinson et al., 2017). Most of these studies used 2D seismic data and processing methods, but, in the modern exploration seismology of the oil and gas industry, 2D seismic methods are gradually upgraded to 3D seismic methods, which provide more adequate seismic images with the help of the additional dimension, leading to a more reliable interpretation (Yilmaz, 2001).

3D seismic surveys are distinguished from 2D seismic surveys by the contemporary acquisition of multiple closely spaced lines (e.g., 25 m) that provides regular data point spacing. This leads to a true data volume from which lines, planes, slices, or probes can be extracted in any orientation, with nominally consistent data processing characteristics. While it is possible to acquire a dense, high-resolution grid of 2D lines, such grids are fundamentally different from a native 3D seismic survey (Lonergan and White, 1999; Yilmaz, 2001). The close line spacing of 3D seismic and the physical illumination of the subsurface from multiple offsets and multiple azimuths remove spatial aliasing problems inherent to 2D seismic data, therefore 3D seismic oceanography has the potential to yield better spatial resolution and can be useful for studying the orientation of ocean structures (Blacic and Holbrook, 2010). To date, 3D seismic oceanography is still not well developed, which can be due to multiple facts: the 3D seismic data are very expensive to acquire, there is an interdisciplinary gap between oceanography and geophysics, and most importantly, a fundamental understanding of the capability of 3D seismic oceanography is missing.

The fundamental principle of exploration seismology assumes prevalently only spatial and not temporal variations in the subsurface (at least in the survey time frame). However, this challenges the development of 3D seismic oceanography, as 3D seismic surveys are generally acquired over a long period (e.g., from hours to months) and the water column may evolve during the collection of 3D seismic data. Until very recently, 3D seismic oceanography moves a big step forward, successfully being applied to explore the evolution of a front (Gunn et al., 2020) and the passage of an eddy (Dickinson et al., 2020). However, these are still many fundamental questions regarding 3D seismic oceanography await to be answered. For example, how do temporal and spatial water-column variations distribute in a single 3D seismic volume? Can we quantify them? Is the oceanic 3D seismic imaging meaningful in all directions? The answers to these questions will be useful to guide the development of future 3D seismic oceanography.
In this study, we explore temporal and spatial variations embedded in 3D ocean seismic volume and answer the fundamental questions mentioned above. We report results of a 3D seismic oceanography study carried out at the continental slope region of the northern Gulf of Mexico, where seismic imaging of ocean structures can be useful for understanding ocean dynamics and mixing. We analyzed multi-directional (inline, crossline, and depth-slice) seismic images to reveal fundamental imaging features. We further conducted theoretical and empirical analyses to understand the distribution of temporal and spatial variations. This new understanding will be useful for the interpretation of 3D seismic data as spatio-temporal evolution of ocean interior structure, which is important to promote the development of 3D seismic oceanography.
2 Data and Methods

2.1 3D Seismic Data

The seismic data used in this study are a portion of a large multichannel 3D seismic survey conducted by Schlumberger WesternGeco in the Northern Gulf of Mexico for oil and gas exploration between 2002 and 2003. Our study region (Fig. 1) is at the continental slope of the northern Gulf of Mexico, outside the Mississippi River delta, where the water dynamics in this region is mainly dominated by the Loop Currents and the Mississippi River outflows (Coleman, 1988; Sturges and Lugo-Fernandez, 2005). Although our seismic region is a bit far north of the Loop Currents, it is still a high eddy-kinetic energy region due to eddies and jets over the continental slope (Hamilton and Lee, 2005). Seismic surveying lines run from northwest to southeast (inline azimuth, 330°) over a gentle continental slope (average inclination, 1.5°) where the seabed depth ranging from 800 m to 1300 m. Seismic data were collected using 2 airguns of 5085 cubic inches each in flip-flop configuration and 8 streamers, each accommodating 640 hydrophones. The streamer spacing is 100 m, and the hydrophone spacing is 12.5 m. We received the raw shot gathers sampled at 2 milliseconds (ms) and cut at the seafloor with no processing applied apart from analog to digital anti-aliasing (frequency range, 3-200 Hz) filter. We received multiple CTD and XBT casts, including three CTD and two XBT casts fall inside the seismic area (see Fig. 1).

2.2 3D Seismic Data Processing

Imaging the ocean water column using 3D seismic data from the oil industry is challenging. Acquisition geometry is not optimized for this target, and ocean internal reflections are inherently weak and masked by noises of different nature. However, oil industry contractors employ cutting-edge technology and therefore the obtained seismic data are generally of very high quality. The seismic data processing was started with trace editing and amplitude balancing. We have removed offsets greater than 4 km (half of the total channel number) to keep computational costs low, and to reduce the effect of long-offset deviations on the data preprocessing and velocity model building. The strong seafloor reflections were also muted to achieve a relative balance of amplitude levels. The data preprocessing used here employed standard techniques for subsurface seismic imaging, described in Yilmaz (2001), adapted to work with the water-column specific issues. Typical marine noises were present in the water-column data, e.g., acquisition-related noise, direct arrivals, reflection energy returns from previous shots, etc. Environmental noises include wind, shipping activity, and inherent ocean noise. We designed a filtering strategy specifically tailored to remove or minimize as much noise as possible while preserving the weak signals of interest. Consequently, we used low-cut 5 Hz and high-cut 150 Hz Butterworth filtering after each processing flow in various data domains to attenuate noise. The direct waves overlapped the subtle internal reflections of the water column and complicated the imaging. We applied frequency-wavenumber (FK) filtering and Radon filtering in different data domains to fruitfully attenuate unwanted linear noise, previous shot multiples, and seafloor refraction.

We processed the 3D data in a 3D fashion (which uses both inline and crossline data), rather than sequential 2D processing. The spherical divergence was compensated using the conventional exponential gain function (with a power of 2) after some trials. For velocity analysis and normal move-out (NMO) correction, the data sort was changed to common-midpoint (CMP)
and the semblance panels were produced in a window of 1410 to 1590 m/s. To build a reliable velocity model, sound velocity derived from CTD measurements were used to calibrate the seismic velocity model when there is a big mismatch. **Afterward,** high coherence semblances were picked manually in a distance interval of every 250 m in both directions to model root-mean-square (RMS) velocities for further processing. Accordingly stacking and time migration were performed using the RMS velocities to produce interpretable seismic images. We have also tested and performed a powerful multi-parameter imaging technique known as the common-reflection-surface (CRS) method for stacking and enhancing the data and also to avoid the NMO stretch effect (Yilmaz, 2001). The size of the CRS stacking surface was however chosen conservatively small in particular in the crossline direction (50 m) to avoid stacking traces from different swaths. The CRS showed improved results compared to the conventional CMP-based imaging especially along the inline direction (Bakhtiari Rad and Macelloni, 2020). **Afterward,** post-stack time migration was performed using the estimated RMS velocities to correct the dipping events. Finally, the data were time-to-depth converted using the estimated velocity function integrated with in situ sound velocity casts. More details of our seismic processing can be found in Bakhtiari Rad and Macelloni (2020).
2.3 3D Seismic Volume

The obtained 3D seismic volume of the ocean interior is illustrated in Fig. 2, showing the “slicing” configuration of 3D inline, crossline, and depth-line seismic images. A 3D seismic volume is generally a 3D matrix in which seismic reflections are color-coded according to the reflection amplitude and polarity. Each seismic reflection in seismic images represents an “interface” between two water layers with different acoustic impedances, stemming from different temperature and salinity in the water column (Ruddick et al., 2009). Because a seismic survey can be acquired in any planar directions, the notation in geographic coordinates (i.e., latitude and longitude) is not adopted. Instead, the planar position is organized in inline (the direction along which the survey vessel tows the streamers; the northwest-southeast direction; along the continental slope) and crossline (perpendicular to inline; the northeast-southwest direction; along the contour); see Figs. 1 and 2. The volume has a spatial resolution of 6.25 m in the inline direction, 25 m in the crossline direction, and 6-7 m in the vertical direction (assuming a sound speed of 1500 m/s and considering the dominant frequency of the airgun signal in the water column between 50 and 60 Hz). Our seismic volume shows only the portion of the water column below 200 m because the geometry of sources and receivers, optimized for deep subsurface targets (several kilometers below the seafloor), poorly image the shallowest portion of the water column (Piété et al., 2013). It is important to note that for a 3D seismic oceanography study, inline sections are often acquired during short temporal intervals (typically a few hours considering the normal vessel velocity of 2.5 m/s).

However, crossline sections, which are obtained interpolating the inline sections perpendicularly, may embrace a wide temporal interval (from a few hours up to several months; the average interval is about 8 hours within the linear acquisition period). We assume that water-column reflectors do not move during the shot and the signal recording (the stick-slip model assumption (Klaeschen et al., 2009)). Considering our inline collection time (a few hours) is smaller than the timescale of the mesoscale ocean dynamics (days), we assume that each inline represents a seismic snapshot of the water column. The entire 3D seismic volume extends for 480 km$^3$ of the water column in the Gulf of Mexico. It consists of 821 inline sections, 3,463 crossline sections, and 256 depth slices. Temporally, it covers over six months, from August 2002 to February 2003, with most collected between September and October.

2.4 Imaging Capability Analysis

To test if the 3D volume properly images the water column structures, we compared the seismic reflections with acoustic reflection coefficient derived by inverting the temperature-salinity curves collected along with the CTD profiles (Nakamura et al., 2006). The acoustic reflection coefficient for normal incident sound waves is given by (Kinsler et al., 1999):

$$ R_s = \frac{\rho_1 c_1 - \rho_0 c_0}{\rho_1 c_1 + \rho_0 c_0} $$

(1)

where $\rho_0$, $\rho_1$ and $c_0$, $c_1$ are the density and sound speed of the medium with the subscript 0 and 1 specifies the layers. It has been widely demonstrated that the amplitude of seismic reflections is largely related to temperature gradients in the water column (Nandi et al., 2004; Nakamura et al., 2006; Ruddick et al., 2009), but sometimes salinity may play a role up to 40% in regions prone to diffusive convection (Sallarès et al., 2009). Figure 3 (a) compares the reflection coefficient derived from
Figure 3. (a) Comparison of seismic imaging (Inline 2130) and the derived reflection coefficient (curve) from CTD data, both acquired on October 17, 2002. (b) Correlation between temperature gradient and the derived reflection coefficient between 200-1000 m.

concurrent CTD measurements (collected on October 17, 2002, location shown in Fig. 1) with our seismic imaging (Inline #2130; seismic data collected on October 17, 2002). The overall agreement between the derived reflection coefficients with the seismic reflections suggests that our 3D seismic data successfully represents water-column thermohaline structures. Also, the derived coefficient reflection highly correlates ($R = 0.9970$) with the temperature gradient [Fig. 3 (b)], suggesting that the seismic amplitude in our seismic images can be interpreted as the vertical temperature gradient of the water column. In addition, the depth of the 3D volume seafloor reflection matches within 5-10 m error the seafloor depth from multibeam bathymetry which is derived using very high accurate sound speed measurements collected by NOAA’s Ship Okeanos Explorer, confirming that our migration is accurate and our seismic images accurately represent the water column structure.

2.5 Survey Line Analysis

Once we have established the oceanic natures of the seismic reflections, we resolve the correct relationship between time and space within our 3D seismic volume. We emphasize that inline sections are generally acquired during a short temporal interval (typically a few hours considering the normal vessel velocity of 2.5 m/s), while crossline sections, which are obtained by interpolating the inline sections perpendicularly, embrace a wide temporal interval, in our case up to several months. It has been demonstrated that water-column reflectors do not move during the very short time between the shot and the recording of the reflected signal (Klaeschen et al., 2009). In 3D surveys each shot is recorded simultaneously along with parallel streamers, generally referred to as swaths, which for our data set count 8 streamers. To better understand the temporal distribution of the inline/swath, we carefully investigate the acquisition time for each survey line by referring to the field acquisition records.
Figure 4. Dates of the seismic survey for the survey lines analyzed in our work. Two highlighted periods are a linear acquisition period (Lines #1900-2130) during which data were collected linearly in time and space intervals, and a contrast acquisition period (Lines #2280-2540) which can display a huge time jump in seismic image. The line number here is equivalent to the inline number at the center of a seismic swath.

Figure 4 shows the seismic line number, which is equivalent to the center inline number of a seismic swath, as a function of the recording date and time. Considering that 3D surveys are ideally carried out by acquiring adjacent swaths consecutively, we should observe a linear relationship between sailing line number and survey time. However, it is common that owing to operational problems (e.g., weather, maritime traffic, etc.) and/or bad data acquisition some portion of the area may be covered at a different time or some lines may be reacquired. Figure 4 shows a general linear trend, in particular for the portion including Lines 1900-2130. In this interval, spatially contiguous seismic lines were collected consecutively in time. We refer to this portion as linear acquisition period and we will use it in the correlation analysis discussed further.

3 Results

3.1 3D Oceanic Seismic Images

In this section, we present multi-directional images excerpted from our 3D seismic volume to improve the understanding of water-column 3D seismic images and the fundamentals of 3D seismic oceanography, and hopefully, shed a light on possible ocean dynamics that can be resolved from our seismic images.

Figure 5 shows three inline seismic images, each representing a snapshot along inline transect in the linear acquisition period. We observe layers of strong seismic reflection in Fig. 5(a), moderate reflection in Fig. 5(b), and weak reflection in Fig. 5(c), respectively, indicating vertical temperature gradients of the water column (see Sec. 2.4). Considering the spatial (2.5 km) and
temporal (about 4 days) separations in these images, we observe that the water-column structures varied, not only spatially (over 5 km), but more importantly, temporally (over 8 days), suggesting a strong water-column mixing process may have occurred in this region. In other words, during the interval between October 20-28, 2002, over this portion (about 4 km) of the continental slope, the strong and thick thermoclines gradually weakened and thinned, and eventually almost disappeared. We interpret the water-column variation as complex and diverse internal wave variation over the continental slope of the northern Gulf of Mexico, caused by a time-varying mesoscale oceanographic process (length $> 10$ km, depth $> 800$ m, time $> 10$ days) which transformed the water column from highly stratified to well-mixed. The possible mesoscale processes that causing this transformation will be further discussed in Sec. 4.

Figure 6 shows one of the widest crossline seismic images in our seismic area. We observe significant discontinuities and a strong pattern of seismic swaths (e.g., vertical stripes). These discontinuities stem from abrupt changes of isopycnal depth (e.g., “heaving” of isopycnals) across seismic swaths, indicating that the occurrence of temporal variation in the water column. In this region, the ocean dynamics that may change isopycnal depths include eddies, internal waves, internal tides, and Mississippi River outflow. Swaths collected over the linear acquisition period (marked by the red line) display some continuity, while swaths collected with longer time shifts can yield significant discontinuities. For example, seismic imaging of the contrast acquisition period (marked by the blue line) looks drastically different from its neighboring parts due to a 20-day time shift (see Fig. 4).
Figure 6. (a) An example of a crossline image (Crossline # 18200). (b) and (c) are close-up views of the regions shown in (a) for two different depths. The dates to collect the data span from August 2002 to February 2003. The red line at top marks the linear acquisition period, while the blue line marks the contrast period.

We also notice that the discontinuity varies with depth. The discontinuity is more significant at 200-350 m [Fig. 6(b)] than at 600-750 m [Fig. 6(c)], suggesting that temporal variation is more significant at shallower depths. Another proof for the discontinuity indicating temporal variation is the continuous seafloor, suggesting no temporal variation. Our analysis suggests that temporal variation of the water column, appearing as imaging discontinuity, is significant along the crossline direction, which lowers the quality of crossline images, and may further hinder their interpretation.

Figure 7 shows depth-slice seismic images at three different depths (250, 500, and 750 m) to represent the shallow, middle, and deep layers of our seismic volume. Water-column seismic depth slices are the most complex representation to conceptualize since they offer a new view of the ocean interior. We observe little discontinuity along the inline direction, suggesting that temporal variation is weak along the inline direction. However, we observe significant swath pattern and strong discontinuity appearing along the crossline direction, and the discontinuity decreases from shallow to deep layers. This decreased discontinuity agrees with the fact that temporal variability of the top ocean is more significant than that of the deep ocean, as the ocean is mainly stirred from the top due to the wind-driven surface mixing (Talley et al., 2012). Due to the presence of temporal variation, interpreting seismic depth-slice images is extremely challenging, but we may get a hint on the timescale of the ocean dynamics in Fig. 7, based on the amount of discontinuities and our 3D seismic setup (e.g., time separation between...
nearby seismic swaths). We suggest that in this region, the ocean dynamics have a timescale less than 8 hours at the depth of 250 m, but way longer than 8 hours at 750 m. The analysis of depth-slice images suggests that in our seismic volume, temporal variation of the water column is non-negligible in the crossline direction but negligible in the inline direction.

Our analysis of 3D seismic images reveals that temporal and spatial variations are both embedded in the seismic volume, and temporal variation is mostly along the crossline direction. Next, we will conduct analyses to quantitatively assess temporal and spatial variations within a 3D ocean seismic volume.

3.2 Theoretical Analysis

Here is a simple theoretical example to help us understand why temporal variation appears differently in inline and crossline directions. Let us assume a water column in which temporal variation occurs at one cycle per day (1 cpd, about $10^{-5}$ Hz) and spatial variation at one cycle per kilometer ($10^{-3}$ cpm). The values here are arbitrary but can represent mesoscale oceanographic processes such as internal waves or internal tides (Talley et al., 2012) for which seismic imaging is particularly useful. We use single-frequency variations here for easy illustration purposes, while more complex variations can be viewed as the sum of multiple single-frequency variations. For simplification, we will refer to the total variation (sum of temporal and spatial variations) in the inline direction as inline variation, and the total variation in the crossline direction as crossline variation.

We assume that this water column is imaged with a common 3D seismic survey setup, having the same field geometry of our survey, and carried out swath-by-swath like the linear acquisition period. The vessel sails at a speed of 2 m/s, the seismic swath is 400 m wide, and the vessel can collect two swaths per day. Therefore, after accounting for the two-way travel time, surveying a 1-km inline section takes $10^3$ s (about 0.012 days, or 0.012 temporal cycle), and surveying a 1-km crossline section takes 2.5 days ($2.5$ temporal cycles, or $2.16 \times 10^5$ s).

Based on the above settings, the inline and crossline variations can be theoretically resolved [Fig. 8 (a) and (b)], summing temporal and spatial variations in inline and crossline directions, respectively. Results suggest that in the inline direction
Figure 8. Illustration of temporal (red), spatial (blue) and total (black) variations in inline and crossline directions for a simple water column. (a) inline variation; (b) crossline variation; (c) spectrum of inline variation; (d) spectrum of crossline variation. Note that the dash line in (c) marked the theoretical position of temporal variations, which may not be resolved due to collection time.

[Fig. 8 (a)], temporal variation is subtle, and the inline variation mostly follows spatial variation. In the crossline direction [Fig. 8 (b)], however, temporal variation is prominent, and the crossline variation is a fair combination of both temporal and spatial variations, with temporal variation being more noticeable. Furthermore, we find that this conclusion can be extended to temporal and spatial variations for all ocean dynamics. This theoretical analysis confirms that with common 3D seismic survey setups, temporal variation of mesoscale ocean dynamics is more significant in the crossline direction. In terms of seismic imaging, inline images mostly represent spatial variation of the water column, while the crossline images represent a combination of temporal and spatial variations of the water column.

Finally, the inline and crossline variations can be spectrally analyzed using Fourier transform, to reveal the distribution of temporal and spatial components in wavenumber domains [Figs. 8 (c) and (d)]. Here, we focused on wavenumber domains instead of frequency domains because seismic images are originally intended to resolve spatial variation rather than temporal variation. We found that the spatial component appears at the same location, e.g., at $10^{-3}$ cpm, in both directions, while the temporal component appears at two different locations, e.g., at about $10^{-5}$ cpm in the inline direction and $2.5 \times 10^{-3}$ cpm in the crossline direction. In other words, in inline images, temporal variation will appear as a low-frequency component, far apart (about two orders, 100 times) from the spatial component, while in crossline images, temporal variation appears as a high-frequency component, very close (about 2.5 times, still in the same order) to the spatial component. The dashed line in the inline spectrum [Fig. 8 (c)] illustrates the theoretical position of the temporal component, which be too weak to resolve when inline sections are too short (i.e., covering far less than one temporal cycle). These spectral analyses suggests that water-
column temporal variation will appear differently in inline and crossline images, posing strong high-frequency aliasing in the crossline imaging. Also, separating temporal and spatial variations in crossline imaging could be very challenging because they are spectrally close to each other.

### 3.3 Empirical Analysis

Our theoretical analysis provides an idea for quantitatively analyzing temporal and spatial variations based on inline and crossline variations. However, real 3D ocean seismic volumes are more complicated than single-frequency-variation examples. Here we developed a method to analyze temporal and spatial variations within our 3D seismic volume. The results will provide empirical values in our seismic volume, which can also be useful to other seismic oceanography studies with similar setups.

For a real 3D seismic volume, inline and crossline variations can be quantified with correlation, which measures the similarity between two variables or images. For 2D seismic images, \( x \) and \( y \), the correlation is defined as:

\[
r = \sum_{i,j} \frac{(x_{ij} - \bar{x})(y_{ij} - \bar{y})}{\sigma_x \sigma_y}
\]

where, \( i \) and \( j \) are the 2D index, \( \bar{x} \) and \( \bar{y} \) are the means, and \( \sigma_x \) and \( \sigma_y \) are standard deviations of \( x \) and \( y \). In practice, due to the perpendicular relationship between inline and crossline directions, the inline variation can be simply derived from correlation between crossline images [Fig. 9 (a)], while the crossline variation from correlation between inline images [Fig. 9 (b)].

We correlate the inline and crossline image series with corresponding reference images (IL #1900, or XL #18000), respectively. The results are plotted as the correlation functions, i.e., the correlation results as a function of inline or crossline number. The inline axis can further be converted to lateral distances (spatial domain), while the crossline axis can be converted to both lateral distances (spatial domain) and acquisition time (temporal domain). The correlation results are between -1 and 1, representing the fluctuation of image similarity with respect to the reference, with +1 being exactly similar, -1 exactly reversed, and 0 completely different. When the water-column structure varies, either temporally or spatially, the similarity between seismic images varies as well. Therefore, the change of the image similarity summarizes the variation of the water column.

The correlation results allow quantitative analysis of the variation of a particular image series or at a particular depth range. For example, we only use the linear period (see Fig. 4) for a more meaningful analysis. To best represent the variation of water column, we only use imaging of 250-750 m, excluding seafloors and low-quality shallow portion data. Furthermore, we divide the water column into two parts, the upper part (250-500 m) and the lower part (500-750 m), to explore the depth dependency. Besides, the correlation function allows the examination of the correlation length, which is defined as the length to the first zero crossing, measuring the length required for two images to be completely different. The shorter the correlation length is, the faster the signal de-correlated. Finally, for periodical signals, the spectra of the correlation function can be used to study the inherent cycles within the signal.

Figure 9 shows the results of inline and crossline variations derived from our 3D seismic volume. Here, inline variation [Fig. 9 (c)] is plotted as a function of space (i.e., lateral distance), while crossline variation [Fig. 9 (d)] is plotted as a function of space or time (based on the acquisition time). Overall, both inline and crossline variations quickly decrease from unity and then fluctuate around zero. The upper and lower water columns vary very differently, and the total variation of the whole
Figure 9. Inline and crossline variations from our seismic volume. Illustrations of (a) deriving inline variation from crossline image series, and (b) deriving crossline variation from inline image series. Results of (c) inline variation and (d) crossline variation. The red, blue and black curves are variations for the upper (200-600 m), lower (600-1000 m) and total (200-1000 m) water column, respectively. The crossline variation is calculated within the linear acquisition period (Inline 1900-2140, see Fig. 4), and the inline variation is limited to 6 km for easy comparison with the crossline.

water column is mostly dominated by the upper part. Comparing these two directions, three observations can be made: (a) the crossline variation is more severe than the inline variation; (b) the crossline variation has a shorter correlation length (about 0.4 km) than the inline variation (about 2.5 km); (c) the crossline variation has more high-frequency fluctuations than the inline variation. These observations can only be explained with the presence of temporal variation in crossline variation, leading to more and faster fluctuation and shorter correlation lengths, agreeing with our theoretical analysis [see Fig. 8 (a) and (b)]. Thus, our analysis confirms that in our 3D seismic volume, the inline variation [Fig. 9(c)] is mostly associated with spatial variation, while the crossline variation [Fig. 9(d)] is associated with both temporal and spatial variations.

Figure 10 further shows the inline and crossline spectra, calculated from the Fourier transform of the inline and crossline variations, respectively. Note that the inline is only associated with space, while the crossline is associated with both time and space. Overall, we observe a similar descending trend in both spectra, providing us information about the spatial features in wavenumber domains. Comparing these two spectra, one can see that many peaks seen in the crossline spectrum are absent.
Figure 10. Spectra of the inline and crossline variations. The spectrum for the crossline variation is associated with both x-axes (time and space), while that for the inline variation is only associated with the lower x-axis only (space). The semi-diurnal (M2) tidal cycle is also denoted.

in the inline spectrum. These peaks show the dominant frequencies of temporal variations. Particularly, we observe the semi-diurnal tidal cycle (marked as $M_2$ in Fig. 10) in the crossline spectrum, which is strong evidence that the crossline variation includes temporal variations, as continental marginal waters are often heavily influenced by tidal-forcing dynamics. A significant amount of high-frequency components seen in the crossline spectrum are temporal variation, agreeing with our theory [Fig. 8 (d)] which suggests that temporal variation appears as a high-frequency aliasing. Our spectral analysis, again, confirms that the crossline imaging captures temporal features of the ocean, while the inline imaging only captures the spatial features.

4 Discussion

The visual, theoretical, and data-driven analysis of the 3D seismic volume has provided a wealth of findings that we further discuss and summarize herein. Notice that this is a fairly new field, and we do not have a complete catalog of results and detailed concurrent oceanographic measurements that would allow unambiguous interpretation of the 3D seismic imaging in light of oceanographic processes.

Fundamentally, 3D seismic oceanography resolved from common 3D seismic survey setups will be intrinsically affected by temporal variations of ocean dynamics. Ideally it is possible to design a special 3D seismic survey that can perfectly image an oceanographic process without significant temporal variation. However, 3D seismic surveys are very expensive to collect and, in most of the case, we have to rely on data acquired for other purposes. 3D seismic surveys conducted for oil and gas exploration cover a very large volume of ocean water and have the right bandwidth to depict water column reflections. Those
surveys often are acquired over time spanning from days to months, and we must look for the oceanographic signals embedded in the seismic data and build the best processing and analysis workflow to extract it. Mesoscale and sub-mesoscale ocean dynamics (e.g., fronts, eddies, internal waves, turbulence, etc) hold a temporal variation of $10^{-6} - 10^2$ Hz and a spatial variation of $10^{-4} - 10^2$ cpm (Talley et al., 2012; Ruddick, 2018). As a result, wave spectra resulting from mismatched imaging inevitably produce a significant overlap of temporal variations on top of spatial variation. Temporal variation on 3D imaging may vary case by case, dataset by dataset, volume by volume.

In standard 3D seismic data processing for earth interior imaging, reflections within a large volume of subsurface are utilized and accounted for the out-of-plane acoustic scattering, to provide higher quality images than those resulting from 2D data. The general rule is to avoid summing inconsistent reflections from different seismic swaths. This is not always possible for the water column due to temporal variation. Narrow aperture 3D multiparametric stack (Bakhtiari Rad and Macelloni, 2020) or swath-by-swath common mid-point 3D stacking (Blacic and Holbrook, 2010) can both be used to create 3D seismic oceanographic images because both implement a time-dependent selection for the seismic data. However, the processing workflow for 3D seismic oceanography can be case-dependent, and we suggest always perform an in-depth temporal analysis to avoid summing time-inconsistent seismic data.

Generally, we found that:

Inline images are not affected by temporal variation (unless the inline is very long or is imaging fast-moving water-column structures (Klaeschen et al., 2009). Each inline can be seen as a snapshot of the water column vertical thermocline structure at a given time over a given location. This temporal and spatial heterogeneity cannot be fully separated because this temporal evolution occurs at different locations. However, available data analysis methods, e.g. wavefield spectral analysis (Holbrook et al., 2013) and diffusivity estimations (Fortin et al., 2017; Dickinson et al., 2017), developed for 2D seismic oceanography can be safely extended to 3D inline images. Most importantly, because an inline section “samples” the ocean at one given time and one given place, we could have a particular sequence of inline images that adequately image both the spatial and temporal variations of oceanographic processes. This knowledge can be applied to understand time-evolving mesoscale ocean dynamics, e.g., eddies and internal waves, as the evolution of their vertical structures is very difficult to capture using traditional in-situ oceanographic measurements. Recent 3D seismic oceanography studies with the time-lapsing concept (Dickinson et al., 2020; Gunn et al., 2020) are perfect examples of the application of this temporal variability in oceanographic studies. This temporal feature makes 3D seismic oceanography an extremely powerful tool for studying the temporal evolution of mesoscale ocean dynamics.

Crossline images capture both temporal and spatial information. Temporal variation being more prominent than spatial variation in the crossline direction is validated by the discontinuity in crossline images (Fig. 6), faster fluctuation in correlation function analysis in crossline direction (Fig. 9) and verified by theoretical analysis [Figs. 8 (b), (d)]. In contrast, if temporal variation of an imaged structure is less prominent, it would be buried under spatial variation without showing any discontinuity in crossline imaging. For example, the seafloor appears highly continuous (does not exhibit temporal variations) in our crossline imaging (Fig. 6) because it is associated with a long geological timescale longer than years. In general, ocean crossline images appear as low-quality seismic images, which might limit the imaging interpretation. This is mostly due to discontinuity induced
by temporal variation, rather than fewer receivers in the crossline direction than in the inline direction (8 vs. 640). Therefore, the low quality cannot be improved through common processing techniques such as trace interpolation (Yilmaz, 2001). Instead, the crossline imaging can only be improved by optimized 3D seismic survey configurations specifically designed for seismic oceanography, e.g., faster data collection across swaths in the crossline direction. Nevertheless, crossline images still provide valuable information, offering an immediate overview of the temporal distribution of the seismic survey.

In depth-slice images, temporal variation only appears in the crossline direction and is highly depth-dependent. This depth dependency comes from the timescale of ocean dynamics that occurred at different depths. Due to water mixing of surface wind-waves, the top portion of the water column is usually highly dynamic, while the deep water is associated with a very long timescale (Talley et al., 2012). Such a depth dependence, in terms of imaging discontinuity, can be seen in the crossline images (Fig. 6) and depth-slice images (Fig. 7), which is also evidence of the presence of temporal variation in the crossline direction. This depth dependency in 3D seismic oceanography can be a useful indicator to study the timescale of ocean dynamics at different depths.

A full investigation of the ocean dynamics observed by our seismic images, which would require further analysis of concurrent in-situ measurements and satellite data, is beyond the scope of this study, and will be conducted in our future study. Here we make a brief discussion on the occurred mesoscale ocean process based on our 3D seismic images. Prior studies shows the water dynamics in this region are dominated by Loop Currents and Mississippi river outflows, and possible ocean dynamics may include river plumes, internal waves, internal tides, and eddies (Coleman, 1988; Sturges and Lugo-Fernandez, 2005; Hamilton and Lee, 2005). According to our seismic images (Figs. 5–7), this mesoscale ocean process should have a temporal cycle longer than 8 days (the time separation between seismic images), a length scale larger than 25 km (exceeding the maximum width of our seismic images), and a depth of influence up to 600-800 m (down to the seafloor). Cross-referencing the above scales with the typical scales of possible ocean dynamics in this region, the only matched ocean dynamics are eddies. The Loop Currents create omnipresent cyclonic and anticyclonic eddies, moving northward and eastward in the Gulf of Mexico. We suggested that our seismic images have captured the process of an eddy approaching to the northern continental slope. When eddies approach the continental margin, they start to interact with the continental slope and generate internal wave fields over the slope. This process increases the vertical mixing and reduces the stratification, leading to a change of the water column from highly stratified to well-mixed (as seen in Fig. 5).

5 Conclusions

This study focuses on provide fundamental understanding of spatial and temporal variations embedded in 3D seismic data collected for oil and gas exploration. A 3D seismic volume of the northern Gulf of Mexico water column has been presented, and temporal and spatial variation in 3D oceanic seismic volume have been investigated for the first time using theoretical analysis and a correlation-based data analysis. Our results shows that in common 3D seismic surveys, temporal variation of mesoscale ocean dynamics can show up in the crossline direction, allowing one to view individual inline images as time-lapsing snapshots. The crossline and depth-slice images are heavily affected by temporal variation, and they cannot be directly
interpreted. This fundamental understanding is essential for the interpretation and analysis of 3D oceanic seismic images. It allows the extension of previous 2D seismic oceanography analysis, such as wave spectral analysis and diffusivity estimations, to 3D inline images, and to study the evolution of time-varying mesoscale ocean dynamics. The correlation analysis proposed in this study is an effective tool to access the temporal and spatial information within the seismic volume. We suggest that it is important to analyze temporal variation within a 3D seismic volume before the interpretation of 3D seismic images and the analysis of wave fields in the seismic images. We believe 3D oil industry seismic data carry a wealth of oceanographic information, and our future 3D seismic oceanography research will focus on further investigation of the evolution of mesoscale ocean dynamics (eddies and internal waves) in the northern Gulf of Mexico.

Data availability. The seismic data for this project were provided by Schlumberger WesternGeco. The data are available from Schlumberger Multiclient Seismic Data Library (http://www.multiclient.slb.com; area MC-14Q).

Author contributions. ZZ and LZ conducted seismic imaging analysis. PBR and LM performed 3D seismic data processing and imaging. All the authors equally contribute in writing and editing the manuscript.

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