Ocean Sci. Discuss., 11, 2119–2172, 2014 www.ocean-sci-discuss.net/11/2119/2014/ doi:10.5194/osd-11-2119-2014 © Author(s) 2014. CC Attribution 3.0 License.



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Modelling of underwater light fields in turbid and eutrophic waters: application and validation with experimental data

B. Sundarabalan and P. Shanmugam

Ocean Optics and Imaging Laboratory, Department of Ocean Engineering, Indian Institute of Technology Madras, Chennai-600036, India

Received: 18 August 2014 - Accepted: 26 August 2014 - Published: 15 September 2014

Correspondence to: P. Shanmugam (pshanmugam@iitm.ac.in)

Published by Copernicus Publications on behalf of the European Geosciences Union.





Abstract

A reliable radiative transfer model is an essential and indispensable tool for understanding of the radiative transfer processes in homogenous and layered waters, analyzing measurements made by radiance sensors and developing remote sensing algorithms

- to derive meaningful physical quantities and biogeochemical variables in turbid and productive coastal waters. Existing radiative transfer models have been designed to be applicable to either homogenous waters or inhomogeneous waters. To overcome such constraints associated with these models, this study presents a radiative transfer model that treats a homogenous layer as a diffuse part and an inhomogeneous layer as
- ¹⁰ a direct part in the water column and combines these two parts appropriately in order to generate more reliable underwater light field data such as upwelling radiance (L_u), downwelling irradiance (E_d) and upwelling irradiance (E_u). The diffuse model assumes the inherent optical properties (IOPs) to be vertically continuous and the light fields to exponentially decrease with the depth, whereas the direct part considers the water
- ¹⁵ column to be vertically inhomogeneous (layer-by-layer phenomena) with the vertically varying phase function. The surface and bottom boundary conditions, source function due to chlorophyll and solar incident geometry are also included in the present RT model. The performance of this model is assessed in a variety of waters (clear, turbid and eutrophic) using the measured radiometric data. The present model shows an ad-
- ²⁰ vantage in terms of producing accurate L_u , E_d and E_u profiles (in spatial domain) in different waters determined by both homogenous and inhomogeneous conditions. The feasibility of predicting these underwater light fields based on the remotely estimated IOP data is also examined using the present RT model. For this application, vertical profiles of the water constituents and IOPs are estimated by empirical models based
- ²⁵ on our in-situ data. The present RT model generates L_u , E_d and E_u spectra closely consistent with the measured data. These results lead to a conclusion that the present RT model is a viable alternative to existing RT models and has an important implication for remote sensing of optically complex waters.





1 Introduction

Knowledge of the transmission and distribution of light fields within the water body is essential for the solution of many problems in optical remote sensing, underwater visibility, underwater imaging, underwater communication and naval operations. In the past decades, several radiative transfer (RT) models have been developed to compute the reflectance and transmittance of direct and diffuse solar fluxes at the ocean surface and in the water column. For instance, Kirk (1981) presented the Monte-Carlo simulation scheme for studying the radiative transfer processes in the ocean and other natural waters. Stamnes et al. (1988) summarized an advanced and thoroughly documented discrete ordinate method (DISORT) for time-independent radiative transfer calculations in vertically inhomogeneous, non-isothermal, plane-parallel media. Mobley (1994) developed the Hydrolight software, which is a radiative transfer numerical model based on the invariant imbedding technique that computes spectral radiance distributions within and leaving the natural water bodies. Haltrin developed a method for estimating the

- ¹⁵ underwater light field parameters in the homogeneous water column illuminated by the direct sun light and sky light (Haltrin and Kattawar, 1993; Haltrin, 1998a, b). Lee et al. (2007) developed a radiative transfer model for a coupled atmosphere–ocean system using the analytic four-stream approximation. Hollstein and Fischer (2012) provided radiative transfer solutions for coupled atmosphere–ocean systems using the
- ²⁰ matrix operator technique. These RT models developed based on numerical as well as analytical solutions perform well in clear oceanic waters but have limitations in turbid coastal and productive waters. The key problems associated with some of the above models include the assumption of flat or randomly chosen slope of the sea surface, the treatment of material reflectance instead of the effective bottom reflectance (tak-
- ing into account the material reflectance and configuration of the seabed), the constant phase function along the depth and the inadequate source function (especially for turbid and productive waters often "optically shallow", "vertically stratified", or "vertically mixed") which introduce significant errors in the simulated underwater light fields



(Sundarabalan et al., 2013). Conversely, the radiative transfer models developed for a inhomogeneous medium does not account for diffuse radiance in the water column, where the influence of IOPs from a particular (adjacent) layer is not the only factor affecting underwater light fields in that layer but the subsequent layers (with non-uniform

- IOPs) would have potential contributions to modifying the underwater light field environment. Moreover, the assumption of the homogenous water column in some of the RT models is not valid in many coastal waters where the water constituents would vary with depth (e.g., an increasing trend of turbidity with depth in many coastal regions). Thus, a reliable RT model is needed accounting for the vertically varying IOPs and
 treating the surface and bottom boundary conditions adequately in order to provide
 - accurate underwater light field data in turbid coastal waters.

Ocean colour data provided by modern days sensors (e.g., NASA's "SeaWiFS" on board its SeaStar satellite and "MODIS" on board its Aqua satellite, ESA's MERIS' on board its Envisat satellite, ISRO's "OCM" on board its IRS satellite; and more recently

- KARI's "GOCI" onboard its COMS satellite) are a vital resource for a wide variety of operational forecasting and oceanographic research, and related applications. With the advent of these new sensors, the prospects of better algorithms to enable the interpretation of ocean colour in Case 2 waters have particularly improved vastly. Some of the potential applications of these sensors include monitoring and assessment of the
- spatial and temporal variability of algal blooms (instrumental in characterizing variability of marine ecosystems and is a key tool for research into how marine ecosystems respond to climate change and anthropogenic perturbations), coastal marine pollution, river plumes, global carbon budgets, ocean radiant heat budget and climate change impacts. Many of these applications can be achieved by estimating IOPs from the remote
- ²⁵ sensing data, since light transmission in the water column is determined by these properties that depend mainly on the contents of chlorophyll (Chl), suspended sediments (SS), and coloured dissolved organic matter (CDOM). In most oceanic waters IOPs are determined primarily by phytoplankton and its associated detrital matter, which in turn determine the distribution and spectral quality of the underwater light fields (Morel,





1988; Hoepffner and Sathyendranath, 1992). Though several inversion models have been developed to estimate IOPs from remote sensing data, they are often reported to yield large uncertainties in turbid coastal waters. Similar problems also exist with the retrieval of the water constituents' concentrations from satellite observations in these
⁵ waters (O'Reilly et al., 1998, 2000; Shanmugam, 2011). The errors of more than 10% in retrieval of IOPs (Stramski, 2001) and even much higher (20 times higher than mea-

surements) in retrieval of chlorophyll are reported (Wozniak and Stramski, 2004). The surface chlorophyll concentration estimated from satellite ocean colour data is

used as an important parameter for reconstruction of its vertical profile in the water col-

- ¹⁰ umn (Morel, 1988; Platt and Sathyendranath, 1988; Sathyendranath and Platt, 1988; Morel and Berthon, 1989; Antoine et al., 1996; Uitz et al., 2006). The generalized Gaussian profile (Lewis et al., 1983) is used to predict the average dimensionless chlorophyll profile, superimposed onto a constant background concentration. The shape of the chlorophyll profiles directly depends on the subsurface chlorophyll maximum (SCM)
- [Chl]_{max} and depth of chlorophyll maximum (DCM) Z_{max} which are parameterized using the surface chlorophyll data. While the background is generally considered as the surface chlorophyll concentration, some of the existing models assume it to decrease progressively with depth (Martin et al., 2010; Stramska and Stramski, 2005; Arrigo et al., 2011; Cherkasheva et al., 2013). Previously, Morel and Berthon modelled Chl profile
- shapes for nine tropic categories and developed a global algorithm for SCM, DCM and other parameters, regardless of region and season (Morel and Berthon, 1989). The estimation of these profile parameters from the existing algorithms is applicable for certain seasons and regions. After the comprehensive study of DCM (Martin et al., 2010), it is confirmed that the published global, statistical relationships between the
- ²⁵ surface Chl and profile parameters lead to a severe underestimation when the SCM is sharp and intense in clear oceanic waters. This investigation motivates us to determine the new relation between the surface Chl vs. profile parameters for predicting the column integrated chlorophyll profiles. In coastal waters, suspended sediments also play a major role on the determination of underwater light fields. Like the chlorophyll





profiles, the surface suspended sediment concentration is used to extrapolate the SS along the depth. Previously, Ramakrishnan et al. (2013) used the power law function to predict the vertical SS profiles from OCM data.

It is well known that the underwater radiometric parameters directly depend on IOPs of the water body (Shanmugam et al., 2010, 2011). The IOPs are mainly absorption, attenuation, scattering and backscattering coefficients which are generally derived as a function of the chlorophyll concentration in oceanic waters. Over the past decades, several models have been developed to estimate IOPs in Case 1 waters (Prieur and Sathyendranath, 1981; Ahn, 1990; Bricaud et al., 1995; Babin et al., 2003; Matsuoka et al., 2011). However, the overly simplified parameterizations do not account for much of the optical variability observed in natural waters. leading to large uncertainties in

- of the optical variability observed in natural waters, leading to large uncertainties in Case 2 waters (Babin et al., 2003; Dmitriev et al., 2009). The variations in these parameters can be attributed to the three water constituents, such as phytoplankton, yellow substances (CDOM) and non-algal particles (both organic and inorganic). The partic-
- ¹⁵ ulate absorption (a_p) is mainly dominated by the non-algal particles, but phytoplankton becomes the dominant contributor in algal bloom waters (Wang et al., 2011). Stramski et al. (2001) explain that the mineral particles could be important for scattering and backscattering. Recently, Gokul et al. (2014) have developed models to predict IOPs and their vertical profiles using the remote sensing reflectance data.

This work intends to derive a generalized radiative transfer model for predicting the underwater light fields in a variety of waters (including turbid coastal waters and eutrophic waters). The model is run with the in-situ IOP data and predicted IOP data from remote sensing data and its results are compared with the measured radiometric data. The results of the present RT model are further discussed for a variety of waters around southern India.

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2 Data and methods

In-situ measurements of the various optical and physical properties together with the water sampling were conducted in relatively clear and turbid coastal waters off Point Calimere and Chennai and eutrophic (lagoon) waters around Chennai during Au-

- ⁵ gust 2012 and August, November and December 2013. The nature and characteristics of these waters have been investigated in a recent study by Pravin and Shanmugam (2014). For each station, water samples were collected from discrete depths and filtered and analyzed for the determination of Chl, SS and CDOM contents. Table 1 summarizes some important symbols and notations used in this paper. The data used
- for this study and the sampling stations are described in Table 2. The vertical profiles of IOPs and other properties were measured with WETLabs AC-S, BB9 and FLNTU sensors. Necessary corrections (for temperature, salinity and scattering effects) were applied to the AC-S data to obtain more reliable absorption and attenuation data (Pegau et al., 1997). Physical properties of the seawater such as conductivity, temperature and depth were measured by a SBE-CTD sensor to support the above data processing

and analysis.

Field radiometric measurements were carried out using RAMSES (Trios) hyperspectral radiometers; RAMSES ARC and ACC were used to measure the upwelling radiance, upwelling irradiance and downwelling irradiance in the water column. The irradiance sensor has an inbuilt pressure sensor which provides the corresponding depth in the water column. Both these sensors measure the radiance signal in the visible and near-infrared (350–950 nm) with a field-of-view of 7° and spectral accuracy of 3.3 nm. Since the radiance sensor was immersed in water, the immersion factors (wavelength-dependent correction factors) were used to correct the measured radi-

²⁵ ance signal (Pravin and Shanmugam, 2014). Similarly, the above-surface measurements were made with another set of Trios sensors that provided the sky radiance L_{skv} , downwelling irradiance $E_d(0^+)$ and total radiance L_t . The desired water-leaving





radiances were determined after eliminating the surface-reflected light contributions to the total radiance signal (Pravin and Shanmugam, 2014).

3 Modelling

Figure 1 shows the schematic flow diagram of the present RT model. It can simulate the underwater light fields based on the measured IOPs (right part) or predicted IOPs from the remote sensing data (left part) for the same solar incident geometry and surface and bottom boundary conditions. For the second part, surface chlorophyll [Chl] and suspended sediments [SS] are estimated from remote sensing reflectance data and their vertical profiles are subsequently predicted using the known functions. These vertical profiles are used to derive the IOPs (hereafter referred to as "Pred IOP"). Finally, the Pred IOPs are used along with the other input parameters to simulate the underwater light fields. The step-by-step procedure is detailed in what follows.

3.1 Radiative transfer model

Radiative transfer is the physical phenomenon of energy transfer in the form of electromagnetic radiation. The propagation of radiation through a medium is affected by absorption, emission, and scattering processes. The equation of radiative transfer describes these interactions mathematically. The basic RT equation that connects the radiance and IOPs is expressed as follows,

$$\cos\theta \frac{dL(z,\theta,\phi,\lambda)}{dz} = -c(z,\lambda)L(z,\theta,\phi,\lambda) + \int_{4\pi} L(z,\theta',\phi',\lambda) \times \beta(z;\theta',\phi'\to\theta,\phi;\lambda)d\Omega' + S(z,\theta,\phi,\lambda).$$
(1)

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The scattering angle ψ in the volume scattering function (VSF) is the angle between the incident direction (θ' , ϕ') and the scattered direction (θ , ϕ). The source term



 $S(z, \theta, \varphi, \lambda)$ describes either an internal light source such as bioluminescence, or inelastically scattered light from other wavelengths.

Figure 2 shows the schematic representation of the in-water radiative transfer technique for homogenous and inhomogeneous waters with the direct and diffuse terms.

For practical applications, it is important to consider the influences of homogenous (diffuse term) and inhomogeneous (direct term) layers of the water column on the underwater light field parameters. The homogenous and inhomogeneous effects are included in the present RT model (by taking the average of these two terms) to simulate the underwater light fields in a wide variety of waters (including relatively clear, turbid and eutrophic waters). The downwelling irradiances along the depth for both homogenous (HE_d) and inhomogeneous waters (*E*_d) can be calculated using,

$$E_{\rm d}(z) = \left(\frac{1}{2}\right) ({\rm HE}_{\rm d}(z) + E_{\rm d}(z)), \tag{2}$$

From the downwelling irradiance and reflectance at different depths, the upwelling irradiance (for both homogenous (HE_u) and inhomogeneous (E_u)) can be calculated from,

$$E_{\rm u}(z) = \left(\frac{1}{2}\right) \left[\mathsf{HE}_{\rm u}(z) + E_{\rm u}(z)\right] + \left[\frac{S(z)}{4\pi}\right],\tag{3}$$

These equations provide more accurate upwelling irradiances along the depth. The upwelling radiance along the depth (for homogenous and inhomogeneous) can be calculated from,

$$_{20} \quad L_{\mathrm{u}}(Z) = \left[\frac{E_{\mathrm{u}}(Z)}{2\pi\mu}\right].$$

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Using the above equations one can generate the underwater light fields and study their fluctuations in both clear and turbid waters. The inhomogeneous or direct term includes the phase function, source term, and surface and bottom boundary condition which are solved in equal interval along the water column. The homogeneous term or diffuse term is directly calculated from the IOPs for any arbitrary depth (Haltrin, 1998b).

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3.1.1 Boundary conditions

Surface transmittance

The propagation of light through the sea surface is calculated from the reflected and transmitted angles using the Fresnel function (Gjerstad et al., 2003). Since the resulting

⁵ underwater light fields strongly depend on the exact shape of the wave, the slope of the sea surface plays an important role in determining the transmitted and reflected angles. The tilt angle is calculated based on the Snell's law. The equation used to determine the tilt angle (γ) of the sea surface from the slope is given below,

$$\gamma = \tan^{-1} \left[\frac{\Delta z}{\Delta x} \right],$$

where " Δx " and " Δz " are the differential space of sea surface wave in the horizontal and vertical directions respectively. The Snell's law for the flat surface is given by $n_1 \sin(\theta_i) = n_2 \sin(\theta_t)$, where θ_i and θ_t are the incident and transmitted angles and "*n*" is the refractive index. After including the slope of the titled angle in the above equation, the transmitted angle for the sea surface is calculated from,

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$$\theta_{\rm t} = \sin^{-1} \left[\frac{n_1}{n_2} \sin(\theta_{\rm i} + \gamma) \right] - \gamma,$$
 (6)

The modified transmitted and incident angles are applied in the Fresnel equation as follows,

$$\mathsf{Rf}_{\mathsf{F}} = \begin{cases} \frac{1}{2} \left[\left(\frac{\sin(\theta_i - \theta_t)}{\sin(\theta_i + \theta_t)} \right)^2 + \left(\frac{\tan(\theta_i - \theta_t)}{\tan(\theta_i + \theta_t)} \right)^2 \right], & \theta_i \neq \theta_t \\ \left(\frac{n_w - 1}{n_w + 1} \right)^2, & \theta_i = \theta_t \end{cases}$$

$$\mathsf{Tx}_{\mathsf{F}} = \mathbf{1} - \mathsf{Rf}_{\mathsf{F}}$$

$$\tag{7}$$

²⁰ The transmittance calculated from the above is used as the interface between the air and water for the downwelling irradiance (notations given in Table 1).



(5)

Bottom reflectance

The effective reflectance R_{eff} of the bottom (considering the bottom material and morphology) is calculated according to Zaneveld et al. (2003),

 $\frac{R_{\rm eff}(\lambda)}{R_{\rm b}(\lambda)} = 0.5 \times \cos[\theta_{\rm z} + \theta_{\rm b}] + 0.5 \times \cos[\theta_{\rm z} - \theta_{\rm b}]. \tag{8}$

⁵ where $\theta_{\rm b} = a \tan(4A_{\rm b}/L_{\rm b})$ the angle of the bottom slope (due to ripples on the sea bed), and $\theta_{\rm z}$ is the zenith angle of the irradiance. $A_{\rm b}$ and $L_{\rm b}$ are the amplitude and wavelength respectively for the triangular shaped bottom. The effective reflectance spectra of the sea bottom are not same for different materials since the reflectance is about to vary for different materials.

3.1.2 Optical properties in the water column

Phase function

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Of several phase function models developed in the past, Fournier Forand (FF) model is an analytic form of the phase function giving better results when compared to other models (Mobley et al., 2002). The FF phase function is given by,

$$\begin{split} \beta(\theta) &= \frac{1}{4\pi (1-\delta)^2 \delta^{\nu}} \left\{ [\nu(1-\delta) - (1-\delta^{\nu})] + \left[\delta(1-\delta^{\nu}) - \nu(1-\delta) \sin^{-2} \left(\frac{\theta}{2}\right) \right] \right\} \\ &+ \frac{1-\delta_{180}^{\nu}}{16\pi (\delta_{180}-1)\delta_{180}^{\nu}} (3\cos^2\theta-1), \\ \nu &= \frac{3-\mu}{2}, \quad \delta = \frac{4}{3(n-1)^2} \sin^2 \left(\frac{\theta}{2}\right) \end{split}$$

Here μ is the slope of the Junge particle distribution and *n* is the real index of refraction and δ_{180} is calculated by considering $\theta = 180^{\circ}$. Based on the previous studies



(9)

(Twardowski et al., 2001; Freda and Piskozub, 2007; Sundarabalan et al., 2013), the parameters μ and *n* are modelled using the IOPs (attenuation *c* (520) and scattering *b* (520)). Finally, the backscattering $b_{\rm b}$ coefficients are computed from the phase function for scattering angles between 90° to 180°,

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$$b_{b}(520) = \int_{\frac{\pi}{2}}^{\pi} \beta(\theta) d\theta$$
,

The spectral variation of the backscattering $b_{\rm b}$ coefficients can be expressed as (Haltrin, 2002),

$$b_{\rm b}(\lambda) = b_{\rm b}(520) \times \left(\frac{520}{\lambda}\right)^{1.1}.$$
(11)

This phase function is mainly used to determine the $b_{\rm b}$ coefficients along the depth, ¹⁰ which are more compatible for turbid coastal waters.

Transmittance along the depth

Haltrin derived the transmittance as a function of depth T(z) based on the self consistent method, which depends on the IOPs of seawater (Haltrin, 1998b). The transmittance function T(z) is expressed as,

$$T(z) = \frac{1 + q \left\{ \mu_{s} \varepsilon(z) + h R_{s} F_{s}(z) [(2 + \overline{\mu}) \mu_{s} + 1] \right\}}{1 + q \mu_{s}}, \qquad (12)$$

Several important parameters that depend on the IOPs are used to calculate T(z). μ_s is the cosine function related to the solar angle which is calculated based on the refractive index of seawater (*n*) and the solar elevation h_s . $\overline{\mu}$ is the average cosine that connects with the Gordon's parameter *g*, which depends on the absorption and backscattering



(10)

coefficients. The result obtained by solving the RTE is α_{∞} which is the division of absorption (*a*) by the average cosine ($\overline{\mu}$). μ_0 is another cosine function which depends on the average cosine $\overline{\mu}$. The reflectance parameters involved in the calculation of T(z) are the diffuse reflectance (R_s) of a deep sea layer optically illuminated by direct solar light and the diffuse reflectance (R_{∞}) of the optically deep sea illuminated by the diffuse light. Both are calculated as a function of the cosine functions as follows,

$$R_{\rm s} = \frac{(1-\overline{\mu})^2}{1+\overline{\mu}\mu_{\rm s}(4-\overline{\mu}^2)}, \quad R_{\infty} = \left(\frac{1-\overline{\mu}}{1+\overline{\mu}}\right)^2, \tag{13}$$

The average cosine function used in the above equation is defined as,

$$\overline{\mu} = \left\{ \frac{1-g}{1+2g + [g(4+5g)]^{1/2}} \right\}^{1/2}, \quad \mu_0 = \frac{1+\overline{\mu}^2}{\overline{\mu}(3-\overline{\mu}^2)}, \quad \mu_s = \left[1 - \left(\frac{\cos h_s}{n_w}\right)^2 \right]^{1/2},$$
(14)

where, c = a + b is the beam attenuation coefficient, $q = \frac{E_{\rm s}^1}{E_{\rm d}^0}$ is the transmittance at air sea interface, $\alpha = a + 2b_{\rm b}$ is the renormalized attenuation coefficient, $\alpha_{\infty} = \frac{a}{\mu}$ is the intermediate parameter which depends on IOPs and $g = \frac{b_{\rm b}}{a + b_{\rm b}}$ is the Gordon's parameter which depends on absorption and scattering.

The IOP dependent intermediate parameters are defined as,

$$\varepsilon(z) = \exp\left[-\alpha z \left(\frac{1}{\mu_{s}} - \frac{1}{\mu_{0}}\right)\right], \quad h = \frac{(1+\overline{\mu})^{2}}{2(1+\overline{\mu}^{2})},$$
$$F_{s}(z) = \begin{cases} \left(1 - \exp\left[-\alpha z \left(\frac{1}{\mu_{s}} - \frac{1}{\mu_{0}}\right)\right]\right) / \left(\frac{1}{\mu_{s}} - \frac{1}{\mu_{0}}\right), & \mu_{s} \neq \mu_{0}, \\ \alpha z, & \mu_{s} = \mu_{0} \end{cases}.$$

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The above parameters ($\varepsilon(z)$, h, and $F_s(z)$) are the functions calculated based on the IOPs and solar elevation (Haltrin, 1998b).

Reflectance along the depth

The reflectance along the depth R(z) is generally calculated based on the IOPs $(b_{\rm b}/(a+b_{\rm b}))$, but it is also highly influenced by the bottom material and solar zenith angle (Lee et al., 1998, 1999). Thus, the reflectance along the depth is calculated from Lee et al. (1998), which takes into account the bottom material effect and the IOPs of the water column. The model parameters are defined as follows,

 $R(z) = R_{\rm iop}(z) + R_{\rm btm}(z),$

The reflectance influenced by the IOPs and bottom effect are calculated from the fol-10 lowing equations,

$$R_{iop}(z) = r_{rs}(z) \times \left\{ 1 - \exp\left[-\kappa(z)H\left(D_{u}^{c} + \left(\frac{1}{\cos\theta_{w}}\right)\right)\right] \right\},$$

$$R_{btm}(z) = R_{effbtm} \times \left\{ -\exp\left[-\kappa(z)H\left(D_{u}^{b}(z) + \left(\frac{1}{\cos\theta_{w}}\right)\right)\right] \right\},$$
(17)

where D_{μ}^{c} is the path-elongation factor for scattered photons from the water column which varies with the IOPs. The optical path-elongation factor D_{μ}^{b} for the bottom mainly depends on the bottom reflectance. These factors are defined as,

$$D_{u}^{c} = 1.03\sqrt{(1 + (2.4 \times u))},$$
$$D_{u}^{b} = 1.04\sqrt{(1 + (5.4 \times u))},$$

 $r_{\rm rs}$ is the subsurface remote-sensing reflectance which is a function of the IOPs at a given depth and expressed as,

 $r_{\rm rs} = u \times [(u \times 0.170) + 0.084],$

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Also, θ_w is the subsurface solar zenith angle, *H* is the bottom depth, $R_{\rm effbtm}$ is the effective bottom reflectance. κ and *u* are the inherent optical parameters which can be obtained from,

$$u = \frac{b_{\rm b}(z)}{a(z) + b_{\rm b}(z)},$$

$$\kappa = a(z) + b_{\rm b}(z).$$

Based on the IOPs along the depth and effective reflectance of the bottom, the reflectance functions along the depth R(z) can be calculated from these equations.

Source function

Since the source function affects the underwater light fields (by way of reemitting photons by phytoplankton at longer wavelengths after absorption at shorter wavelengths), it is also included in the present RT model. The source function can be computed as follows (Gower et al., 2004),

$$\mathsf{FI}(\lambda) = \frac{0.15 \times \mathsf{ChI}}{1 + 0.2 \times \mathsf{ChI}},$$

The source function is calculated as a function of the chlorophyll fluorescence as follows,

 $S(\lambda) = \mathsf{FI}(\lambda) \times h(\lambda),$

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where $h(\lambda)$ is the fluorescence emission function per unit wavelength calculated based on the Gaussian distribution,

$$h(\lambda) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\lambda - \lambda_0)^2}{2\sigma^2}\right).$$
(23)

²⁰ The wavelength of maximum emission is $\lambda_0 = 685$ nm and the standard deviation $\sigma = 10.6$ nm.

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3.1.3 Inhomogeneous term: underwater light field parameters

The downwelling irradiance $E_d(0^-)$ just below the water for the inhomogeneous (or layer by layer) condition can be calculated from the downwelling irradiance $E_d(0^+)$ just above the water along with the transmittance derived from the Fresnel equation (Eq. 7),

 $E_{\rm d}(0^-) = E_{\rm d}(0^+) \times {\rm Tx}_{\rm F},$

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Once the downwelling irradiance is transmitted through the water surface, the intensity of the downwelling irradiance based on the transmittance is purely dependent on the IOPs. The downwelling irradiances for the first and subsequent layers of the depth are calculated from,

$$E_{d}(z_{1}) = E_{d}(0^{-}); \quad E_{d}(z_{2}) = E_{d}(z_{1}) \times Tx(z_{2}),$$

The downwelling irradiance along the depth can be calculated from an explicit method with the corresponding depth transmittance Tx(z). The common equation for calculating $E_d(z)$ along the depth is given as,

$$E_{d}(z) = E_{d}(z-1) \times Tx(z),$$

The upwelling irradiances below the water along the depth are calculated from,

 $E_{u}(z) = (E_{d}(z) \times R(z)).$

where, $E_d(z)$ is downwelling irradiance and R(z) is the reflectance for the corresponding depth which includes the effect of the bottom reflectance and IOPs from the bottom boundary condition.



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3.1.4 Homogeneous term: underwater light field parameters

The downwelling irradiance equation developed by Haltrin (1998b) for the homogenous water column takes the following expression,

$$HE_{d}(z) = E_{d}^{0} \exp(-\alpha_{\infty} z)$$

+
$$E_{s}^{\perp} \exp(-\alpha z/\mu_{s}) + E_{s}^{\perp} hR_{s} \left\{ 1 + \mu_{s}(2 + \overline{\mu}) \right\} F_{s}(z) \exp(-\alpha_{\infty} z).$$
(28)

The upwelling irradiance for the homogenous water column can be calculated from the Haltrin's (1998b) equation,

$$HE_{u}(z) = E_{d}^{0}R_{\infty}\exp(-\alpha_{\infty}z) + \mu_{s}E_{s}^{\perp}R_{\infty}\exp(-\alpha z/\mu_{s}) + E_{s}^{\perp}hR_{s}\left\{\mu_{s}(2-\overline{\mu}) - 1\right\}F_{s}(z)\exp(-\alpha_{\infty}z).$$
(29)

The total underwater light field parameters (E_d , E_u and L_u) can be obtained by applying the Eqs. from (26)–(29) in Eqs. (2)–(4). The model presented in this study is much easier to implement when compared to the existing RT models.

3.2 Prediction of remotely sensed IOPs along the water column

15 3.2.1 Bio-optical model

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This section presents methods to estimate the surface chlorophyll $[Chl]_{sur}$ and suspended sediments $[SS]_{sur}$ concentrations from remote sensing reflectance R_{rs} data. Since R_{rs} values are generally too small, these data are converted to the normalized water leaving radiances nL_w for calculating the slope values as follows,

²⁰
$$nL_w(443) = R_{rs}(443) \times 187.688,$$
 (30)
 $nL_w(547) = R_{rs}(547) \times 186.584,$ (31)

$$S_{nL_w} = 100 \times \left[\frac{nL_w(443) - nL_w(547)}{443 - 547} \right],$$

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(32)

Based on the S_{nL_w} and R_{rs} data, three scenarios are found adequate for the various water types. The coefficients are derived based on the measured R_{rs} , $[ChI]_{sur}$ and $[SS]_{sur}$ data (Table 3). The first scenario accounts for open ocean waters and relatively clear waters where S_{nL_w} is less than 0.5 and [ChI] is based on the ratio of R_{rs} (488) and R_{rs} (547). The second scenario indicates turbid coastal waters where the same band ratio is used for the [ChI] parameterization. The [SS] parameterizations are different for both these scenarios. The third scenario is developed for inland and eutrophic waters based on the exponential function that uses the R_{rs} values at three different bands (690, 700 and 760 nm) (Zhang et al., 2009). The coefficients of the exponential equation are obtained based on the IR_{rs} values which is defined as follows,

$$IR_{rs} = \left(\frac{1}{R_{rs}(690)} - \frac{1}{R_{rs}(700)}\right) \times R_{rs}(760).$$
(33)

For the [SS] parameterization, there is a shift of peak between 547 and 488 nm in clear waters (first scenario) and the ratio of $R_{rs}(620)$ to the maximum value of $R_{rs}(488)$ and $R_{rs}(547)$ is found to be suitable for these waters. In turbid coastal waters (second scenario), the reflectance peak at 547 nm dominates the R_{rs} values at 488 nm and the relative change of these values are used in terms of the ratio to estimate [SS] in turbid waters. Considering the inland and eutrophic waters (third scenario), the ratio of R_{rs} at 620 and 720 nm is used for the estimation of [SS] in these waters.

3.2.2 Vertical profiles of chlorophyll and suspended sediments

- ²⁰ The chlorophyll and suspended sediments along the vertical column are determined from the surface [Chl] and [SS] data. For the chlorophyll profile, Lewis et al. (1983) found the generalized Gaussian distribution model which captures the major features of the observed vertical profile. The major parameters used to determine the chlorophyll profile are the surface chlorophyll [Chl]_{sur}, maximum chlorophyll [Chl]_{max}, depth ²⁵ chlorophyll maximum Z_{max} , and σ (standard deviation that controls the thickness of
- [Chl]_{max} layer and determines the vertical spread). The schematic representation of





these chlorophyll profile parameters, dissolved organic $a_{\text{CDOM}}(\lambda, z)$, is shown in Fig. 3. The determination of the chlorophyll profile based on the above parameters is given below,

$$\operatorname{Chl}(z) = \operatorname{Chl}_{\operatorname{sur}} + C_{\operatorname{m}} \times \exp\left[-\frac{(z - z_{\operatorname{m}})^2}{2\sigma^2}\right],$$
(34)

⁵ The chlorophyll profile parameters calculated from the surface [Chl] are shown in Table 4 and the basic equations are taken from Gokul et al. (2014). The equations were developed based on a large number of in-situ data. Conversely, the SS profile is estimated using the power law function,

$$SS(z) = SS_{sur} \times \left(\frac{z}{z_{sur}}\right)^{0.0383}$$

¹⁰ The slope is calculated based on the mean slope values from a number of measured SS profiles.

3.2.3 IOP model

Clear and turbid coastal waters

A simplified model is used to estimate the vertical profiles of IOPs using chlorophyll and suspended sediment profile data. Though the IOPs may be determined by more than three substances, it is assumed that the absorption and scattering coefficients in clear and turbid coastal waters are mainly determined by water itself, suspended sediment particles and phytoplankton (both living and non-living). Thus, the total absorption coefficient of seawater, $a(\lambda, z)$, is the sum of the absorption of seawater $a_w(\lambda, z)$, dissolved organic matter $a_{CDOM}(\lambda, z)$, and particulate matter $a_p(\lambda, z)$. The total absorption



(35)



coefficient observed at any given wavelength can be expressed as,

$$a(\lambda, z) = a_{w}(\lambda, z) + a_{CDOM}(\lambda, z) + a_{p}(\lambda, z),$$

$$a_{p}(\lambda, z) = a_{ph}(\lambda, z) + a_{ss}(\lambda, z),$$
(36)
(37)

Here the total absorption (pure water, chlorophyll, suspended sediments and coloured dissolved organic matter) is estimated from Morel (1991) and the absorption coefficient of suspended sediments is calculated from Gokul et al. (2014).

$$a(\lambda, z) = \left(a_{w}(\lambda) + 0.06a_{C}^{*}(\lambda)[Chl(z)]^{0.65}\right) \times (1 + 0.2\exp(-0.014(\lambda - 400))) + a_{ss}(\lambda, z),$$
(38)

The seawater absorption coefficients were taken from Pope and Fry (1997). The absorption coefficient of suspended sediments is estimated as follows,

$$a_{\rm ss}(\lambda, z) = a_{\rm ss}(\lambda_r) \times \exp(-0.0104(\lambda - \lambda_r)), \tag{39}$$

where the absorption at a reference wavelength 443 nm is calculated from the power fit shown in Fig. 4a and the equation is given as,

$$a_{\rm ss}(443) = 0.0007[SS(z)]^{1.7653}$$
. $[R^2 = 0.9]$ (40)

Similarly, the total scattering coefficient of sea water is the sum of the scattering due to pure seawater $b_w(\lambda, z)$ and particulate matter $b_p(\lambda, z)$ (due to phytoplankton and suspended sediments). The pure sea water scattering coefficients were taken from Smith and Baker (1981). Since the contribution of CDOM is negligible, it is omitted leading to the total scattering $b(\lambda, z)$,

$$b(\lambda, z) = b_{w}(\lambda, z) + b_{ph}(\lambda, z) + b_{ss}(\lambda, z),$$

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(41)

previous studies, phytoplankton absorption $a_{ph}(\lambda)$ were generally calculated based on



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(42)

(43)

(44)

The scattering due to phytoplankton $(b_{\rm ph})$ depends on the chlorophyll concentration

where S is the slope which is calculated based on the chlorophyll concentration (Huot

et al., 2008). When the Chl is greater than 2 mg m^{-3} , S is considered as zero. If Chl is

The scattering due to suspended sediments is estimated using power law model

Finally, the attenuation coefficients $\alpha(\lambda, z) (= c(\lambda, z))$ are calculated based on the total

For eutrophic and phytoplankton-dominated waters, the variations in absorption and scattering coefficients are poorly documented as most of the previous studies on IOPs

were conducted in relatively clear and open ocean waters. In this study, absorption and

scattering by particles are estimated using separate models for these waters. In the

the specific phytoplankton absorption $a_{ph}^{*}(\lambda)$. Here the specific particulate absorption

less than 2 mg m^{-3} , then the slope is calculated from the following equation,

which is derived from Gordon and Morel (1983),

 $b_{\rm ph}(\lambda, z) = \left(\frac{550}{\lambda}\right)^{S} \times (0.3[\operatorname{Chl}(z)]^{-0.3}),$

 $S = 0.5 \times (\log([Ch](z)]) - 0.3).$

(Fig. 4b) which is expressed as,

¹⁰ $b_{ss}(\lambda, z) = \frac{1}{2} \left(\frac{412}{\lambda} \right)^{0.88} \times (0.0043 [SS(z)]^{1.9657}).$

absorption $a(\lambda, z)$ and total scattering $b(\lambda, z)$ coefficients.

Eutrophic and phytoplankton-dominated waters

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The values of new $a_p^*(\lambda)$ are given in Table 5. The particulate absorption coefficients are then derived as a function of chlorophyll as follows,

$$a_{\rm p}(\lambda, z) = a_{\rm p}^*(\lambda) \times [\operatorname{Chl}(z)] \times \left(\frac{[\operatorname{Chl}(z)]}{54}\right),\tag{45}$$

Similarly, the particulate scattering is calculated directly based on the exponential function of chlorophyll (Fig. 4c) as given below,

$$b_{\rm p}(\lambda, z) = 1.4 \times \exp(0.0525 \times [\text{Chl}(z)]) \times \left(\frac{\lambda}{532}\right)^{-0.3}.$$
(46)

This equation is derived from the relationship between in-situ chlorophyll and particulate scattering (c-a from WetLabs AC-S). Both particulate absorption and scattering coefficients are added with the respective pure water coefficients to obtain the total absorption and scattering coefficients.

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4 Results and discussion

Results are categorized into two parts: (1) comparison of the model vs. measured IOP profile data, and (2) comparison of the underwater light fields predicted by the RT model based on the measured and estimated IOPs profiles from remote sensing data. Figure 5 shows the examples of measured remote sensing reflectances from different waters (clear, turbid and eutrophic waters) used for construction of the vertical profiles of IOPs and simulation of the underwater light fields. The specific spectral features of these waters have been described in a recent study (Pravin and Shanmugam, 2014).

4.1 Prediction of the IOPs profiles from remote sensing data

²⁰ This section is focused on the determination of the vertical profiles of IOPs based on the seawater constituents (chlorophyll and suspended sediments at the surface level) that are estimated from the above-water remote sensing reflectance ($R_{\rm rs}$) data.





4.1.1 Retrieval of the seawater constituents

The spectral information of the remote sensing reflectance (R_{rs}) was used to estimate [ChI] and [SS] concentrations in surface waters off Point Calimere and Chennai. Since the models are based on the different spectral slopes (R_{rs}), different scenar-

is were used to estimate these water constituents accurately. The estimated [ChI] and [SS] show good agreement with measured data from different waters (Fig. 6a), where [ChI] ranged from 0.1–100 mg m⁻³. The statistics analyses indicate low errors and high slopes and correlation coefficients (MRE = 0.17, RMSE = 0.18, slope = 1.0, bias = -0.031, $R^2 = 0.91$, N = 98). Similarly, the estimated [SS] agree closely with the in-situ [SS] (Fig. 6b), with good statistics (MRE = 0.01, RMSE = 0.09, slope = 0.98, bias = -0.01, $R^2 = 0.84$, N = 98). These results clearly demonstrate consistency between the estimated and measured data for a wide range of waters.

4.1.2 Vertical profiles of chlorophyll and suspended sediments

On the basis of surface chlorophyll [Chl]_{surf} and [SS] estimated from remote sensing data, the vertical profiles of [Chl(*z*)] and [SS(*z*)] were constructed in relatively clear and turbid coastal waters. It is observed that the modelled and measured chlorophyll profiles agree well in relatively clear waters off Chennai (31 August 2013 at 13:00 and 15:00 LT) (Fig. 7a and b). The Chl concentration is low in surface waters (0.3 mg m^{-3}) and gradually increases along the depth. For relatively clear waters off Point Calimere in August 2013 (Fig. 7c), the surface chlorophyll is very low (0.8 mg m^{-3}) and the depth of chlorophyll maximum (Z_{max}) shifts to the seabed exponentially. This profile indicates more light transmission towards the sea bed. The sub-surface chlorophyll maximum [Chl] might ensure due to the influences of bonthis resuscence of a succed by tides and

- [Chl]_{max} might occur due to the influences of benthic resuspension caused by tides and currents. Though the modelled chlorophyll profile typically follows the measured chlorophyll profile at this station, there is a slight deviation of the modelled chlorophyll profile
- observed at the intermediate depth. The $[Chl]_{surf}$ in surface waters off Point Calimere is relatively high (5 mg m⁻³) during August 2012 (Fig. 7d). As the depth increases, [Chl]





increases with a maximum value [(Chl]_{max}) around 7 m depth (20 mg m^{-3}) and then decreases following the surface [Chl]_{surf}. This trend typically follows the Gaussian distribution function, and thus there is better consistency between the modelled and measured Chl profiles (Fig. 7e). Another station towards the coast of Point Calimere during

the period was found to have a similar Gaussian profile indicating that the euphotic zone lies horizontally at a depth of 7 m. The corresponding measured and modelled SS profiles [SS(z)] are shown in Fig. 7a–c for these stations. Generally, the measured [SS] profiles are uniform along the depth and the power law function captures their depth variations adequately.

10 4.1.3 Modelling of IOPs based on the Chl and SS profiles

The [Chl(*z*)] and [SS(*z*)] profiles constructed from the models were used to estimate the IOP profiles. Figure 8 shows the comparison of estimated (black colour) and predicted (grey colour) IOPs (plotted for three wavelengths 440, 555 and 676 nm) with the in-situ IOP data, where the three clusters correspond to different waters (bottom – clear waters, middle – turbid coastal waters, top – eutrophic waters). Since a wide variety of waters is considered in this study, separate models were developed to treat the different water types. In Fig. 8 (top row), the model provides good estimates of a_p across the entire visible wavelengths (MRE –0.06–0.0774), although there is a slight overestimation (at higher wavelengths) especially in low Chl waters. The predicted a_p

- ²⁰ values are also better consistent with in-situ a_p data. Figure 8 (second row) presents the comparison of modelled and measured b_p values (at 440, 555 and 676 nm). Interestingly, the model performs well in different waters with a wide range of chlorophyll concentration. The MRE values associated with this model are very less (0.1169 at 440 nm, 0.5816 at 555 nm, and 0.2316 at 676 nm). Similarly, b_p predicted by the model
- have low MRE values (-0.1473 at 440 nm, 0.3152 at 555 nm and 0.0726 at 676 nm). Comparison of the modelled backscattering (b_b) with in-situ b_b data (at 440, 555 and 677 nm as shown in the third row of Fig. 8) shows that the model works slightly better





in relatively clear, turbid and eutrophic waters but slightly overestimates $b_{\rm b}$ values in clear waters. This problem could be attributed to measurement errors in very clear waters [38]. The MRE values are -0.0735 at 440 nm, -0.1309 at 555 nm and -0.0876 at 676 nm for the estimated $b_{\rm b}$ using in-situ Chl and SS data and -0.0604 at 440 nm, -0.1194 at 555 nm and -0.0763 at 676 nm for the predicted $b_{\rm b}$ using estimated Chl and SS data.

4.2 Underwater light field parameters

The results of the present RT model (with the consideration of solar zenith angle, sea surface slope, IOP-dependent phase function, bottom slope/material) based on the ¹⁰ in-situ and predicted IOP profile data are evaluated by comparison with measured underwater radiometric data such as downwelling irradiance $E_d(\lambda, z)$, upwelling irradiance $E_u(\lambda, z)$, and upwelling radiance $L_u(\lambda, z)$. The predicted IOP (from remote sensing reflectance data) in-situ IOP profile data were used as inputs for the present RT model. The IOP data measured from different waters (Fig. 9) include the particulate absorption ¹⁵ (a_p) , particulate attenuation (c_p) , and backscattering (b_p) .

4.2.1 Clear ocean waters

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Figure 10 shows the comparisons of simulated and measured underwater light fields $(E_d, E_u \text{ and } L_u)$ for four discrete water depths in relatively clear waters off Chennai. Looking at the E_d spectra (orange colour – present RT model using in-situ IOP data and blue colour – present RT model using Pred IOP data from remote sensing reflectance), the maximum value is seen at 490 nm throughout the water column. As the depth increases, E_d becomes attenuated in the blue (400–500 nm) but progressively more attenuated in the red region (> 600 nm). The E_d values from the present RT model using the in-situ and predicted IOP data are closely consistent with measured E_d across the entire visible wavelengths. The simulated E_d yields very low MRE (at





555 nm) 0.03 and -0.01 for the present RT model using in-situ IOP data and predicted

IOP data respectively. Conversely, the spectral pattern of E_u is different from that of E_d (second column) displaying two peaks – one at 490 nm (primary) and another at 520 nm (secondary). The E_u from the present RT model using the in-situ IOP data closely match with measured E_u at most wavelengths, except in the region of secondary peak at 520 nm. The MRE (at 555 nm) is very low (-0.3) for the present model using the predicted IOP data. Similar peaks – primary peak around 500 nm and secondary peak around 550 nm are also seen in the L_u spectrum. As the depth increases the secondary peak becomes more pronounced due to an increase in turbidity level. The deviation in L_u is very small for the present RT model as its predicted L_u spectra are better consistent with the measured L_u spectra, because of the inclusion of the effective bottom reflectance instead of the material reflectance.

4.2.2 Moderately turbid waters

Figure 11 shows the spectral variations of simulated and measured underwater light field data for four discrete depths in moderately clear waters (with elevated chlorophyll in relatively deep waters as compared to the previous case) off Point Calimere (August 2012). At this location, the vertical profile of chlorophyll typically followed the Gaussian pattern, with the surface chlorophyll 6.2 mg m⁻³ and maximum chlorophyll 18.5 mg m⁻³ at 7 m. The range of suspended sediments varied from 10.9–15.3 g m⁻³. The solar zenith angle measured was 44.9°. Thus, the spectral pattern of E_d (first col-

- ²⁰ umn) just below the surface resembles that of clear waters. As the depth increases, the pattern changes following the turbid water case with a major peak at 555 nm. The simulated E_d spectra from the present RT model using the in-situ IOP data appear similar and match with the measured E_d . Since the predicted IOPs are low at the surface, the magnitude of the predicted E_d is relatively high when compared to the measured and
- ²⁵ simulated E_d . The spectral pattern of E_u (second column) is slightly different for these waters as the primarily peak is located around 555 nm and a secondary peak around 685 nm due to the chlorophyll fluorescence. Similar features are also observed in the L_u spectra. The shape and magnitude of the E_u and L_u from the present RT model based





on the in-situ IOP data agree well with measured data (with MRE values 0.1 and 0.04 respectively). By contrast, the E_u and L_u spectra generated from the present RT model using the predicted IOP data are improved although showing a slight overestimation in the green domain.

5 4.2.3 Turbid coastal waters

Figure 12 shows the spectral comparisons of simulated and measured underwater light fields (E_d , E_u and L_u) for four discrete depths in turbid coastal waters off Point Calimere during August 2013. This station is in the vicinity of the coast with a depth of 6.3 m, where the in-situ measurements of AOPs, IOPs and other parameters were made when the solar zenith angle was 4.55°. At this station, the benthic resuspension and sediment transport noticeably increased the magnitude of the IOPs and turbidity. The measured E_d spectra (first column) show the maximum values at green wavelengths (555 nm) and minimum values at blue and red wavelengths throughout the water column, which are the characteristic features of turbid waters. Note that the magnitude of E_d spectra from the present model using the in-situ and predicted IOP data is closer to the measured

- ¹⁵ the present model using the in-situ and predicted IOP data is closer to the measured E_{d} spectra, with low MRE values 0.006 and 0.03 respectively. The E_{u} and L_{u} spectra produced by the present RT model based on the in-situ and predicted IOP data also match well with the measured E_{u} and L_{u} spectra (with relatively low MRE values -0.06-0.1 and -0.1 to -0.09 respectively). Better results associated with the present
- ²⁰ RT model are due to the modified boundary conditions and new phase function which varies along the depth.

4.2.4 Phytoplankton-dominated harbour waters

Figure 13 depicts the differences between simulated and measured underwater light fields in phytoplankton-dominated harbour waters of Chennai. Since these waters were well mixed vertically, the vertical profiles of IOPs predicted by the respective models were considered continuous along the depth. The spectra of E_d , E_u and L_u obtained



from these waters appear slightly different from the previous cases because of a well pronounced peak around 555 nm and a fluorescence peak shifted from 685 nm to 700 nm. Interestingly, the E_d , E_u and L_u spectra of the present RT model from the in-situ IOP data are well consistent with measured data across the entire visible wave-

⁵ lengths. As a result, its MRE values are reduced to 0.04 for E_d , 0.029 for E_u and L_u . Slight deviations are observed in the E_d , E_u and L_u spectra generated by the present RT model, which could be attributed to errors associated with the predicted IOPs and the assumption of the vertically homogenous water column (i.e., constant IOPs along the depth). This would eventually increase the MRE values to 0.3 for E_d , 0.2 for E_u , and 0.26 for L_u .

4.2.5 Eutrophic waters

The performance of the RT models is also examined in highly complex eutrophic waters, which exhibit much higher magnitudes in IOP spectra compared to other waters (Fig. 9). Figure 14 provides the spectral comparisons of simulated and measured underwater light fields from four different discrete stations (profile data not collected due to shallow water body). At these stations, both ChI and SS reached beyond 73 mg m⁻³ and 71 g m⁻³ respectively (in addition to high CDOM) ultimately reducing the magnitude of E_d (more at station #11) in the blue wavelength region and shifting the position of the red peak towards 715 nm (by the combined effect of fluorescence and backscattering by the phytoplankton cells). Thus, the RT models failed to generate

- the measured E_d in the blue wavelength region although their results are reasonably good in the green and red regions. The mean MRE values (for E_d at 555 nm) are 0.003 and 0.016 for the present RT model using the predicted IOPs and in-situ IOPs respectively. Interestingly, the present RT model based on the predicted and in-situ IOP
- ²⁵ data gives accurate E_u and L_u in terms of magnitude and shape at all four stations. The shifted red peaks are also better captured by the present RT model due to the inclusion of the appropriate source function. The MRE values (at 555 nm) are 0.07 and -0.06 for the E_u and L_u (from the predicted IOP data) and 0.08 and -0.05 for the E_u





and L_{μ} (from the in-situ IOP data). These results suggest that the present RT model can be used combined with remote sensing data to simulate the underwater light fields in a wide variety of waters.

Summary and conclusion 5

Existing radiative transfer models to simulate the underwater light fields often lead to 5 large uncertainties in turbid coastal and eutrophic waters. This could be due to the fact that some models treat the water column as homogenous (not considering the direct term) while others consider the water column as inhomogeneous (not considering the diffuse term). Assuming a constant phase function along the water column, a flat or oversimplified sea surface in a random manner, and considering the bottom material 10 reflectance instead of the effective bottom reflectance (based on bottom slope and material reflectance) have already been reported to introduce large errors in the simulated underwater light fields (Sundarabalan et al., 2013). Thus, it is necessary to develop a

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waters. To overcome the above issues, the proposed RT model can now handle more complex interactions of light with particulate matters with different surface and bottom boundary conditions. The direct and diffuse terms are included in this model to deal with the homogenous and inhomogeneous effects in the water column. The new sea

reliable RT model to generate the underwater light field parameters in a wide variety of

- surface boundary condition and the estimated sea surface transmittance have signif-20 icant effects on the downwelling irradiance (E_d) . As the sea surface slope increases, transmission through the air-water interface to the water column increases but effects of the sea surface are most prominent when the sun is away from the nadir (Jin et al., 2006). The significance of the modified phase function is especially noticed in the simulated underwater light fields (Twardowski et al., 2001; Mobley et al., 2002; Freda and
- Piskozub, 2007; Sundarabalan et al., 2013). Since the sea bed is not uniform or flat, the inclusion of bottom morphology along with the material reflectance (effective bottom



reflectance) in the bottom boundary shows better upwelling radiance L_u (Zaneveld and Boss, 2003). The bottom reflectance affects the entire water column, and is treated properly with IOPs along the depth (Lee et al., 1998). The source function based on the chlorophyll is included in the model and its effect is clearly seen in the simulated E_{μ}

- and L_u with a florescence peak at 685 nm (Gower et al., 2004). Finally, the calculated transmittance T(z) is purely based on the IOPs (Haltrin and Kattawar, 1993; Haltrin, 1998a, 1998b) and the reflectance R(z) based on the IOPs and bottom effects (Lee et al., 1998). The results of the present RT model based on the in-situ IOPs have good agreement with the measured underwater light field parameters.
- ¹⁰ In the context of satellite remote sensing, the present RT model has been extended to predict the underwater light fields from the remotely sensed IOP profiles and its results have been validated using the measured underwater radiometric data and those simulated from the same RT model using the measured IOP profile data. The remotely sensed IOP profiles were derived from the new parameterizations developed by con-
- ¹⁵ sidering the different types of waters. These IOP profiles were determined based on the estimated ChI and SS. The chlorophyll profile was determined by the Gaussian distribution function (Lewis et al., 1983) and SS profile by the power law function. The vertical structures of these estimated ChI and SS had good agreement with the measured profile data. It was found that the predicted underwater light field parameters (E_d ,
- E_u and L_u) from the present RT model using the Pred_IOPs were better consistent with the measured radiometric data as well as those obtained from the same RT model using the in-situ IOP data in clear waters, turbid waters, phytoplankton-dominated waters and eutrophic waters. However, one limitation is that due to the non-uniform trend of the chlorophyll pattern along the water column, the predicted E_d , E_u and L_u parameters
- ²⁵ may not be accurate in such cases of waters. Nevertheless, this comprehensive study demonstrates that the present RT model is capable of dealing with homogenous and inhomogeneous water conditions and has the ability to generate more realistic underwater light field parameters (E_d , E_u and L_u) using the measured IOPs as well as those





estimated from remote sensing data. The present RT model is a viable alternative to existing models and has an important implication for remote sensing as well.

Acknowledgements. This research was supported by INCOIS under the grant (OEC1314117INCOPSHA) of the SATCORE program. We thank D. Rajasekhar, The Head, Vessel Management Cell (VMC), and the Director of National Institute of Ocean Technology (NIOT) for providing Coastal Research Vessels to Indian Institute of Technology (IIT) Madras, Chennai, India for conducting various bio-optical measurements in coastal waters off Point Calimere and Chennai on the southeast coast of India. We are thankful to Scientists N. Ravi and K. Shashikumar of VMC for arranging the vessels for making necessary measurements.

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 Table 1. Symbols and notations.

Symbol	Description	Unit
U	Wind speed	$m s^{-1}$
θ_{z}	Solar zenith angle	0
Ζ	Depth	m
n _w	Refractive index	
μ	Average cosine	
q	Transmittance at air-water interface	
Tx _F	Fresnel transmittance at air-water interface	
Rf _F	Fresnel reflectance at air-water interface	
T(z)	Transmittance at depth z	
R(z)	Reflectance at depth z	
$R_{\rm s}$	Diffuse reflectance (direct solar light)	
R_{∞}	Diffuse reflectance (diffuse light)	_1
С	Attenuation	m ⁻
а	Absorption	m ⁻¹
b	Scattering	m^{-1}
$E_{d}(0^{+})$	Downwelling Irradiance just above the water	mW cm ² μ m ⁻¹
$E_{d}(0^{-})$	Downwelling Irradiance just below the water	mW cm ² μ m ⁻¹
$E_{\rm d}(z)$	Downwelling Irradiance	mW cm ² μ m ⁻¹
$E_{\rm u}(z)$	Upwelling irradiance	mW cm ² μ m ⁻¹
$L_{\rm u}(z)$	Upwelling radiance	mW cm ² μ m ⁻¹ sr ⁻¹
[Chl] _{sur}	Surface chlorophyll concentration	$\mathrm{mg}\mathrm{m}^{-3}$
[SS] _{sur}	Surface suspended sediments concentration	$mg m^{-3}$
$Z_{\rm max}$	Depth of chlorophyll maximum	m
[Chl] _{max}	Subsurface chlorophyll maximum	$mg m^{-3}$
σ	Standard deviation	m





Station	Date	Time	Latitude	Longitude	$\theta_{\rm z}$	Depth (m)	U (m s ⁻¹)	[Chl] (mg m ⁻³)	[SS] (mg m ⁻³)
St-1	31 Aug 2013	13.00	13°08.715′ N	80°21.041' E	21.9	19.8	7.7	0.2-1.1	7.9–17.7
St-2	31 Aug 2013	15.00	13°08.715′ N	80°21.041' E	43.6	19.8	7.7	0.3–0.5	8.2–11.1
St-3	26 Aug 2013	15.00	10°20.714′ N	80°08.604' E	43.2	17.7	5	1.0-6.7	7.0–15.8
St-4	26 Aug 2013	11.45	10°22.103' N	79°57.720' E	4.55	6.3	7.7	0.8–2.3	33.8–41.9
St-5	17 Aug 2012	15.10	10°20.992' N	80°05.573' E	44.9	17.9	4	6.2–18.5	10.9–15.7
St-6	17 Aug 2012	15.55	10°20.714′ N	80°08.604' E	55.9	22	3	5.3-20.4	8.4–16.6
St-7	8 Nov 2013	14.00	13°07.408′ N	80°17.565' E	42.8	5	0.25	18.3–18.5	21.6-24.0
St-8	10 Nov 2013	14.50	12°48.474′ N	80°14.204' E	53.2	1	0.25	52.5	70.4–71.6
St-9	10 Nov 2013	15.10	12°48.321′ N	80°14.239' E	59.5	1	0.25	54.1	68.2-87.3
St-10	16 Dec 2013	13.15	12°48.474′ N	80°14.204' E	42.5	1	0.25	72.1	63.6-65.5
St-11	16 Dec 2013	13.30	12°48.321′ N	80°14.239' E	43.8	1	0.25	73.8	62.1–64.8

Table 2. Station details and the observed environmental parameters used for this study.



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Table 3. Empirical relationships between the R_{rs} and surface concentration ([ChI]_{sur} and [SS]_{sur}) in a variety of waters for three different scenarios. Note that S.No. 3 will have another expression [ChI]sur = 17.128 × exp(0.888×IRrs) if one intends to use R_{rs} (680) instead of R_{rs} (690) in Eq. (33).

S.No	[Chl] _{sur}	[SS] _{sur}	Scenario
1	$1.123 \times \left(\frac{R_{rs}(488)}{R_{rs}(547)}\right)^{-3.7144}$	$21.503 \times \left(\frac{R_{\rm rs}(620)}{\max[R_{\rm rs}(488), R_{\rm rs}(547)]}\right)^{0.3998}$	$S_{\rm nL_w} < 0.5$
2	$0.409 \times \left(\frac{R_{\rm rs}(488)}{R_{\rm rs}(547)}\right)^{-7.567}$	$34.01 \times \left(\frac{R_{\rm rs}(547)}{R_{\rm rs}(488)}\right)^{-1.2615}$	$S_{nL_w} > 0.5$
3	$18.267 \times \exp(1.9913 \times \mathrm{IR}_{\mathrm{rs}})$	$38.685 \times \left(\frac{R_{\rm rs}(620)}{R_{\rm rs}(720)}\right)^{-0.554}$	$R_{\rm rs}(547) > R_{\rm rs}(488)$ $R_{\rm rs}(680) < R_{\rm rs}(690)$



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Table 4. Empirical relationships of the chlorophyll profile parameters ([Chl]_{max}, Z_{max} and σ) for the various ranges of surface chlorophyll [Chl]_{sur} from different stations.

Chl _{sur}	Chl _{max}	Z _{max}	Σ
1.0 < Chl _{sur} < 10	2.019 × Chl _{sur} – 0.2328	0.7595 × Chl _{sur} + 4.082	0.3456 × Chl _{sur} + 4.104
0.5 < Chl _{sur} < 1	-8.288 × Chl _{sur} + 8.3628	-12.247 × Chl _{sur} + 15.479	3.1606 × Chl _{sur} – 0.199
0 < Chl _{sur} < 0.5	-8.288 × Chl _{sur} + 2.6628	-12.247 × Chl _{sur} + 15.479	3.1606 × Chl _{sur} – 0.199

Table 5. New spectral absorption coefficients of water particles derived from the in-situ data,
which are used only when the concentration of [Chl] _{sur} is greater than 15 mg m ⁻³ for the calcu-
lation of the particulate absorption.

Wavelength	$a^*_{\sf p}$	Wavelength	$a^*_{\sf p}$
401	0.195342	575	0.038799
425	0.208779	601	0.044386
451	0.168103	625	0.056005
475	0.129094	651	0.053105
501	0.098007	675	0.080339
525	0.061625	701	0.019868
551	0.042149	725	0.002783



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Figure 1. The schematic block diagram indicates the overall system for the simulation of underwater light fields using the present RT model with the in-situ IOP (right) or predicted IOP from remote sensing data (left) along with other input parameters.







Figure 2. Schematic diagram showing the homogenous (left) and inhomogeneous radiative transfer concepts (right) with the diffuse and direct terms for the layers in the water column from the sea surface to sea bed.

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Figure 3. Schematic diagram represents the vertical profile of the chlorophyll along the depth including the distribution of profile parameters using the Gaussian distribution function.





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Figure 4. (a) Relationship between the suspended sediments concentration and absorption by suspended sediments $a_{ss}(443)$, used to calculate the absorption coefficient of suspended sediments $a_{ss}(443)$. (b) Relationship between the suspended sediment concentration and scattering b(412), used to calculate the scattering (b_{ss}) coefficient of suspended sediments. (c) Relationship between the Chlorophyll and particulate scattering $b_p(532)$ which is used to calculate the particulate scattering directly from the chlorophyll concentration. This is applicable only for surface Chl should be greater than 15 mg m^{-3} .







Figure 5. The typical remote sensing reflectance spectra $R_{rs}(\lambda)$ measured at four stations in the study area during 2012 and 2013. (a) Relatively clear waters off Chennai, (b) moderately turbid waters off Point Calimere, (c) phytoplankton-dominated harbour waters of Chennai, and (d) eutrophic waters.









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Figure 8. Comparisons of the modelled and in-situ IOP data (particulate absorption a_p , particulate scattering b_p , and backscattering b_b) at three wavelengths 440, 555, 676 nm. Black colour represents model results based on the in-situ concentrations ([Chl(*z*)] and [SS(*z*)]) and gray colour represents model results from the predicated profile data (from the estimated Chl and SS concentrations using remote sensing reflectance data).





Figure 9. Spectral plots of the in-situ IOPs (particulate absorption a_p , particulate attenuation c_p , and particulate backscattering b_b) from different waters. **(a)** Relatively clear waters off Chennai (St-1), **(b)** moderately turbid waters off Point Calimere (St-5), **(c)** turbid waters off Point Calimere (St-4), **(d)** phytoplankton-dominated harbour waters of Chennai (St-7), and **(e)** eutrophic waters of Chennai (St-8–11).







Figure 10. Spectral comparisons of the simulated and measured underwater light fields (E_{d}, E_{u}) and L_{μ}) for four discrete depths in clear waters off Chennai (St-1). The black colour represents the measured data, orange colour represents results from the present RT model using in-situ IOP data, and the blue colour represents results from the present RT model using the predicted IOPs from the remote sensing reflectance data.



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Figure 11. Spectral comparisons of the simulated and measured underwater light fields (E_d , E_u and L_u) for four discrete depths in moderately turbid waters off off Point Calimere (St-5). The black colour represents the measured data, orange colour represents results from the present RT model using in-situ IOP data, and the blue colour represents results from the present RT model using the predicted IOPs from the remote sensing reflectance data.









Figure 12. Spectral comparisons of the simulated and measured underwater light fields (E_d , E_u and L_u) for four discrete depths in turbid coastal waters off Point Calimere (St-4). The black colour represents the measured data, orange colour represents results from the present RT model using in-situ IOP data, and the blue colour represents results from the present RT model using the predicted IOPs from the remote sensing reflectance data.





Figure 13. Spectral comparisons of the simulated and measured underwater light fields (E_d , E_u and L_u) for four discrete depths in phytoplankton-dominated harbour waters of Chennai (St-7). The black colour represents the measured data, orange colour represents results from the present RT model using in-situ IOP data, and the blue colour represents results from the present RT model using the predicted IOPs from the remote sensing reflectance data.



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Figure 14. Spectral comparisons of the simulated and measured underwater light fields (E_d , E_u and L_u) just below the surface in eutrophic waters of Chennai (St-8–11). The black colour represents the measured data, orange colour represents results from the present RT model using in-situ IOP data, and the blue colour represents results from the present RT model using the predicted IOPs from the remote sensing reflectance data.



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