



- 1 Application of EnOI Assimilation in BCC_CSM1.1: Twin
- 2 Experiments for Assimilating Sea Surface Data and T/S Profiles
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11 Key words:

- 12 Global ocean data assimilation; EnOI; Twin experiments; One-year prediction
- 13





14	Abstract – We applied an Ensemble Optimal Interpolation (EnOI) data assimilation
15	method in the BCC_CSM1.1 to investigate the impact of ocean data assimilations on
16	seasonal forecasts in an idealized twin-experiment framework. Pseudo-observations
17	of sea surface temperature (SST), sea surface height (SSH), sea surface salinity (SSS),
18	temperature and salinity (T/S) profiles were first generated in a free model run. Then,
19	a series of sensitivity tests initialized with predefined bias were conducted for a
20	one-year period; this involved a free run (CTR) and seven assimilation runs. These
21	tests allowed us to check the analysis field accuracy against the "truth". As expected,
22	data assimilation improved all investigated quantities; the joint assimilation of all
23	variables gave more improved results than assimilating them separately. One-year
24	predictions initialized from the seven runs and CTR were then conducted and
25	compared. The forecasts initialized from joint assimilation of surface data produced
26	comparable SST root mean square errors to that from assimilation of T/S profiles, but
27	the assimilation of T/S profiles is crucial to reduce subsurface deficiencies. The ocean
28	surface currents in the tropics were better predicted when initial conditions produced
29	by assimilating T/S profiles, while surface data assimilation became more important
30	at higher latitudes, particularly near the western boundary currents. The predictions of
31	ocean heat content and mixed layer depth are significantly improved initialized from
32	the joint assimilation of all the variables. Finally, a central Pacific El Niño was well
33	predicted from the joint assimilation of surface data, indicating the importance of joint
34	assimilation of SST, SSH, and SSS for ENSO predictions.





35 1. Introduction

Oceans play a key role in the predictability of the climate system due to their tremendous thermal inertia compared to atmosphere or land (Counillon et al. 2014). Accuracy of the ocean initialization during modeling can significantly impact seasonal to decadal climate predictions (Alves et al. 2011; Zheng and Zhu 2015). A common strategy to obtain the optimal initialization is to assimilate available ocean observations into ocean models, which aim to produce the best estimates of ocean states.

43 There have been many advances in data assimilation techniques ranging from the 44 relatively simple optimum interpolation (OI) and three-dimensional variational 45 methods (3DVAR) to more sophisticated four-dimensional variational methods (4DVAR) and the Ensemble Kalman Filter (EnKF) approach. The OI and 3DVAR 46 based schemes are computationally cheap to perform and have been widely used in 47 operational ocean forecasting systems. However, both OI and 3DVAR use the 48 49 time-invariant background error covariance, which tends to produce inaccurate 50 analyses in areas with highly nonlinear flows. This problem can be partly solved by 51 using the flow-dependent error covariance adopted in EnKF and 4DVAR.

Although EnKF and 4DVAR have been used in many studies, practical problems still exist for realistic ocean applications, especially for operational global ocean data assimilation systems. One disadvantage is that EnKF and 4DVAR are computationally expensive to perform. For example, the computational costs of EnKF





56	increase linearly with the ensemble number N. A value of $N > 20$ is unaffordable for
57	operational forecasting given our current limited computer resources, while EnKF
58	usually requires more than 20 ensemble members (e.g., Miyazawa et al. 2012; Xu et
59	al. 2013: Xu and Oev 2014).

60 We adopt a computationally inexpensive Ensemble Optimal Interpolation (EnOI) 61 approach in this study. EnOI runs only a single model member every time and has no risk of ensemble collapse (Pan et al. 2014). Its analysis formula is identical to that of 62 the Local Ensemble Transform Kalman Filter (LETKF, refer to Miyazawa et al. 2012 63 64 for details), except that its background error covariance is advanced from a prescribed 65 100 static ensemble members instead of a flow-dependent ensemble. In general, EnOI 66 many attractive characteristics such as multivariate assimilation and has inhomogeneous and anisotropic covariance. In addition, the static ensembles for EnOI 67 can be time-dependent (e.g., Oke et al. 2005, 2013; Fu et al. 2008) or seasonally 68 varying. Consequently, EnOI has been used in many operational ocean forecast 69 70 systems such as BODAS (Bluelink Ocean Data Assimilation System) at the Bureau of 71 Meteorology in Australia (Oke et al. 2013).

A new generation of climate forecast system at the Beijing Climate Center is under development (Beijing Climate Center Climate System Model, BCC_CSM1.1) (e.g., Wu et al. 2010; Wu et al. 2014). BCC_CSM1.1 is a fully coupled climate system consisting of atmosphere, land, ocean, and sea ice components. The primary objective in regard to developing BCC_CSM1.1 is to generate a high-quality





reanalysis dataset and improve predictions from sub-seasonal, seasonal, and up to
decadal time scales. The development of a data assimilation system is crucial for this
objective. One purpose of this study is to introduce the new ocean data assimilation
system that is going to be adopted in the BCC_CSM1.1.

81 The other purpose of this study is to investigate the impact of data assimilation 82 of various available observations on seasonal forecasts. For this purpose, the individual and combined contributions of sea surface satellite data to forecasting, such 83 84 as sea surface temperature (SST), sea surface height (SSH), sea surface salinity (SSS), 85 and temperature and salinity (T/S) profiles were evaluated. Model generated SST, 86 SSH, and SSS were taken as pseudo-observations of satellites, and T/S profiles close 87 to locations of Argo floats were chosen to represent pseudo-observations of Argo. The satellite sea surface data and Argo float data are major observational data sources 88 89 nowadays, with global coverage and widespread availability in most of the ocean 90 observing network. The satellite SST observations have been widely used in ocean 91 assimilation applications since SST is a key geophysical variable in air-sea exchanges 92 of heat (e.g., Tang et al. 2004). The SSS plays an important role in surface mixed 93 layer dynamics, water mass formation, and global ocean circulation (Vernieres et al., 94 2014). The satellite observations of SSS have been available since the first satellite 95 was launched by the European Space Agency (ESA) to monitor SSS (Boutin et al. 96 2016). Global SSH data from TOPEX/Poseidon altimeters have been available since 97 October 1992. The dynamic topography depicts the surface geostrophic flow field.





98	Furthermore, large-scale variability of SSH has close connections with climate signals.
99	For example, assimilation of SSH contributes to better understanding of the tropical
100	Pacific variability (Carton et al. 2008) and El Niño forecasting (Ji et al. 2000). One
101	major concern in assimilating SSH is how to project the surface information
102	downward to subsurface quantities (Fu et al. 2011). At present, SSH data are
103	assimilated into ocean models either by developing a statistical relationship between
104	SSH and subsurface temperature/salinity (Behringer et al. 1998; Yan et al. 2004) or
105	by the inherent multivariate relation derived from the ensembles by using some
106	ensemble-based data assimilation methods (Oke et al. 2008; Zheng et al. 2015). T/S
107	profiles improve the representation of seawater density, which dictates water mass. In
108	addition, T profiles have a direct influence on ocean heat content.
109	EnOI is implemented in a global ocean model (about 110 km in the horizontal)
110	based on MOM4.0, which is the ocean model used in BCC_CSM1.1. An idealized
111	twin experiment was carried out to test the assimilation and prediction system in a
112	situation where the "truth" was known. The "observed" SST, SSH, SSS, and T/S were
113	derived from free mode simulations and considered as the "truth." This paper is

derived from free mode simulations and considered as the "truth." This paper is organized as follows. Section 2 presents a brief introduction of the EnOI data assimilation system and experimental setup. The assimilation and forecast results of all experiments are presented in Section 3. The discussion and summary are given in Section 4.





119 2. The EnOI assimilation system and twin-experiment setup

120 2.1 EnOI

EnOI is a simplified form of EnKF, which uses a stationary historical ensemble of model states to represent the background covariance matrix instead of time-dependent ensembles for EnKF. Consequently, it is more computationally efficient than EnKF, but is still multivariate and three-dimensional. In this study, we derive EnOI based on LETKF, an advanced version of EnKF (Miyoshi et al. 2010).

126 Here, the calculation equations of EnOI are given below (Oke et al. 2013).

127
$$\varphi^{a} = \varphi^{f} + \rho A' w^{a} \tag{1}$$

where φ^a is an m-dimensional vector representing the model analysis, φ^f is an 128 129 m-dimensional vector representing the model forecast, and ρ is a scaling factor used to represent the instantaneous forecast error variance, which is usually less than the 130 historical error variance over a long time period. ρ is in the range between 0 and 1, 131 and it was set to 0.5 here by tuning the assimilation results. A is the historical 132 ensemble composed of model states, and A' is the centered historical ensemble (i.e., 133 $A' = A - \overline{A}$. $A = \sum_{1}^{N} \frac{A_i}{N}$, and N represents the number of the historical ensembles. A 134 (A', A) is an m \times N matrix. w^a is an N-dimensional vector calculated from the 135 observational data, model forecast, and historical ensemble model simulations; it can 136 137 be computed as follows:

138
$$w^{a} = A'(\rho H A' A'^{T} H^{T} + (N-1)R)^{-1} (d - H \varphi^{f})$$
(2)





- where d represents the measurements, H is the measurement operator that interpolates
 the model space into the observational space, and R is the measurement error
 covariance.
- Localized use of observation data is important in the method. The primary benefit of localization is to increase the rank of the forecast covariance, thus resulting in analysis fields that fit well with the observations (Oke et al. 2007). Localization is implemented explicitly in consideration of observational data from a region surrounding the target model grids. We define two localized scale parameters following Miyoshi et al. (2010) and Miyazawa et al. (2012):

148
$$Dist_{zero} = \sigma_{obs} * \sqrt{10/3} * 2$$
, $Dist_{zerov} = \sigma_{obsv} * \sqrt{10/3} * 2$ (3)

149 where σ_{obs} (the number of surrounding grids) and σ_{obsv} (meters) are the horizontal 150 and vertical localization scales, respectively. The localization scale is chosen to 151 correspond to the distance at which the Gaussian function drops to $e^{-0.5}$ (Miyoshi et 152 al. 2010). Observational data far from the target grid with horizontal distances larger 153 than $Dist_{zero}$ or vertical distances larger than $Dist_{zerov}$ are not used. A factor, 154 $\exp(0.5 * ((\frac{Dist}{Dist_{obs}})^2 + (\frac{Dist}{Dist_{obsv}})^2))$, is multiplied to enhance observational errors of 155 data far from the target grid (Miyazawa et al. 2012). The resulting localization scales

- are approximately 110 km and 2000 m in the horizontal and vertical, respectively.
- 157 2.2 The global ocean model

We have implemented the EnOI algorithm in MOM4, which was originallydeveloped at the Geophysical Fluid Dynamics Laboratory (Griffies et al. 2003). The





160 model covers the global ocean with a horizontal resolution of 1° and at 50 vertical levels. In the meridional direction, the resolution increases to 1/3° within 10° of the 161 equator, and it smoothly reduces down to 1 ° poleward of 30 °. To avoid a singularity 162 163 at the North Pole, tripolar grids are adopted (Griffies et al. 2005). The physical parameterization schemes used in the simulation include the K-profile 164 165 parameterization vertical mixing scheme, the isopycnal tracer mixing and diffusion, and the Laplace horizontal friction scheme, etc., the same as described in Griffies et al. 166 167 (2005).

168 The model is driven by wind stress and heat fluxes estimated from 6-hourly 169 atmospheric variables obtained from the National Centers for Environmental 170 Prediction National Center for Atmospheric Research Reanalysis I dataset (NCEP/NCAR, http://www.esrl.noaa.gov/psd/). The climatological river runoff 171 (http://www.cgd.ucar.edu/cas/catalog/) is specified at the model coastlines. The 172 surface temperature and salinity are relaxed to World Ocean Atlas (WOA09) monthly 173 174 climatology (http://coastwatch.pfeg.noaa.gov/erddap/griddap/nodcWoa09mon1t.html), 175 with restoring time scales of 90 and 120 days, respectively. Tidal forcing is not included. Sea ice is simulated with the Sea Ice Simulator (SIS) (Griffies et al. 2011). 176 In this study, the model was first spun up from 1948 to 2000, and a statistically 177 178 quasi-equilibrium ocean field was established. This run was then continued from 179 January 1, 1990 through 2009. One hundred ensemble members for estimates of the





- 180 background error covariance were sampled from the free-run simulation at time
- 181 intervals of 25 days from January 1, 1995 to December 31, 2009.

182 2.3 Twin-experiment setup

An experiment (denoted as TRU), which was allowed to freely run from January 1, 2005 to December 31, 2006, was designed to produce pseudo-observations and make comparisons with the assimilative analysis and model predictions. Another free model run (denoted as CTR), which was the same as TRU but initialized on a start date of June 1, 1990, was used to create large biases for initial conditions.

188 The sea surface pseudo-observations including SST, SSH, and SSS were selected 189 every three points in the model grids meridionally and zonally. The pseudo T/S 190 profiles were selected at model grids that were as close to the locations of Argo floats on June 1, 2005 as possible (Fig. 1). This time was chosen because it was the median 191 192 time of the assimilation period (January 1, 2005-December 31, 2005). Considering 193 the slow drifts of most Argo floats, the locations of pseudo T/S profiles did not change with time because of the relatively low model resolution of about $1 \circ \times 1 \circ$. The 194 195 vertical levels are set as the same as the model levels. The altimeter SSH errors 196 generally vary from 1 cm to 4 cm (Chambers et al. 2003), and thus, the pseudo SSH error was specified as 3 cm. The SST error was set to be 0.3 °C according to Guan and 197 198 Kawamura (2004). The SSS error was set to be 0.1 PSU in consideration of the rapid 199 development in inversion algorithms for satellite salinity (Peng et al. 2016). Similarly,





- 200 for T/S profiles, the temperature and salinity errors were prescribed to be the same as
- 201 the SST error and the SSS error, respectively.
- 202 Assimilation experiments, E01–E07 initialized as CTR, assimilated 203 pseudo-observations from January 1, 2005 to December 31, 2005 (Table 1). E01 assimilated SST only, E02 assimilated SSH only, E03 assimilated both SST and SSH, 204 E04 assimilated SSS, E05 assimilated all the SST, SSH, and SSS data, E06 205 assimilated T and S, and E07 assimilated all the variables. Then, we conducted seven 206 12-month test forecasts starting from January 1, 2006 corresponding to the seven 207 208 analyses. By comparing the model states from CTR, E01-E07 against the known 209 "true" states, we were able to investigate the performance of the assimilation system 210 and forecast skills.

211

212 **3. Results**

213 3.1 Assimilation performance measures

To evaluate the performance of data assimilation experiments, we examined the domain-averaged root-mean-square error (RMSE) of SST, SSH, SSS, temperature, and salinity in the upper ocean (0–500 m) and the deep ocean (500–1500 m) with respect to the TRU experiment from months 1 to 12 (Fig. 2). All assimilative experiments generally showed improvements over CTR, but the improvements varied among different experiments. The SST RMSEs of E02 and E04 were comparable with that of CTR, while the other assimilation experiments approximately reduced the





221	RMSEs by half (Fig. 2a). These results indicate that assimilation of SSH and SSS
222	alone do not contribute to the SST analysis in the system. The SSS RMSEs of E04,
223	E05, and E07 were reduced by about 80% compared to CTR (Fig. 2b). The RMSEs of
224	E03 and E06 were reduced by about 30%. E01 and E02 only slightly improved SSS
225	estimates. So experiments with SSS assimilation improve the SSS the most, while
226	assimilating T/S profiles alone (E06) or SSH and SST (E03) can only improve SSS to
227	a limited extent. For SSH, E02, E03, E05, and E07, the RMSE of SSH was reduced
228	by about 82%, thus indicating the importance of the SSH assimilation (Fig. 2c). The
229	T/S profile assimilation (E06) reduced the SSH RMSE by about half. SST (E01) and
230	SSS (E04) only improved the SSH by about 20%. For the analysis of temperature and
231	salinity at depth, all experiments showed improvements (Fig. 2d-g). E07 had the
232	smallest RMSEs among all experiments. The RMSEs obtained when assimilating SST
233	alone (E01) were larger than those obtained when assimilating T/S profiles (E06).
234	Similarly, the RMSEs obtained when assimilating SSS alone (E04) were larger than
235	those obtained when assimilating T/S profiles (E06). These results demonstrate the
236	importance of the assimilation of T/S profiles in the global data assimilation system.

237 3.2 Predictions

The impacts of data assimilation on seasonal forecasts were investigated by
conducting a 12-month forecast initialized from restart files produced by CTR, E01–
E07. The forcing was identical for all cases.

241 The time series of spatial RMSEs for temperature and salinity among all forecast





242	experiments and TRU are shown in Fig. 3. All RMSEs from the forecasts initialized
243	from the assimilated runs were smaller than that from CTR. The E07 forecast,
244	initialized from joint assimilation of SST, SSS, SSH, and T/S profiles, had the
245	smallest RMSEs for temperature and salinity compared to the others. Figure 3 also
246	shows the "persistence" curves (black lines) based on TRU, i.e., the temperature,
247	salinity, and SSH from TRU (January 1, 2005–December 31, 2005) were assumed as
248	"repeat" for the subsequent 12 months. The model forecasts from E03, E05, and E07
249	beat the persistence in the upper ocean (Fig. 3a-d,f), while the other experiments
250	showed some deficiencies, such as E01 for the SSS forecast (Fig. 3b) and E04 for the
251	SSH forecast (Fig. 3c), etc. In contrast, in deep water (500-1500 m), the persistence
252	beat the model forecasts because of the large bias from the initialization starting on
253	June 1 st in the CTR run and all assimilation runs (Fig. 3e&g). These results
254	demonstrate that the deep ocean bias cannot be completely corrected after one-year
255	assimilations, though improvements are possible.

In addition to the aforementioned temporal variability, the spatial variability of ocean predictions was evaluated in different experiments as well. The SST and surface currents were compared at first. Ocean heat content (OHC) and mixed layer depth (MLD) were used to examine the subsurface predictions. Besides, the values of the Ni ño 3.4 index were compared too, because it is an important climate signal in the tropical Pacific.

262 <u>SST</u>





263	Figure 4 shows the spatial distribution of the RMSE for SST from CTR and the
264	differences with respect to E01-E07 over the prediction period (months 13-24).
265	Reductions of the RMSE were generally found in all experiments in regions where the
266	RMSE was relatively high in CTR, such as the tropical eastern Pacific, the subarctic,
267	and the Southern Ocean. The domain-averaged RMSE from E07, which was about
268	0.11 °C, was the smallest. Interestingly, the experiment initialized from the
269	assimilation of T/S profiles (E06) produced a comparable RMSE to the one from the
270	experiment initialized from the joint assimilation of all surface data (E05). The values
271	of the domain-averaged RMSEs from these two experiments were much smaller than
272	those of E01, E02, and E04. These results indicate the importance of multivariate
273	assimilation on initial conditions, and subsequently the forecasting.
274	Noticeably, in the Southern Ocean south of Africa ([0 E-60 E], [48 S-60 S],
275	the black box in Fig. 4), the RMSEs for SST were much larger in E01, E02, and E03
276	than that in CTR. To explore the reasons for the high RMSEs, we examined the time
277	evolution of vertical profiles of temperature averaged over the high RMSE region.
278	Figure 5 shows the vertical profiles of temperature and the corresponding RMSEs in
279	January and September from all experiments. In January, SST estimates in E01, E03,
280	E05, and E07 were much better than that in CTR (Fig. 5a,c). Conversely, in the
281	subsurface layer (50–150 m), the values of RMSE in E01 and E03 were about 0.3 $\ensuremath{\mathbb{C}}$
282	larger than that in the CTR. In September, a thick mixed layer about 100 m deep
283	developed after the austral winter (Fig. 5b,d). A pre-existing subsurface bias of





284	temperature in E01, E03, and E05 emerged near the surface due to the winter mixing.
285	Since temperatures in both the surface and subsurface in E02 and E04 were more
286	biased than those in CTR, the values of RMSE remained relative high. On the other
287	hand, the temperatures in deep ocean waters (below ~ 200 m) were improved in all
288	experiments compared to the CTR. Thus, the high RMSE found in the black box of
289	Fig. 4 mainly developed as a result of the large temperature bias in the subsurface.
290	The subsurface bias probably came from inaccurate estimates of the background error
291	covariance in the multi-fronts Antarctic circumpolar region during the surface data
292	assimilation.

293 Ocean surface currents

294 Large-scale ocean circulation is primarily geostrophic a few degrees away from 295 the equator. Because of the availability of long-term satellite altimeter data, 296 geostrophic parts of any model generated currents can be easily evaluated by using altimetry data. It is hence interesting to assess all forecasting experiments in this 297 regard. Figure 6 compares the RMSEs of the predicted SSH from all experiments. 298 299 Compared to CTR, significant improvements of SSH were found in E02, E03, E05, 300 E06, and E07. Similar to the SST RMSE reduction, the large reduction primarily occurred in regions where the RMSE was large in CTR. However, E01 and E04 301 302 showed almost no reduction, thus indicating that assimilation of SST or SSS alone cannot largely improve SSH forecasting. 303





304	The RMSEs of the predicted surface current speed from all experiments are
305	compared in Fig. 7. The largest reduction of the overall RMSE was observed in E07.
306	E02, E03, and E05 showed clear improvements near the tropical Pacific and the
307	western boundary current regions such as the Gulf Stream, the Kuroshio extension,
308	and so on. Comparisons of E01-E05 revealed that SSH assimilation was the dominant
309	factor accounting for the forecast improvements. In contrast, major improvements in
310	E06 were observed in the tropical regions, and these were more prominent than those
311	in E05. These results indicate that the ocean surface currents in the tropics are better
312	predicted when initial conditions are produced by assimilating T/S profiles, while
313	surface data assimilation becomes more important at higher latitudes, particularly near
314	the western boundary currents. This can be attributed to the dominant effects of SSH
315	assimilation on geostrophic parts of surface currents away from the equator.

316 <u>*OHC*</u>

Ocean heat content is an important variable in climate studies, and it reflects the 317 318 internal energy that the ocean has. To assess the standalone and joint effects of assimilation of surface data and T/S profiles on ocean predictions, we explored the 319 320 upper 700 m OHC estimates from all experiments. Figure 8 shows the global 321 distribution of the time-averaged upper 700 m OHC per unit area from all forecast experiments relative to that from the "truth." E07 had the smallest RMSE for OHC 322 compared to TRU (Fig. 8h). The RMSE in E06 was about 1.2×10^8 J m⁻² larger than 323 that in E05, and this was primarily caused by the large bias in the subpolar regions 324





325	(Fig. 8f,g), where the T/S profiles were relatively sparse compared to the gridded
326	satellite surface data. In the lower latitudes, the difference between E06 and TRU was
327	smaller than that in E05. Interestingly, none of the standalone assimilation of surface
328	data experiments (E01, E02, or E04) significantly improved the OHC estimates (Fig.
329	8b,c,e). The joint assimilation of SST and SSH had already reduced the deficiency of
330	OHC predictions to a large extent (Fig. 8d). When SSS was assimilated, the reduction
331	was more significant (Fig. 8f). Thus, both surface variables and T/S profiles are
332	important for OHC predictions.

333 <u>MLD</u>

334 Mixed layer depth is one of the most important quantities in the upper ocean. 335 Here, we define MLD following Breugem et al. (2008) as the depth (z) at which the potential density is $\sigma_z = \sigma(S_{10m}, \theta_{10m} - 0.2)$, where θ_{10m} and S_{10m} are the potential 336 temperature and salinity at a depth of 10 m, respectively, and σ is the potential density. 337 We examined the MLD in the tropical Pacific since its variability is closely related to 338 the El Niño Southern Oscillation (ENSO). Figure 9 shows the spatial distribution of 339 340 differences of the time-averaged MLD (over months 13-24) from all experiments relative to TRU in the tropical Pacific. A weak Central Pacific (CP) El Niño appeared 341 in TRU. Compared to CTR, improvements in MLD were seen in all seven 342 343 experiments, but the improvements were most significant in E06 and E07 (Fig. 9g,h). 344 Noticeably, the differences of MLD from E02 were much smaller than those from 345 E01, which suggests that assimilation of SSH instead of SST is important for





improving MLD forecasting. E06 performed better than E05 because the assimilated T/S profiles had a direct influence on the MLD of initial conditions used for forecasting (Fig. 9f,g). Since the surface variables are influenced by intense air–sea interactions, there are thus more uncertainties when calculating the background error covariance. Consequently, the deficiency of initial conditions resulting from the assimilation of surface data is then inherited in the forecast.

352 <u>Niño 3.4</u>

353 Figure 10 compares the Niño 3.4 index from all experiments. Over the 354 assimilation period, the values of the index from all experiments including CTR 355 gradually approached towards the "truth", though relatively large deficiencies still 356 existed in some experiments such as CTR and E02 (Fig. 10a). It is interesting to note that E04, which involved assimilating SSS, significantly improved the Niño 3.4 data. 357 358 Over the prediction period, the values of the index started to diversify after four 359 months (Fig. 10b). CTR and E04 did not produce a large positive Niño 3.4 index at 360 the end of the prediction period, thus suggesting that standalone assimilation of SSS 361 cannot well capture an El Niño event one year in advance. Conversely, E02 produced 362 a too strong Ni ño 3.4 index, thus implying that standalone assimilation of SSH might 363 overestimate an incoming El Niño event. E03, E05, and E07 produced the best 364 estimates of Niño 3.4. These findings tell us that the joint assimilation of surface 365 variables and T/S profiles are crucial for ENSO predictions. The newly developed 366 system can well predict an El Niño event one year ahead.





367	Equatorial long wave propagations are critical to ENSO development. According
368	to Boulanger and Menkes (1995), the coefficient amplitude of the SSH and surface
369	zonal current represents the projection of the ocean variations onto these equatorial
370	long waves (Kelvin waves and Rossby waves). In this study, we examined the
371	prediction of wave propagation at a given longitude and time. Figure 11 shows the
372	coefficients for the long waves, which were computed from SSH and surface current
373	anomalies of TRU, and the differences from CTR and E01-07 relative to TRU.
374	Eastward propagation of Kelvin waves and westward propagation of Rossby waves
375	clearly appeared (Fig. 11i), and subsequently contributed to the occurrence of the CP
376	El Niño (Fig. 9i). E07 produced the best estimates of the wave propagation (Fig. 11h).
377	The second best estimate came from E05 (Fig. 11f). Comparing E03 and E05, the
378	findings suggest that assimilation of SSS can improve the prediction of wave
379	propagation. Besides, the prediction initialized from joint assimilation of surface data
380	(E05) slightly outperformed that from assimilation of T/S profiles (E06) in terms of
381	ENSO predictions.

382

383 4. Discussion and conclusion

In this study, we applied EnOI with a global ocean model (MOM4.0) to estimate three-dimensional global ocean states when assimilating various variables, e.g., SST, SSH, SSS, and T/S profiles, in an idealized twin-experiment framework. Tests were conducted step-by-step to explore the sensitivity of estimates to each variable. The





- 388 results were compared against quantities from the TRU experiment to assess the
- 389 analysis and forecasting skills. The major findings are as follows:
- 390
- 391 1. Data assimilation generally improved all investigated quantities; assimilation of all
- 392 the variables together gave more improved results than assimilating them separately.
- 393 2. A 12-month test forecast showed that initializations from E07 produced
- 394 significantly improved forecasts compared to the others.
- 395 3. The SST forecasts initialized from joint assimilation of surface data (E03 and E05)
- 396 produced comparable global averaged RMSEs to that from assimilation of T/S
- 397 profiles (E06), but the assimilation of T/S profiles should not be overlooked because
- 398 subsurface deficiencies can develop into the surface during forecasts, particularly for
- 399 highly nonlinear flow regions.
- 400 4. The ocean surface currents in the tropics were better predicted when initial
 401 conditions were produced by assimilating T/S profiles (E06), while surface data
 402 assimilation (E05) became more important at higher latitudes, particularly near the
 403 western boundary currents.
- 5. The development of a CP El Niño was well predicted in E05 and E07, thus
 indicating that it is important to jointly assimilate SST, SSH, and SSS for ENSO
 predictions.
- 407





408	To apply the data assimilation method in actual operations, we can decrease the
409	forecast run number to 1 in LETKF. This time evolving run is combined with 100
410	static ensemble members to build the background error covariance for data
411	assimilation. We found that increasing the number of time evolving ensemble
412	members from 1 to 5 was not effective for obtaining more accurate ensemble
413	covariance using the LETKF assimilation scheme. If the number increases to 20, the
414	covariance is more accurate. This has been demonstrated in many previous studies
415	such as Miyazawa et al. (2012), Xu et al. (2013), and Xu and Oey (2014). However,
416	the computer costs of more than 10 ensemble numbers limits the ability of this
417	approach in operational applications.
418	The inclusion of large errors in the initial conditions was aimed at testing the
419	ability of the ocean assimilation system to correct the errors. We also conducted a
420	series of experiments similar to the above experiments but initialized from January 5,
421	1990 to reduce initial errors. Note that TRU was initialized starting from January 1,
422	1990. The results showed improvements of the analysis and forecasts as well, though
423	not as significant as those from the experiments listed in Table 1.
424	The newly developed system was tested in a twin-experiment framework. This
425	approach allowed for extensive tests of system accuracy, and such an approach has
426	been widely used in data assimilation studies (e.g., Counillon et al. 2014; Zhou et al.
427	2016). Even though the results were encouraging, our plan is to conduct a
428	comprehensive test in a realistic framework before the system is put into operation.





429	Finally, coupled	assimilation	with ice	properties	and atm	ospheric	fluxes l	has been

- 430 shown to be advantageous in climate system analyses (e.g., Zhang et al. 2009; Zheng
- 431 and Zhu 2010). Thus, we will consider the assimilation of those variables in future
- 432 studies.
- 433

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				T/S	Assimilation	Free run
	SST	SSH	SSS	profiles	(months)	(months)
CTR	/	/	/	/	1-12	13–24
	Yes				1-12	13–24
E01		/	/	/		
		Yes			1–12	13–24
E02	/		/	/		
					1–12	13–24
E03	Yes	Yes	/	/		
					1-12	13-24
E04	/	/	Yes	/		
					1-12	13-24
E05	Yes	Yes	Yes	/		-
					1-12	13-24
E06	/	/	/	Yes		
					1-12	13-24
E07	Yes	Yes	Yes	Yes		10 21

541 Table 1. Experimental design.

542







544

Fig. 1. Locations of Argo floats on June 1, 2005, which were used to producepseudo-observations of T/S profiles.







Fig. 2. Time series of domain-averaged RMSEs for (a) SST, (b) SSS, (c) SSH, (d)
temperature in the upper 500 m, (e) temperature from 500 m to 1500 m, (f) salinity in
the upper 500 m, and (g) salinity from 500 m to 1500 m from all the experiments
(CTR and E01–E07) over the assimilation period (months 1–12). Temperature is in
degrees Celsius, SSH is in meters, and salinity is in PSU.







555

Fig. 3. Time series of domain-averaged RMSEs for (a) SST, (b) SSS, (c) SSH, (d)
temperature in the upper 500 m, (e) temperature from 500 m to 1500 m, (f) salinity in
the upper 500 m, and (g) salinity from 500 m to 1500 m from all the experiments
(CTR and E01–E07) over the prediction period (months 13–24). The black lines
denote the persistence. Temperature is in degrees Celsius, SSH is in meters, and
salinity is in PSU.







Fig. 4. Global distribution of the RMSE for SST from CTR, and the RMSE differences between E01–E07 and CTR from months 13 to 24. Negative values mean that the RMSE from the assimilation runs is smaller than that from CTR. The black box (in [0 £–60 £], [48 \$S–60 \$S]) indicates an area with enhanced RMSE. The domain-averaged RMSE is shown on the top left of each panel in degrees Celsius.







Fig. 5. Vertical profiles of the box-averaged temperature (°C) in all experiments (a, b)
and the RMSE for temperature (c, d) in January and September (in [0 °E-60 °E],
[48 °S-60 °S]) derived from 8 experiments along with the TRU experiment.







576 Fig. 6. As in Fig. 4, but for SSH.

577







578

579 Fig. 7. As in Fig. 4, but for surface current speed.







618 Fig. 8. Global distribution of the time-averaged upper 700 m ocean heat content 619 (OHC) per unit area from the "truth" experiment from months 13 to 24 and the 620 differences of the mean values between the forecast experiments (CTR, E01–E07) 621 and the "truth." The domain-averaged RMSE of OHC per unit area is shown on the 622 top left of each panel in J m⁻².







Fig. 9. The time-averaged mixed layer depth (MLD) in the tropical Pacific from TRU
and the differences between all prediction experiments (CTR, E01–E07) and TRU
from months 13 to 24. The domain-averaged RMSE of MLD is shown on the top left
of each panel in meter.









Fig. 10. Comparison of the estimated Ni ño 3.4 from all experiments from months 1 to

666 12 (left) and from months 13 to 24 (right).







668

Fig. 11. Coefficients of the equatorial waves for (i) TRU and the difference between
all experiments including (a) CTR and (b–h) E01–E07 and TRU. The coefficients
are nondimensional and computed from the surface zonal current and the sea surface
height anomalies.