

Interactive comment on “Formulation of an ocean model for global climate simulations” by S. M. Griffies et al.

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- Horizontal friction

The transition in OM3.0 between the tropical viscosity to middle latitudes is large. Our motivation for using this large middle latitude viscosity was, unfortunately, due to problems with the atmospheric model's winds. We describe this issue in the manuscript. It represents one of the least satisfying aspect of OM3.0. We tried unsuccessfully a few times to reduce the friction, but had problems with drift in the North Atlantic heat transport.

- Appendix: Is is needed?

The appendix was added to the manuscript in response comments from informal reviewers. Its purpose is to summarize the model equations and numerical methods forming the basis for the MOM4.0 code. This summary is perhaps not as necessary for those already familiar with MOM. Nonetheless, we feel it nec-

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essary to provide details of the model equations, general assumptions, and brief description of methods not covered in the main text. We point to many of the equations in the appendix throughout the main text. Absent this appendix, much of its material would need to be incorporated into the main text. Separating the material into an appendix allows for more streamlined discussions in the main text. We therefore feel that this appendix serves the paper well.

- Advection metric frequency

The so-called *advective metric frequency* \mathcal{M} appears in the thickness weighted velocity equation as $[\partial_t + (\mathcal{M} + f) \hat{z} \times] (h u)$. It therefore has the *same* dimensions as the Coriolis parameter f , and so can be measured in cycles per second if one chooses.

As detailed in Section 4.4.1 of [Griffies(2004)], \mathcal{M} arises when expressing the material time derivative of velocity on a sphere. Two terms arise in this derivative: the familiar divergence term also occurring in flat space with Cartesian coordinates, plus the *advective metric frequency*. Hence, our choice for the name of this term is motivated because it (1) is associated with the advection of velocity, (2) arises from velocity advection on a sphere, (3) has units of a frequency. Note that when choosing spherical coordinates, this term takes the form

$$\mathcal{M} = (u/R) \tan \phi. \quad (1)$$

This is the form that appears in most treatments of the primitive ocean equations (e.g., [Bryan(1969)]). We chose to be more general, however, since MOM4 is written using generalized orthogonal coordinates.

- Stability of the Coriolis force

We agree with the reviewer's analysis. We have corrected our discussion, and raised the issues of phase and amplitude errors associated with the trapezoidal or semi-implicit treatment of the Coriolis force.

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