

1 **Using kinetic energy measurements from altimetry to detect shifts in the**
2 **positions of fronts in the Southern Ocean**

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7 **Abstract.** A novel analysis is performed utilizing cross-track kinetic energy (CKE) computed
8 from along-track sea surface height anomalies. The mid-point of enhanced kinetic energy
9 averaged over three-year periods from 1993 to 2016 is determined across the Southern Ocean
10 and examined to detect shifts in frontal positions, based on previous observations that kinetic
11 energy is high around fronts in the Antarctic Circumpolar Current system due to jet instabilities. It
12 is demonstrated that although the CKE does not represent the full eddy kinetic energy (computed
13 from crossovers), the shape of the enhanced regions along groundtracks is the same, and CKE
14 has a much finer spatial sampling of 6.9 km. Results indicate no significant shift in the front
15 positions across the Southern Ocean, on average, although there are some localized, large
16 movements. This is consistent with other studies utilizing sea surface temperature gradients, the
17 latitude of mean transport, and probability of jet occurrence, but is inconsistent with studies
18 utilizing the movement of contours of dynamic topography.

19 1. INTRODUCTION

20 There is as much we don't know about the circulation of the Southern Ocean as we do.
21 Although the current system is routinely called the Antarctic Circumpolar Current (ACC), it
22 consists of several fronts with distinct water properties to the north and south of the fronts
23 (Nowlin and Clifford, 1982; Orsi et al., 1995; Belkin and Gordon, 1996). The most significant of
24 these fronts, responsible for the majority of the ACC volume transport (e.g., Cunningham et al.,
25 2003), are the Subantarctic Front (SAF) and the Polar Front (PF). However, even this is not a
26 realistic picture of the circulation in the Southern Ocean, since at any specific time, there can be
27 from three to ten narrow jets around the fronts that are highly variable in strength and location,
28 masking the specific frontal boundary (Sokolov and Rintoul, 2007, 2009a, 2009b; Sallee et al.,
29 2008; Thompson et al., 2010; Thompson and Richards, 2011; Langlais et al., 2011; Graham et
30 al., 2012; Chapman, 2014; Gille, 2014; Kim and Orsi, 2014; Shao et al., 2015; Chapman, 2017a).
31 Although positions of fronts have been estimated throughout the Southern Ocean, primarily
32 using gradients of subsurface density measured from hydrographic sections (Orsi et al., 1995),
33 contours of dynamic topography (Sokolov and Rintoul 2007, 2009a, 2009b; Langlais et al.,
34 2011), or a combination Kim and Orsi (2014), in many places there are no strong currents that
35 can be measured near the front position (Chapman, 2014; 2017a).

36 Because of the highly variable nature of jets and the lack of clear observational detection of
37 fronts in some areas, the literature has become muddled over the difference between a front and a
38 jet, primarily because the "front" is rarely observed at any specific time due to the high-
39 variability of jets (Thompson et al., 2010; Thompson and Richards, 2011; Chapman 2014;
40 2017a). However, even in the presence of highly variable jets, methods have been developed to
41 determine mean fronts positions in a probabilistic sense. Thompson et al. (2010) demonstrated

42 one could define fronts in the Southern Ocean by computing probability density functions of
43 potential vorticity in an eddy-resolving general ocean circulation model. Chapman (2014, 2017a)
44 later showed this could also be done using localized gradients in dynamic topography (i.e., high
45 geostrophic velocity) using satellite altimeter observations, but again, only as statistical
46 probability. This is because these areas of enhanced gradients and velocity are more reflective of
47 jets, which strengthen and die, appear and disappear, bifurcate and join back together. Because of
48 this, they can only be detected on average 10-15% of the time. However, Chapman (2014,
49 2017a) has demonstrated that, at least in a mean sense, fronts defined by mean dynamic
50 topography contours (commonly known as the “contour method”) do lie within the probability
51 distribution inferred from “gradient” methods.

52 An open question is how the fronts and jets that comprise the ACC will respond in a
53 warming climate. Analysis of climate models (which cannot simulate jets in the Southern Ocean)
54 suggests that as the atmosphere warms, the winds that drive the fronts and jets of the ACC will
55 migrate south (e.g., Fyfe and Saenko, 2006; Swart and Fyfe, 2012). It should be noted, however,
56 that the mean position of the southern hemisphere westerlies in the models lies significantly
57 equatorward of the true position (e.g., Figure 2 in Fyfe and Saenko, 2006). Thus, it is not entirely
58 clear whether the model is predicting a true shift in the wind position, or whether the model has
59 not yet reached equilibrium with winds in the proper location.

60 Still, based on these model results, researchers have been testing the hypothesis that as winds
61 in the Southern Ocean shift south, the frontal positions and jets will also migrate south. So far,
62 the results are mixed. Using the contour method and tracking how the dynamic topography
63 contours associated with a front position shift in time, Sokolov and Rintoul (2009b) found that
64 the SAF and PF had both moved south by approximately 60 km over 15 years between 1993 and

65 2008. Kim and Orsi (2014) recently updated this analysis and found that while the average
66 frontal position across the Southern Ocean indicates a strong southward shift, this is due
67 primarily to substantial shifts only in the Indian Ocean sector. They found no significant shifts
68 throughout the Pacific or Atlantic Ocean sectors using the contour method.

69 The primary assumption of these analyses is that if a contour of dynamic topography shifts
70 south, it is uniquely caused by a front moving south. This is not necessarily true. Gille (2014)
71 recently demonstrated that all contours in the Southern Ocean have shifted south on average, and
72 that this follows from the observed rise in sea level – as the sea surface height rises, the contours
73 will appear to shift south. While this breaks down at the far south and north of the ACC where
74 dynamic topography gradients are small, these areas are far away from the PF and SAF and so
75 have not been considered in previous analyses. Gille (2014) used a different measure to
76 determine the position of the ACC fronts, based on the latitude of the mean surface transport of
77 the ACC measured by altimetry, which is in essence a mean location of all the jets in the
78 Southern Ocean. She found no significant shift on average, but considerable interannual
79 variability, especially regionally.

80 Another factor other than sea level rise can cause the dynamic topography contour to shift
81 south -- if the magnitude and width of the jet has changed. This is demonstrated in **Figure 1**,
82 where we show the mean dynamic topography from two jet scenarios: 1) where the peak of two
83 Gaussian shaped jets have shifted south, and 2) where the peak has not shifted, but the magnitude
84 has decreased, the width has broadened, and the shape has become slightly skewed. Although the
85 resulting topography profiles are not identical, they are similar, and both suggest a southward
86 movement of dynamic topography contours.

87 Researchers using other methods also find little or no southern migration of the fronts or jets
88 in the Southern Ocean as a whole. Graham et al. (2012) used a high-resolution model to show
89 that the Polar Front and Subantarctic Front are constrained by bathymetry, even in increasing and
90 shifting winds. Shao et al. (2015) utilized the skewness of sea level anomalies to identify front
91 positions, and found no southward motion, but did find changes in the east Pacific correlated
92 with the Southern Annual Mode. Chapman (2017a), using positions of fronts determined from
93 the probability of jet locations, also found no significant southward movement, but high
94 interannual variability. Finally, Freeman and Lovenduski (2016a) used weekly estimates of the
95 Polar Front position determined from satellite sea surface temperature (SST) gradients to show
96 no significant southward shift between 2002 and 2014 on average, except in the Indian Ocean.
97 They also found a statistically significant northward shift of the PF in part of the south Pacific.

98 Thus, recent studies all agree that the Subantarctic Front and Polar Front have not shifted
99 south, even though there is evidence the winds have shifted south in the austral summer months
100 (Swart and Fyfe, 2012). It should be noted that when averaged over the full calendar year,
101 however, there has been no significant shift in the wind position (Swart and Fyfe, 2012).

102 In this paper, we develop a new method to study variability in the position of the fronts in the
103 Southern Ocean, based on tracking the location of envelopes of kinetic energy measured by
104 satellite altimetry. It is known from modeling studies that the front positions are associated with
105 increased kinetic energy, due to instabilities in the jets and interactions with bathymetry
106 (Thompson et al., 2010; Thompson and Richards, 2011). After demonstrating that kinetic energy
107 computed from along-track satellite altimetry forms relatively wide envelopes of enhanced
108 energy that occur within the probability range of jets and fronts (e.g., Chapman, 2017a), we track
109 the positions of these envelopes from 1993 until 2016 to quantify if the envelopes have shifted

110 south by a statistically significant amount. This is based on the assumption that if the front and
111 jets around the front have shifted south, then the envelope of high kinetic energy should also
112 move by a comparable amount. Since the kinetic energy calculation is based on estimating
113 gradients of sea level anomalies, this approach is similar to other gradient methods for detecting
114 fronts or jets (e.g., Chapman, 2014; 2017a; Gille, 2014; Freeman and Lovenduski, 2016a). It
115 differs from these approaches, however, in that instead of determining individual gradients and
116 tracking these over time, it looks for regions of high gradients (i.e., high energy) surround by
117 regions of low gradient (i.e., low energy). This allows us to detect envelopes for every time-
118 period considered, instead of only a fraction of the time, allowing for better tracking of the
119 change over time.

120 Section 2 will describe the data and methods used, while section 3 will present results,
121 including evaluation of the method for detecting mean positions of fronts and for tracking their
122 change over time. Section 4 will discuss the results in the context of previous studies and
123 evaluate the usefulness of the method.

124 **2. DATA AND METHODS**

125 We utilize geostrophic surface current anomalies computed from the 24-year record of 1-Hz
126 sea surface height (SSH) data along the TOPEX/Poseidon (T/P) groundtrack in the Southern
127 Ocean (**Figure 2**). The altimetry data used are from four separate altimeter missions:
128 TOPEX/Poseidon (January 1993 – January 2002), Jason-1 (February 2002 – July 2008), Jason-2
129 (August 2008 – August 2016), and Jason-3 (August 2016 – December 2016). Because the
130 official TOPEX/Poseidon (T/P) geophysical data records (GDRs) have not been updated since
131 the late 1990s, we utilize the corrected data products from the Integrated Multi-Mission Ocean
132 Altimeter Data for Climate Research provided by Beckley et al. (2010) at the NASA PO.DAAC

133 site (https://podaac.jpl.nasa.gov/Integrated_Multi-Mission_Ocean_AltimeterData). Jason-1 data
134 are from the GDR-C version and were downloaded from the NASA PO.DAAC site in June 2010.
135 Jason-2 are from the GDR-D version and were downloaded from NOAA NODC
136 (<ftp://ftp.nodc.noaa.gov/pub/data.nodc/jason2>) between August 2012 and June 2016. Jason-3 are
137 also from the GDR-D version and were downloaded from NOAA NODC
138 (<ftp://ftp.nodc.noaa.gov/pub/data.nodc/jason3>) on August 7 and 8, 2017.

139 We utilize the 1-Hz along-track SSH data from the four altimeters and compute sea level
140 anomalies by interpolating the DTU10 mean sea surface model (Andersen and Knudsen, 2009;
141 http://www.space.dtu.dk/english/Research/Scientific_data_and_models/downloaddata) to the
142 SSH location using bilinear interpolation. The DTU10 mean sea surface model is based on SSH
143 from multiple altimeters averaged over 17 years in a rigorous and consistent manner (Andersen
144 and Knudsen, 2009). T/P, Jason-1, and Jason-2 data were all included. All recommended
145 geophysical and surface corrections (e.g., water vapor, ionosphere, sea state bias, ocean tides,
146 inverted barometer, etc) have been applied, to correct for biases introduced by atmospheric
147 signal refraction and sea state effects (e.g., Chelton et al., 2001).

148 We utilize this record rather than the gridded products based on mapping SSH from multiple
149 altimeters (e.g., Ducet et al., 2000; Pujol et al., 2016), because the along-track data have a finer
150 resolution in space (6.9 km along the groundtrack) and we recently demonstrated that the
151 mapped altimetry data underestimated eddy kinetic energy (EKE) throughout the Southern
152 Ocean compared to using along-track data by as much as 60-70% (Hogg et al., 2015). While the
153 along-track sea level anomalies are filtered to reduce noise and thus may attenuate some signal,
154 the filtering used (described later in this section), is less than that used for the mapped data,
155 which uses observations from as long as 20 days and 200 km away to influence the mapped

156 value. By filtering only alongtrack data, the time differences are small (a few minutes at most),
 157 and the spatial influence is less than 100 km. Tests with unfiltered data accounting for estimated
 158 random noise in the sea level anomaly data suggests attenuation of kinetic energy is minimal
 159 with this approach and, more importantly, that the shape of the kinetic energy envelope does not
 160 significantly change.

161 One can only compute EKE from alongtrack data at crossover points, where the ascending
 162 and descending groundtracks cross (Figure 2). Knowing the groundtrack angle with the north
 163 meridian (θ) one can compute the zonal ($d\eta/dy$) and meridional gradients ($d\eta/dx$) of SSHA
 164 directly from the gradients of SSHA for the ascending pass ($d\eta/dr_{asc}$) and descending pass
 165 ($d\eta/dr_{des}$) using simple geometry (Parke et al., 1987)

$$166 \quad \frac{d\eta}{dy} = \frac{\left[\frac{d\eta}{dr_{asc}} - \frac{d\eta}{dr_{des}} \right]}{2 \sin \theta}, \quad \frac{d\eta}{dx} = \frac{\left[\frac{d\eta}{dr_{asc}} + \frac{d\eta}{dr_{des}} \right]}{2 \cos \theta}, \quad (1)$$

167 noting that this formulation assumes the gradients represent the derivative of the northern SSHA
 168 relative to the southern SSHA (for both the ascending and descending passes). Once this is
 169 computed, the velocities can be computed directly from the zonal and meridional gradients:

$$170 \quad u = -\frac{g}{f} \frac{d\eta}{dy}, \quad v = \frac{g}{f} \frac{d\eta}{dx}, \quad (2)$$

171 where g is the acceleration due to gravity, and f is the Coriolis parameter

172 This formulation assumes that the velocity field has not changed significantly between the
 173 times the two passes fly over the crossover point. At high latitudes, the majority of crossovers (>
 174 78%) have a time separation of less than 3 days. At 40° , the average propagation speed of an
 175 eddy is about 3 cm s^{-1} [Chelton et al., 2007], meaning the eddy would have only been displaced

176 by 8 km at most over this period. At higher latitudes, this is even less. Considering the diameter
177 of eddies at these latitudes are of order 100 km [Chelton et al., 2007], the movement is not large
178 enough to cause a significant change in velocity at the point. The primary problem with
179 velocities computed from crossovers is the smaller number compared to using gridded data, or
180 the time-varying, anomalous geostrophic current normal to the groundtrack (u_T). This can be
181 computed directly from the derivative of the SSH anomaly (η) along the ground-track distance
182 (dr) from

$$183 \quad u_T = -\frac{g}{f} \frac{d\eta}{dr} \quad (3)$$

184 This cross-track current is a projection of both the zonal (u) and meridional (v) components of
185 the full anomalous velocity field. However, neither u nor v can be determined unambiguously
186 from u_T . Here, we merely examine the variability of u_T without making any assumptions
187 concerning how it may be related to the full velocity, or u and v .

188 Because derivatives of SSHA (Equations 1 and 3) have to be computed numerically (here,
189 center-differences are used) and η contains significant noise at the 1 Hz sampling-rate of the
190 altimeters, we optimally interpolate η along-track using a model of the covariance of the signal
191 and error. We used the method of Wunsch (2006, Chapter 3) and a covariance function modeled
192 as a Gaussian with a roll-off of 98 km and random noise of 2 cm, which was determined from the
193 autocovariance of all TOPEX/Poseidon, Jason-1, and Jason-2 SSHA data from 1993-2015
194 between 40°S and 65°S.

195 Once $u_T(t)$ was computed at each 1-sec bin along the groundtracks in Figure 2 for each 10-
196 day repeat cycle, the cross-track kinetic energy (CKE) was computed as $\text{CKE}(x,t) = 0.5 u_T(x,t)^2$,

197 where x here is used to denote a generic 1-sec bin along the ground track. We also computed the
198 full EKE at the more limited crossover points as $EKE(x,t) = 0.5(u(x,t)^2 + v(x,t)^2)$.

199 The CKE values were averaged over the entire 24-year record and examined for each
200 groundtrack segment (both ascending and descending) to judge where CKE was exceptionally
201 high (Figure 3). We also computed CKE using the raw values of η with no optimal interpolation
202 and compared to that computed with optimal interpolation. The locations of high CKE were the
203 same, although values were significantly higher with the unsmoothed data. The quiescent regions
204 of the ocean also showed considerably more noise, making it more difficult to determine
205 boundaries of elevated CKE. For this reason, the values determined from the optimally
206 interpolated data were used.

207 Several criteria were utilized to quantify where the high CKE values were considered to be
208 associated with fronts. First, we constrained the southern boundary to be 5° south of the Orsi et
209 al. (1995) values of the PF and the northern boundary to be 5° north of the SAF. Secondly, we
210 used a lower-limit for CKE of $200 \text{ cm}^2 \text{ s}^{-2}$ for detection and tested that the width of the envelope
211 of high CKE above the lower-limit was at least 100 km. The requirement that the envelope be
212 greater than 100 km was done to reduce the impact of eddies in an otherwise quiescent region,
213 since the diameter of eddies in the Southern Ocean is about 100 km. The CKE lower-limit was
214 determined via iteration with different limits. For each case, the average center of the CKE
215 envelope averaged over 24-years (based on the mean of the first and last points to exceed the
216 lower-limit) was computed and compared visually to the Orsi et al. (1995) front positions. 200
217 $\text{cm}^2 \text{ s}^{-2}$ was selected because there were a significant amount of CKE envelope centers clustered
218 around the Orsi et al. (1995) fronts and the envelopes were found for every 10-day repeat cycle.
219 Using a higher limit resulted in fewer detections, especially when smaller time-averages were

220 used. Using a lower limit, we could find more potential front positions based on CKE, but many
221 were far from the front positions estimated by Orsi et al (1995).

222 An example of a detected high CKE envelope is shown in Figure 3, based on the average of
223 CKE between 1993 and 2015 computed from T/P-Jason satellite pass 207 in the south Indian
224 Ocean. This pass starts at 64.3°S near the prime meridian and extends to 41.2°S and 41°E
225 longitude. There is clearly a wide envelope of enhanced CKE greater than 200 cm² s⁻² between
226 55°S and 47°S.

227 The mean CKE profile pictured in Figure 3 has multiple local maxima, most likely associated
228 with variability of the narrow jets that surround the front. As shown by Chapman (2017a), these
229 jets (evidenced in higher gradients of SSHA) do not occur around a front 100% of the time. At
230 most, they occur about 30% of the time, and more often less than 15% of the time. Figure 4
231 shows the behavior of CKE along this pass for different 3-year periods. Note that the number of
232 clearly defined maxima ranges from a low of 4 for the 2014-2016 average to 9 in 1993-1995.
233 While other studies have estimated positions of these maxima in SSHA gradients on daily
234 intervals (e.g., Chapman, 2017a), one does not obtain a consistent number of maxima each time,
235 making the determination of shifts difficult. Moreover, note that although there are two general
236 peaks in CKE in the long-term mean profile, the minimum between them is still higher than 200
237 cm² s⁻². A minimum is also not well defined in several of the shorter averaging periods (for
238 example, 2008-2010).

239 Thus, instead of attempting to track all the maxima of CKE individually – analogous to
240 tracking steepest gradients, as in Thompson et al. (2010), Graham et al. (2012), or Chapman
241 (2017a) – we track an estimate of the center of the envelope of enhanced CKE, as it exists in all
242 averaging periods. The assumption we make in doing this is that the localized maxima are

243 associated with variable jets, but the position of the envelope of high CKE is related to the front.

244 There are many different ways to compute a “center” of the envelope, ranging from the
245 average of the two end points, to a centroid calculation, to computing the point where the integral
246 of CKE over distance is balanced on both sides, which we call the “half-power point.” We have
247 selected the latter to use, as it defines a “center” closer to the peak of CKE in the envelope. This
248 is advantageous when the CKE curve is slightly skewed, with less magnitude on one side and
249 more on the other. Assuming that the variability (and hence CKE) would be highest near the
250 front (i.e., what is assumed in studies using the gradient method), finding a center of the
251 envelope that is biased toward peak CKE is a reasonable approach.

252 The half-power point (x_{mid}) is computed so that

$$253 \int_{x_{south}}^{x_{mid}} CKE(x) dx = \frac{1}{2} \int_{x_{south}}^{x_{north}} CKE(x) dx, \quad (4)$$

254 where x_{south} and x_{north} are computed by first finding the maximum of CKE in the envelope above
255 $200 \text{ cm}^2 \text{ s}^{-2}$, then finding the first value to the north just below 25% of that peak along with the
256 similar value to the south (shown in Figure 3). Values other than 25% of the peak were tested.
257 Using value greater than this, up to 50%, resulted in no significant difference in the half-power
258 point. Using values smaller resulted in some boundaries not being defined. Thus, 25% of peak
259 CKE was considered reasonable. If multiple regions of enhanced CKE were found along the
260 same track, this process was carried out for each of them. This was done for all the 24-year mean
261 CKE profiles to establish the mean locations of the fronts between 1993 and 2016.

262 A similar procedure was done for CKE averaged over discrete 3-year intervals, starting in
263 January 1993 and ending in December 2016. A 3-year average was used to reduce the influence
264 of individual eddies on determining the envelope, and to reduce interannual variations in the

265 front position, which have been observed in other studies at some locations (e.g., Kim and Orsi,
266 2014; Shao et al., 2015). In particular, Kim and Orsi (2014) and Shao et al. (2015) found
267 significant correlation with the Southern Annular Mode, which has a quasi-biennial oscillation
268 (Hibbert et al., 2010). By averaging over three years, we found 8 distinct, statistically
269 uncorrelated samples of CKE for each groundtrack from which to deduce shifts in the half-power
270 point.

271 **3. RESULTS AND ANALYSIS**

272 The first thing tested was how well CKE represented the full EKE. If CKE does not have the
273 same general shape as EKE, then using it as a proxy for EKE to determine high energy envelopes
274 is not valid. After finding satellite passes with high CKE as discussed in Section 2, EKE was
275 computed along the same pass, using the crossover method (Equations 1 and 2).

276 Although CKE is lower than EKE along all groundtracks (see Figure 5 for examples), the
277 pattern of KE rise then fall is virtually identical. CKE, however, has the benefit of higher and
278 more regular sampling. Thus, we conclude CKE is a reasonable proxy for locating front positions
279 even though it may not be useful for quantifying the full energy of the anomalous currents.

280 Four general types of enhanced CKE were found (Figures 4 and 5). In most regions, the
281 envelope in CKE is more or less symmetrical (52% of cases). Only a few profiles have two
282 distinct regions of enhanced CKE that were identified, with a clearly defined minimum below
283 $200 \text{ cm}^2 \text{ s}^{-2}$ between them in all time periods (3% of cases). 20% of the passes have multiple
284 peaks that vary in time but have no consistent minimum between the peaks (i e., Figure 4), while
285 25% have a skewed envelope (Figure 5), with a long rise in CKE followed by a sharp drop-off.
286 In all cases, though, the shape of the CKE envelope closely follows that of EKE, although the

287 amplitude was attenuated, by anywhere from 25-50%. Having closer samples of CKE, however,
288 allows for a better computation of the half-power point and possible shifts.

289 Figure 6 shows the locations of the half-power points determined from the mean CKE
290 profiles, along with estimate of the front position based on different methods: density gradients
291 from historical hydrographic sections (Orsi et al., 1995), dynamic topography contours (Kim and
292 Orsi, 2014), and the gradient of sea surface temperature (Freeman and Lovenduski, 2016a).
293 There are two estimates of the SAF and SACCF, and three of the PF. One of the PF estimates
294 (from Freeman and Lovenduski, 2016a) includes the standard deviation of the daily estimates.

295 It is important to note the large differences in estimates for the same front, which indicates
296 how uncertain these calculations are. For instance, in the Indian Ocean at 50°E, Freeman and
297 Lovenduski (2016a) find the PF at the same location that Orsi et al. (1995) found the SAF, while
298 Kim and Orsi (2014) find it significantly farther south. The SAF determination using the contour
299 method (Kim and Orsi, 2014) is substantially farther north than the one determined from
300 hydrographic data (Orsi et al., 1995) at most longitudes.

301 Many estimates from the half-power points of enhanced CKE occur between the same front
302 estimated by different methods, indicating they are at least within the uncertainty bounds of
303 frontal detection by other methods. Other values are at locations either north or south of the other
304 front estimates by as much as 3°, but it should be noted that the standard deviation of the PF
305 estimated by Freeman and Lovenduski (2016a,b) averages 2-3°, indicating these positions
306 estimated from CKE are well within the level of expected frontal variability.

307 Probably a better method for determining frontal position is to examine the probability of jets
308 occurring (Chapman, 2017a) (Figure 7). The CKE-defined mean front positions lie within the
309 probability envelopes, giving more confidence that the CKE measure is providing a comparable

310 measure of frontal position in many areas. The only location where CKE-defined fronts don't
311 agree well with the probability field from Chapman (2017a) is just west of the dateline, where
312 two points lie between levels of high jet (and hence front) probability.

313 Still, the good comparison is reassuring that the method developed in Section 2 is
314 successfully detecting regions of high energy related to jets around fronts. Since the movement
315 of jet positions has been used to estimate movement of the fronts (e.g., Chapman, 2017a), a
316 comparable calculation with positions of high CKE seems reasonable.

317 To quantify movement of the envelope of enhanced CKE, a linear trend is fit to the 8
318 estimations of the half-power point from 1993-2016 for each location shown in Figures 5 and 6.
319 Analysis of the residuals about the trend indicated they were random (lag-1 autocorrelation < 0.1
320 for all cases), so standard error was computed by scaling the formal error from the covariance
321 matrix determined in ordinary least squares by the standard deviation of the residuals. This was
322 also scaled up to account for the degrees of freedom lost by estimating the trend by $\sqrt{n/n_{EDOF}}$,
323 where $n = 8$, and $n_{EDOF} = 6$. Finally, the 90% confidence interval was computed by scaling by
324 1.94 for 6 effective degrees of freedom assuming a normal t-distribution of the residuals.

325 The results indicate considerable regional variability in the change of the half-power point
326 over 24 years, with large uncertainty bars (Figure 8). This is due to the substantial temporal
327 variability in the positions, which can be seen in Figure 4, where the leading edge of the CKE
328 envelope varies by over 1 degree of latitude (over 100 km) between 1993-1995 and 2011-2012.
329 To better see significant changes outside the uncertainty (90% confidence) interval, one can
330 compute the signal to noise ratio (SNR = trend/uncertainty). Examining this (Figure 9), one can
331 see there are some regions where the half-power point has moved southward by a significant
332 distance over the last 24 years (13.6% of points), but there are also points where it has moved

333 north (9.6%). For the majority of points (76.8%), there is no statistically significant change,
334 meaning no movement of the front is as likely as either a southward or northward shift due to the
335 high variability in 3-year positions.

336

337 **4. DISCUSSION AND CONCLUSIONS**

338 The results from the analysis of the positions of enhanced kinetic energy suggest no overall
339 shift in the frontal positions across the Southern Ocean, but some large, localized movements.
340 The region indicative of some southward shift between 90°E and 170°E is in approximately the
341 same area where Kim and Orsi (2014) and Freeman and Lovenduski (2016a) also reported large
342 shifts, between 1992 to 2011 and 2002 and 2014, respectively. However Freeman and
343 Lovenduski only examined the Polar front, and Kim and Orsi (2014) only found large shifts in
344 the PF and the southern ACC front. They found shifts of order 50-100 km in the SAF where the
345 points in this study cluster, which is considerably smaller than the individual shifts we find
346 between 90°E and 170°E along the SAF. However, the overall average over the region between
347 90°E and 170°E (-29 km per decade, or -66.7 km in 23 years), is consistent with what Kim and
348 Orsi (2014) found.

349 Kim and Orsi (2014) and Freeman and Lovenduski (2016a) also found slight northward
350 shifts in the front positions in the southeast Pacific, between 200°E-270°E. We also find some
351 locations in this region with a significant northward shift in the SAF. Kim and Orsi (2014) found
352 the shift of the SAF was about 30-40 km between 1992 and 2011. Our results suggest larger
353 shifts in some areas; averaged over the area, our results are 46 km per decade to the north, or 106

354 km from 1993-2015, which is consistent with the average over the region computed by Freeman
355 and Lovenduski (2016a) from sea surface temperature data, but for the Polar Front.

356 Kim and Orsi (2014) suggest that the shift of the fronts in the Indian Ocean were not directly
357 related to shifts in winds, but instead were caused by an expansion of the Indian subtropical gyre.
358 They linked the shift in the southeastern Pacific to wind changes related to mainly the Southern
359 Annular Mode in that region (Kim and Orsi, 2014).

360 Overall, this study supports the recent studies by Kim and Orsi (2014), Gille (2014), Freeman
361 and Lovenduski (2016a), and Chapman (2017a). All find that, while the frontal positions of the
362 ACC are highly variable in time, there is no statistically significant shift in the fronts to the south
363 on average. This study utilized a novel technique to reach this conclusion, which adds to the
364 robustness of evidence that there has not been a shift in the frontal positions. Thus, while the
365 fronts may eventually shift south in a warming climate, there is no strong evidence that it is
366 happening at the moment.

367 Other studies have shown significant positive trends in the Southern Ocean that have been
368 connected to the warming climate. These include changes in the ocean heat content in the upper
369 ocean between the 1930s-1950s and 1990s (e.g., Böning et al., 2008; Gille, 2008), increases in
370 the heat content of deep water between the 1990s and 2005 (e.g., Purkey and Johnson, 2010),
371 and increases in eddy kinetic energy in the Indian and Pacific Oceans since 1993 (Hogg et al.,
372 2015). Observational evidence of shifts in the winds, however, indicates that while there may be
373 a slight southward shift in winds during the southern hemisphere summer, the overall yearly
374 average shift is not significant (Swart and Fyfe, 2012). Thus, the growing consensus that fronts
375 have not shifted to the south, on average, is consistent with observations of no significant shift in
376 the yearly averaged winds.

377 The only evidence supporting a hypothesis that ACC fronts have shifted southward since the
378 1990s comes from mapping the location of contours of constant dynamic topography over time
379 (e.g., Sokolov and Rintoul, 2009b; Kim and Orsi, 2014). As Gille (2014) argued and as we have
380 demonstrated based on a simple thought experiment (Figure 1), there are other equally plausible
381 explanations for the apparent southern shift of the contours. Considering that four different
382 techniques – location of mean transport (Gille, 2014), maximum SST gradients (Freeman and
383 Lovenduski, 2016a), probability of jet positions (Chapman, 2017a), and the location of enhanced
384 kinetic energy (this study) – all agree that the fronts have not moved significantly on average,
385 one has to conclude that the method of using dynamic topography contours to detect changes in
386 front position is too sensitive to sea level rise to be useful for determining shifts in frontal positions,
387 although it may prove useful for determining the mean position as Chapman (2017a) has argued.
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493 **Figure Captions**

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495 **Figure 1.** a) Mean dynamic topography in the Southern Ocean along a north-south meridian for three
496 scenarios, and b) the corresponding geostrophic velocity, with positive values indicating eastward flow.
497 The scenarios are: an initial state (dashed black line), a shift of the two fronts south by 60 km with no
498 change in magnitude or shape of the currents (red line), and no shift of the mean of the current, but a
499 change in the magnitude and shape (blue line).

500

501 **Figure 2.** Positions of the T/P, Jason-1, Jason-2 and Jason-3 groundtracks used for this study (black
502 lines), and the approximate locations of the Subantarctic Front (red line) and the Polar Front (blue
503 line) as estimated by Orsi et al. (1995). The orange track shows the location of the pass used in analysis
504 shown in Figures 3 and 4.

505

506 **Figure 3.** An example profile of mean CKE (1993-2015) along a ground track in the southern Indian
507 Ocean (shown in orange in Figure 2), demonstrating the location of the half-power point and the locations
508 of the southern and northern boundaries of the enhanced CKE envelope. See text for details of the
509 computations.

510

511 **Figure 4.** Three-year averages of CKE estimated along pass shown in Figure 2 (solid lines) along with
512 the long-term mean from 1993-2016 (dotted line).

513

514 **Figure 5.** Examples of the three types of CKE profiles found (black lines), along with the value of the full
515 EKE computed at crossover points.

516

517 **Figure 6.** Mean positions of fronts estimated from CKE (orange dots) along with estimates from other
518 authors: Orsi et al. (1995) computed using hydrographic sections, Kim and Orsi (2014) based on contours
519 of dynamic topography, and Freeman and Lovenduski (2016a) based on gradients of sea surface
520 temperature. The Orsi et al. (1995) fronts were downloaded from
521 https://gcmd.nasa.gov/records/AADC_southern_ocean_fronts.html. The Freeman and Lovenduski fronts
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523 2016b). The Kim and Orsi (2014) fronts were provided by Yong Sun Kim upon request.

524

525 **Figure 7.** Mean positions of fronts estimated from CKE (black dots) along with the percent occurrence of
526 a jet between 1993 and 2014 computed by Chapman (2017a). Data were downloaded from
527 <http://dx.doi.org/10.5061/dryad.q9k8r> (Chapman, 2017b). The percent occurrence of the jet was
528 computed by calculating the number of times a jet occurred in the daily files, dividing by the total number
529 of days between January 1993 and December 2014, and multiplying by 100.

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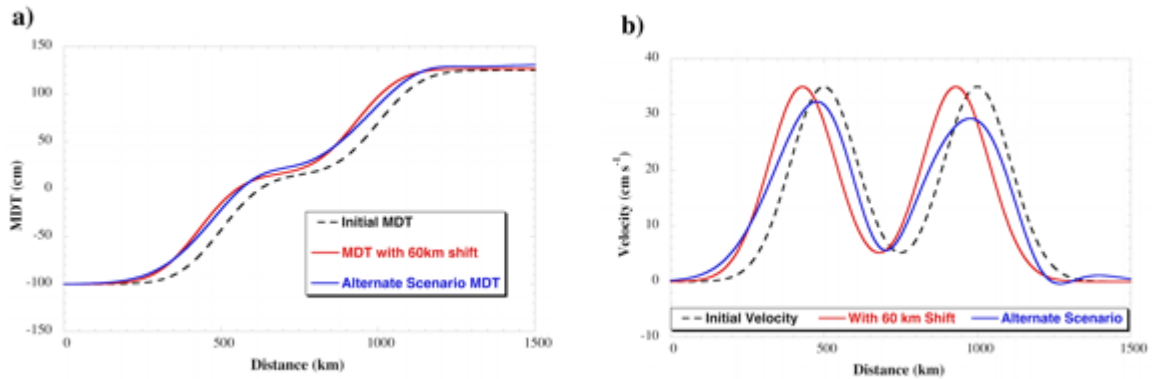
531 **Figure 8.** Estimated trend in the half-power point of CKE for each location shown in Figures 6 and 7, as a
532 function of latitude. Error bars represent the 90% confidence interval.

533

534 **Figure 9.** SNR (trend/error in Figure 8). Values larger than 1 indicate a statistically significant northern
535 shift. Values smaller than -1 indicate a statistically significant southern shift. Values between ± 1 indicate
536 no statistically significant shift.

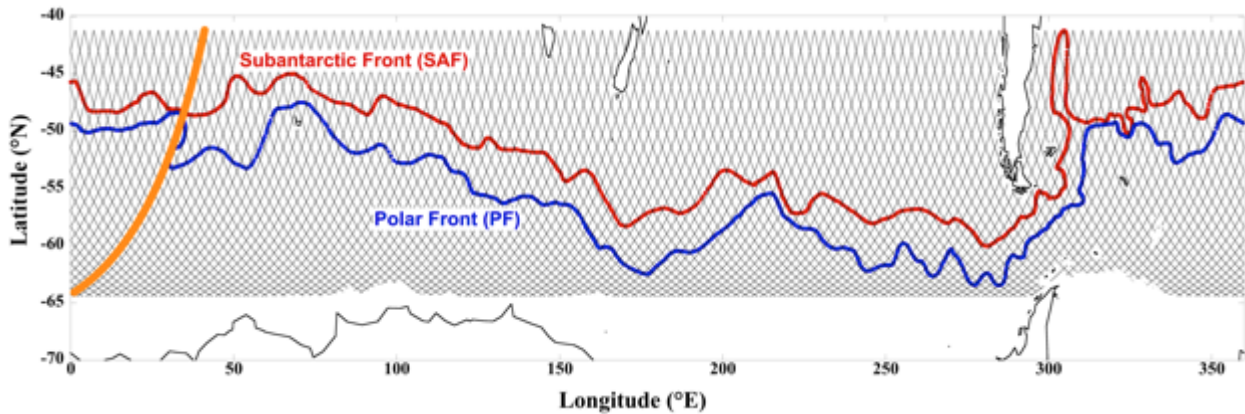
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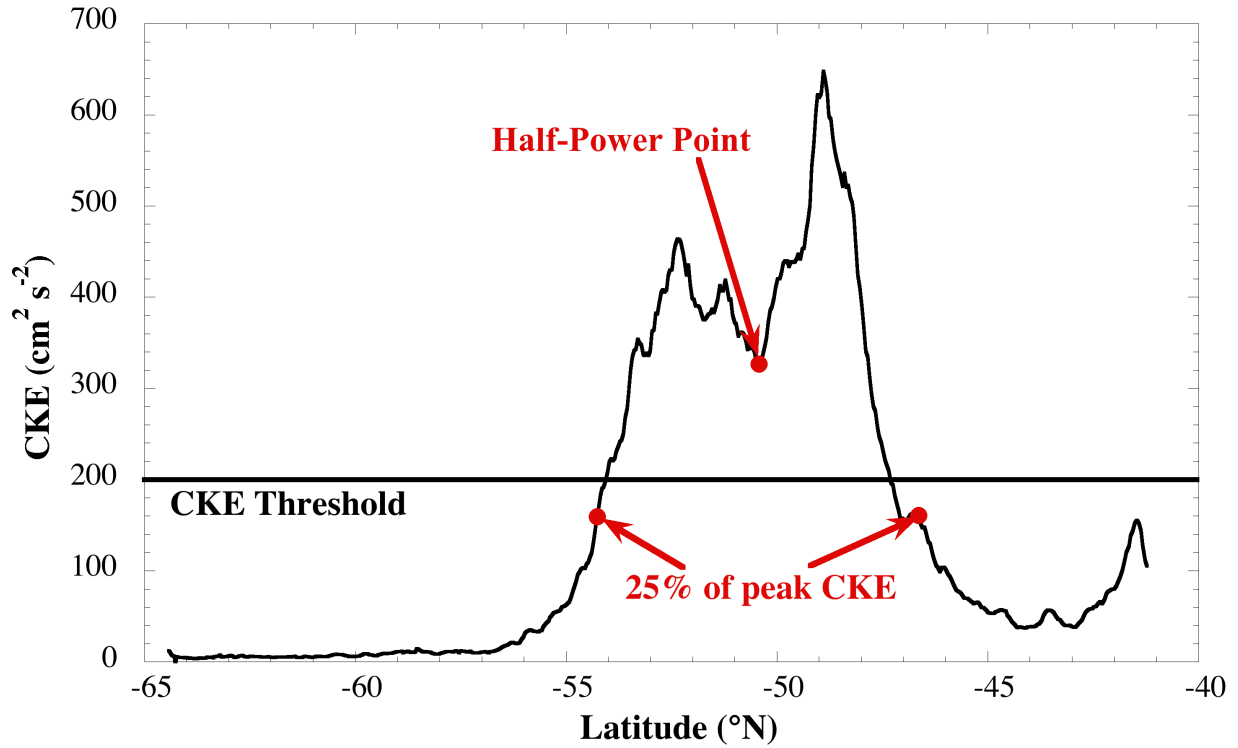
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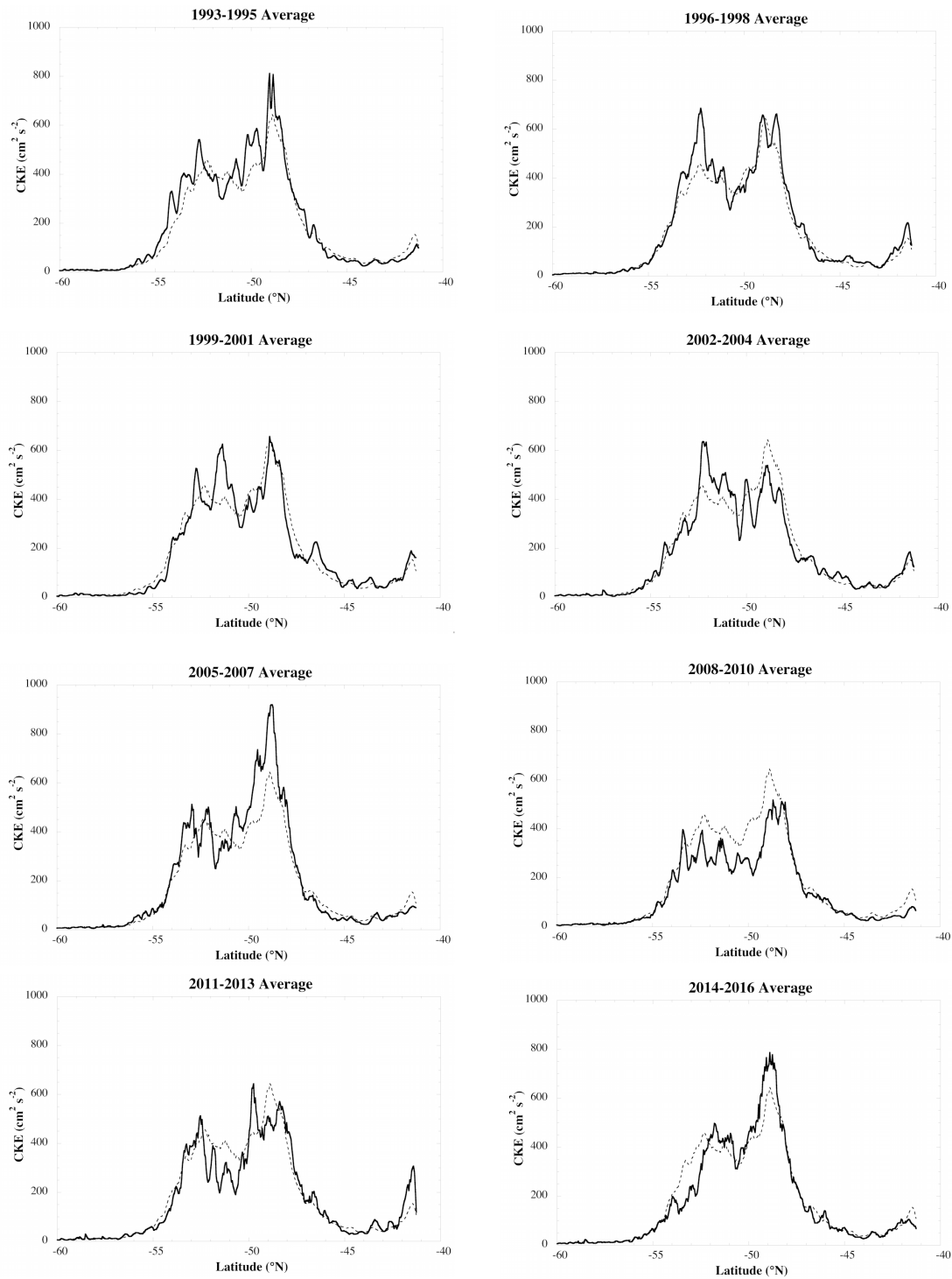
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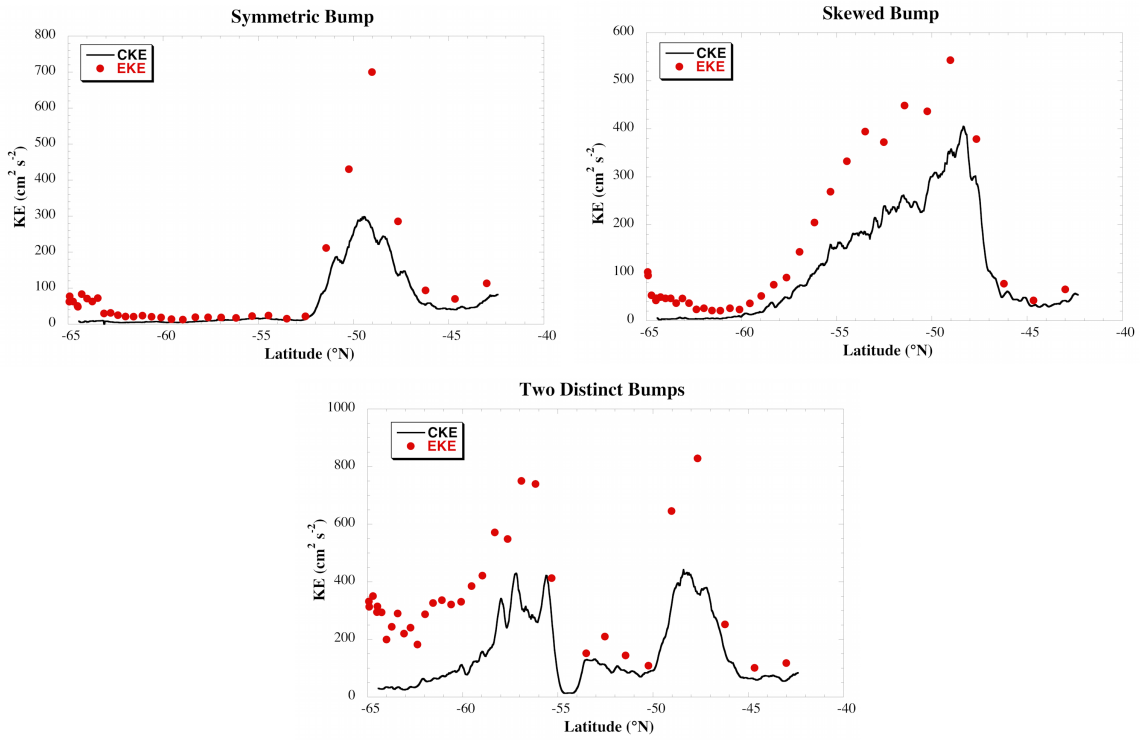
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Figure 4. Three-year averages of CKE estimated along pass shown in Figure 2 (solid lines) along with the long-term mean from 1993-2016 (dotted line).

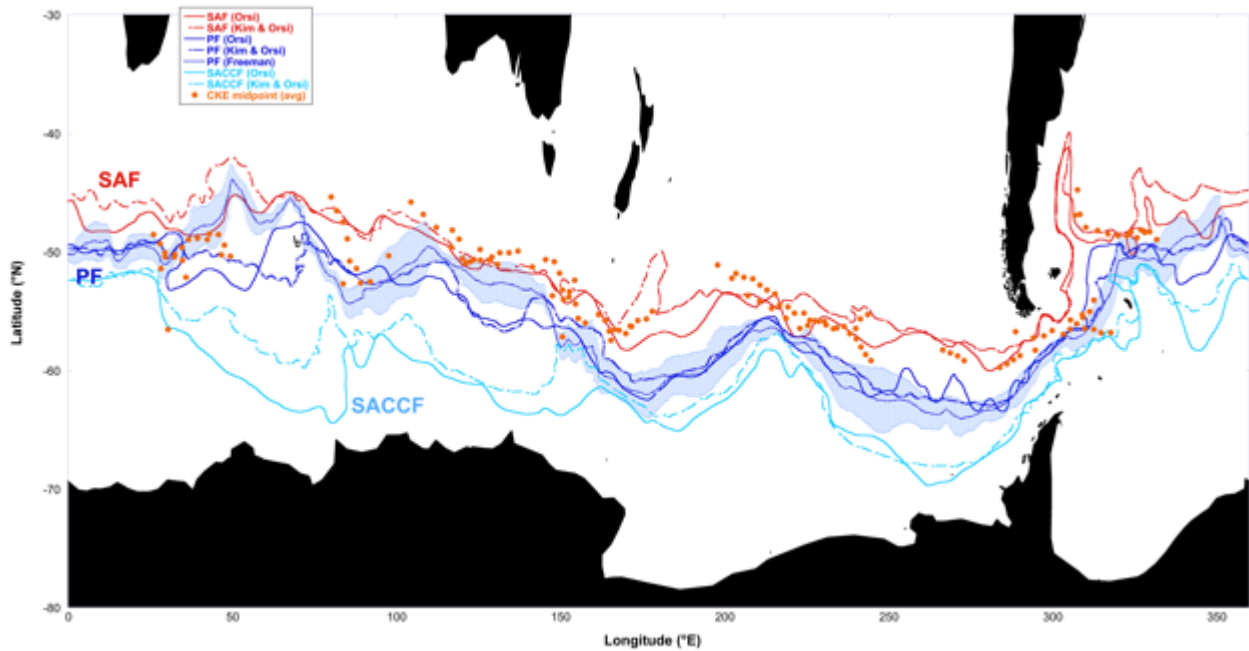
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Figure 5. Examples of the three types of CKE profiles found (black lines), along with the value of the full EKE computed at crossover points.

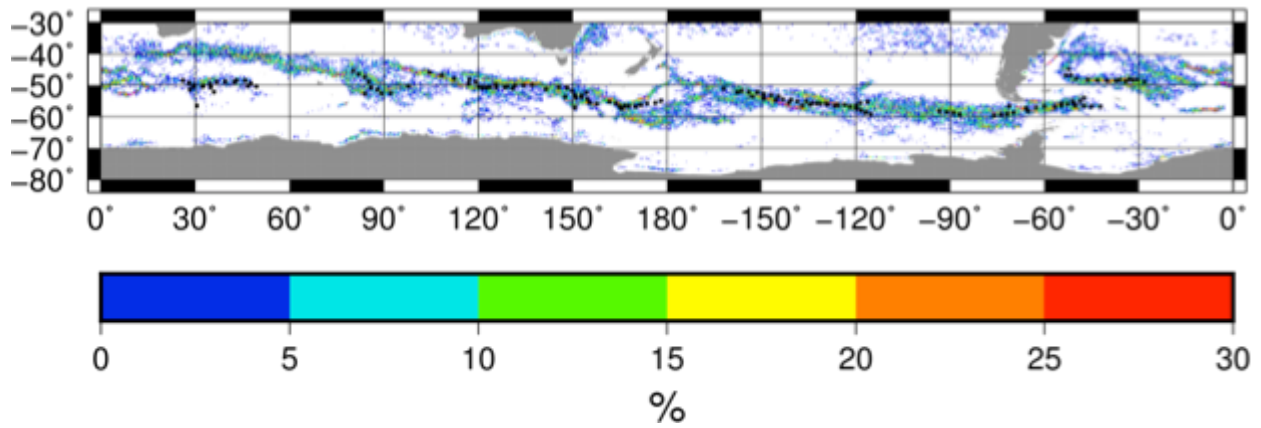
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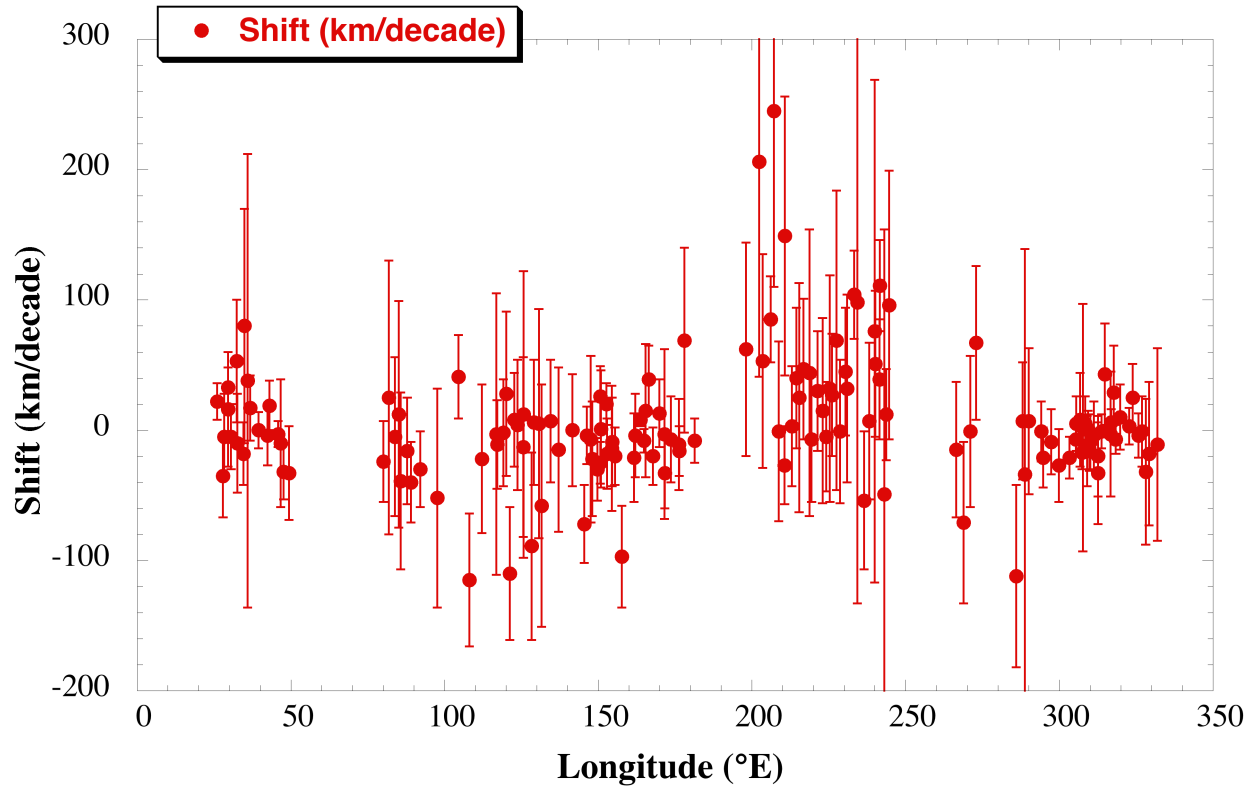
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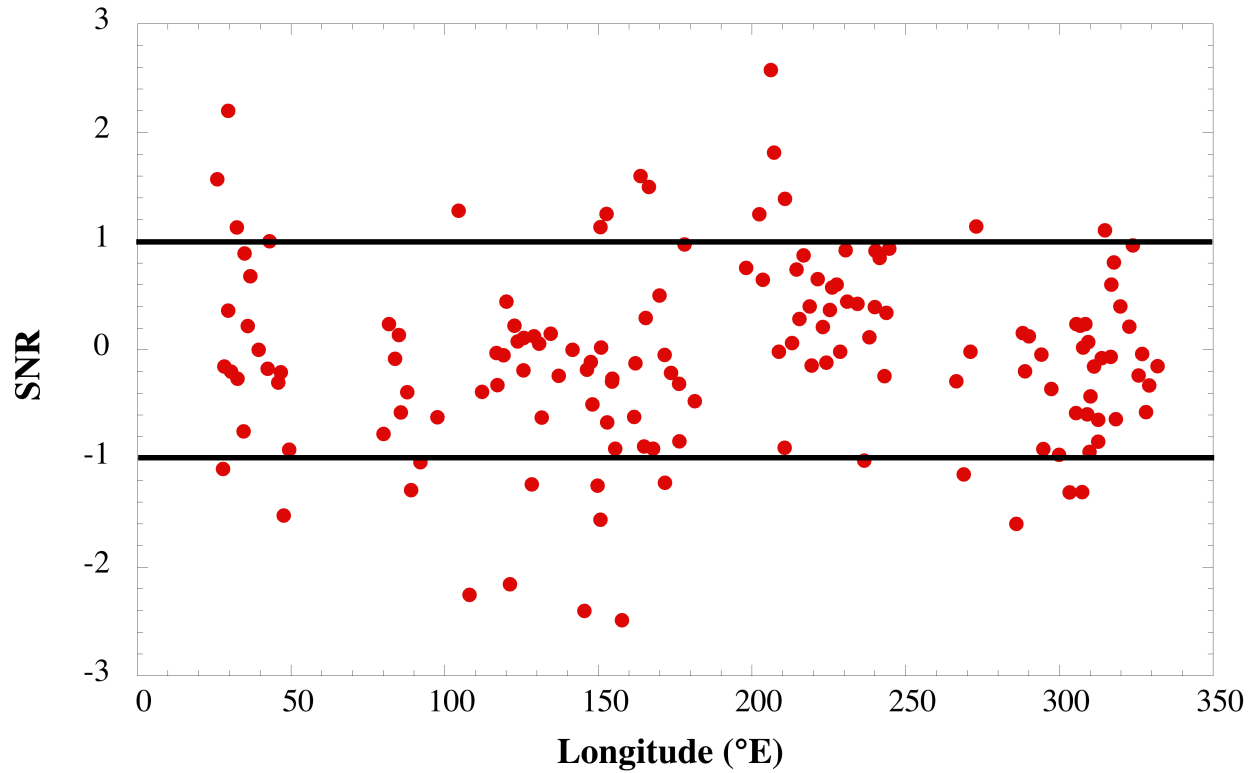
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